ASL1500SHN

Single phase boost converter

Rev. 4 — 26 October 2017

1. Introduction

The ASL1500SHN is a highly integrated and flexible single phase DC-to-DC boost converter IC. It has an SPI interface allowing control and diagnostic communication with an external microcontroller.

It is designed primarily for use in automotive LED lighting applications and provides an optimized supply voltage for ASLx415SHN Multi-channel LED Buck Driver.

2. General description

The ASL1500SHN has a fixed frequency peak current mode control with parabolic/non-linear slope compensation. It can operate with input voltages from 5.5 V to 40 V. It can be configured via SPI for output voltages of up to 80 V, to power the LED buck driver IC.

The ASL1500SHN boost converter drives one external low-side N channel MOSFET from an internally regulated adjustable supply to drive either logic or standard level MOSFET.

The integrated SPI interface also allows for programming the supply under/over voltage range, output voltage range and DC-to-DC switching frequency. It enables the optimization of external components and flexibility for EMC design. This interface can also be used to provide diagnostic information such as the driver temperature.

Additional features include input under-voltage lockout and thermal shutdown when the junction temperature of the ASL1500SHN exceeds +175 °C.

The device is housed in a very small HVQFN32 pin package with an exposed thermal pad. It is designed to meet the stringent requirements of automotive applications. It is fully AEC Q100 grade 1 qualified. It operates over the -40 °C to +125 °C ambient automotive temperature range.



3. Features and benefits

- The ASL1500SHN is an automotive grade product that is AEC-Q100 grade 1 qualified.
- Operating ambient temperature range of -40 °C to +125 °C
- Wide operating input voltage range from +5.5 V to +40 V
- Output voltage programmable via SPI interface
- Flexible output voltage with 3 % accuracy programmable via SPI
- Fixed Frequency Operation via built-in oscillator
- Slope compensation to track the frequency and output voltage
- Programmable control loop compensation
- Fast high efficiency FET switching
- Programmable internal gate driver voltage regulator
- Gate switching is halted when overvoltage on output is detected
- Support both Logic Level and Standard Level FETs
- Low Electro Magnetic Emission (EME) and high Electro Magnetic Immunity (EMI)
- Output voltage monitoring
- Supply voltage measurement
- Control signal to enable the device
- Read-back programmed voltage and frequency range via SPI
- Junction temperature monitoring via SPI
- Small package outline HVQFN32
- Low quiescent current <5 μA at 25 °C when EN = 0</p>

4. Applications

- Automotive LED lighting
 - Daytime running lights
 - Position or park light
 - Low beam
 - High beam
 - Turn indicator
 - Fog light
 - Cornering light

5. Ordering information

Table 1.Ordering information

| Type number | Package | | | | | |
|-------------|---------|--|-----------|--|--|--|
| | Name | Description | Version | | | |
| ASL1500SHN | HVQFN32 | plastic thermal enhanced very thin quad flat package; no leads; 32 terminals; body 5 \times 5 \times 0.85 mm | SOT617-12 | | | |

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6. Block diagram



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7. Pinning information

7.1 Pinning



7.2 Pin description

Table 2.Pin description[1]

| Symbol | Pin | Description | | | |
|--------------------|-----|---------------------|--|--|--|
| SNL1 | 1 | phase 1 sense low | | | |
| SNH1 | 2 | phase 1 sense high | | | |
| GND | 3 | ground | | | |
| G1 | 4 | phase 1 gate driver | | | |
| VGG | 5 | gate driver supply | | | |
| n.c. | 6 | not connected | | | |
| GND | 7 | ground | | | |
| n.c. | 8 | not connected | | | |
| n.c. | 9 | not connected | | | |
| n.c. | 10 | not connected | | | |
| FB1 ^[2] | 11 | feedback, output 1 | | | |
| n.c. | 12 | not connected | | | |
| VBAT | 13 | battery supply | | | |
| n.c. | 14 | not connected | | | |
| n.c. | 15 | not connected | | | |

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| Symbol | Pin | Description | | | |
|-----------------------|-----|----------------------|--|--|--|
| n.c. | 16 | not connected | | | |
| n.c. | 17 | not connected | | | |
| i.c. <mark>[3]</mark> | 18 | internally connected | | | |
| n.c. | 19 | not connected | | | |
| n.c. | 20 | not connected | | | |
| n.c. | 21 | not connected | | | |
| n.c. | 22 | not connected | | | |
| n.c. | 23 | not connected | | | |
| i.c. <mark>[3]</mark> | 24 | internally connected | | | |
| n.c. | 25 | not connected | | | |
| SDI | 26 | SPI Data Input | | | |
| SCLK | 27 | SPI Clock | | | |
| CSB | 28 | SPI chip select | | | |
| EN | 29 | enable signal | | | |
| VCC | 30 | external 5 V supply | | | |
| SDO | 31 | SPI Data Out | | | |
| GND | 32 | chip ground | | | |

[1] Not connected (n.c.) pins are internally not connected and can be left floating or can be connected to any voltage level.

[2] See <u>Figure 4</u> and <u>Figure 14</u> for recommend connections for pin FB1.

[3] Internally connected pins should be connected to GND.

For enhanced thermal and electrical performance, the exposed center pad of the package should be soldered to board ground (and not to any other voltage level).

8. Functional description



8.1 Operating modes

Table 3. Operating modes

| Mode | Control registers | Configuration registers | Diagnostic registers | VGG | Vout1 | Remarks |
|---------------|-------------------|-------------------------|-------------------------|--------------------------|--------------------------|---|
| Off | n.a. | n.a. | n.a. | off | off | device is off, no communication possible. |
| Configuration | read/write | read/write | read | off | off | VGG is off if no outputs were previously enabled |
| | | | read | according to register | off | VGG is on as soon as one of the outputs has been enabled |
| Operation | read/write | read | read | locked | according to register | configuration registers are locked |
| Fail silent | read/write | read | read ^[1] | off | off | communication possible, but all outputs off. Restart via EN possible. |

[1] Setting the bit cfg_dn to 0 also grants write access to the configuration registers.

8.1.1 Off mode

The ASL1500SHN switches to off mode, if the input voltage drops below the power-on detection threshold ($V_{th(det)pon}$) or the EN pin is low.

The SPI interface and output are turned off when the ASL1500SHN is in the Off mode.

8.1.2 Configuration mode

The ASL1500SHN switches from off mode to configuration mode, as soon the input voltage is above the power-on detection threshold ($V_{th(det)pon}$) and pin EN is high.

The configuration registers can be set when the ASL1500SHN is in the Configuration mode.

8.1.3 Operation mode

The ASL1500SHN switches from configuration mode to operation mode, as soon as the configuration done bit is set. Once the bit is set, the configuration registers are locked and cannot be changed.

In operation mode, the output is available as configured via the SPI interface. Setting the bit Vout1en, starts up the gate driver. Once the gate driver is in regulation (signaled by bit VGG_ok), the output voltage $V_{o1(prog)}$ is turned on accordingly. When the converters are on, the battery monitoring functionality is available.

8.1.4 Fail silent mode

The ASL1500SHN switches from Operation mode to Fail silent mode, when the junction temperature exceeds the over temperature shutdown threshold or a VGG error is detected. It will also switch modes when the input voltage is below the under voltage detection threshold or above the over voltage detection threshold.

In Fail silent mode, the output is turned off and only the SPI interface remains operational.

8.2 Boost converter configuration

The ASL1500SHN is an automatic boost converter IC delivering constant DC-to-DC voltage to a load. It has a fixed frequency current-mode control for an enhanced stable operation.

The ASL1500SHN offers one phase. The phase consists of a coil, a resistor, a MOSFET and a diode as shown in Figure 4.



To allow flexible use of the ASL1500SHN, the configuration is based on virtual phases. These phases are then mapped to a real, physical phase according to the physical connections and conditions of the circuitry around the ASL1500SHN as shown in Figure 5.



8.2.1 Configuration of the virtual phases

The ASL1500SHN can generate up to four internal phases at up to two virtual outputs. With the internal phase control enable registers, it can be selected, how many virtual phases are generated for the individual virtual outputs.

| Bit | Symbol | Description | Value | Function |
|-----|-------------------------|-----------------|-------|--|
| 7:4 | | reserved | 0000 | reserved; should remain cleared for future use |
| 3 | EN_P4_1 phase 4 enabled | | 0 | phase 4 is off |
| | | | 1 | phase 4 is enabled |
| 2 | EN_P3_1 phase 3 enable | phase 3 enabled | 0 | phase 3 is off |
| | | | 1 | phase 3 is enabled |
| 1 | EN_P2_1 | phase 2 enabled | 0 | phase 2 is off |
| | | | 1 | phase 2 is enabled |
| 0 | EN_P1_1 | phase 1 enabled | 0 | phase 1 is off |
| | | | 1 | phase 1 is enabled |

Table 4. Internal phase control enable for output 1, address 0x0Bh

| Bit | Symbol | Description | Value | Function |
|-----|-------------------------|-----------------------|--------------------|--|
| 7:4 | - | reserved | 0000 | reserved; should remain cleared for future use |
| 3 | 3 EN_P4_2 phase 4 e | phase 4 enabled | 0 | phase 4 is off |
| | | 1 | phase 4 is enabled | |
| 2 | 2 EN_P3_2 phase 3 er | phase 3 enabled | 0 | phase 3 is off |
| | | | 1 | phase 3 is enabled |
| 1 | EN_P2_2 phase 2 enabled | | 0 | phase 2 is off |
| | | | 1 | phase 2 is enabled |
| 0 | 0 EN_P1_2 | _P1_2 phase 1 enabled | 0 | phase 1 is off |
| | | | 1 | phase 1 is enabled |

Table 5. Internal phase control enable for output 2, address 0x0Ch

8.2.2 Association of physical phases to the output voltages

The phase that the ASL1500SHN offers, must be associated to the output.

Table 6. Gate driver output, address 0x02h

| Bit | Symbol | Description | Value | Function |
|-----|--------|---------------------|---------|--|
| 7:1 | | reserved | 0000000 | reserved; should remain clear for future use |
| 0 | O_G1 | association phase 1 | 0 | phase 1 is connected to Vout1 |
| | | | 1 | not allowed |

8.2.3 Association of connected phases to the internal phase generation

The physical phase that the ASL1500SHN offers, must be associated to one of the virtual phases of the output. It is established with the gate driver phase and phase select configuration registers.

Table 7. Gate driver phase, address 0x0Fh

| Bit | Symbol | Description | Value | Function |
|-----|--------|---------------------|--------|--|
| 7:1 | | reserved | 000000 | reserved; should remain clear for future use |
| 0 | O_GP1 | association phase 1 | 0 | phase 1 is connected to Vout1 |
| | | | 1 | not allowed |

Table 8. Phase select configuration, address 0x10h

| | • | | |
|-------------|---------------------|----------|---|
| Symbol | Description | Value | Function |
| | reserved | 0000 | reserved; should remain clear for future use |
| Phsel1[1:0] | association phase 1 | 0x0h | routing from phase 1 |
| | | 0x1h | routing from phase 2 |
| | | 0x2h | routing from phase 3 |
| | | 0x3h | routing from phase 4 |
| | - | reserved | reserved 0000 Phsel1[1:0] association phase 1 0x0h 0x1h 0x2h |

8.2.4 Enabling of connected phases

The gate driver enable register is used to configure which of the phases is active.

| Bit | Symbol | Description | Value | Function |
|-----|--------|-----------------|---------|--|
| 7:1 | | reserved | 0000000 | reserved; should remain clear for future use |
| 0 | EN_G1 | phase 1 enabled | 0 | phase 1 is off |
| | | | 1 | phase 1 is enabled |

Table 9. Gate driver enable, address 0x01h

8.2.5 Configuration of the boost converter frequencies

The operation frequency of the boost converter can be set with via several SPI registers. For the regulation loop, an integer number downscales the internal oscillator frequency. The slower clock controls the off-time of a phase and the delay from one phase of the regulation loop to the next internal phase. The number of phases determinates finally when the phase is turned on again and defines so the operation frequency of the boost converter.



Fig 6. Phase control generator

Table 10. Clock divider for Vout1, address 0x09h

| Bit | Symbol | Description | Value | Function |
|-----|---------|-------------------|-------|------------------------------------|
| 7:0 | Clkdiv1 | clock divider for | 0x00h | clock is not divided |
| | [7:0] | output voltage 1 | | clock is divided by clkdiv1[7:0]+1 |
| | | | 0xFFh | clock is divided by 256 |

| Bit | Symbol | Description | Value | Function |
|-----|--|-------------------|---|--|
| 7:3 | 7:3 Phdel1 delay to next [4:0] phase of output1 | | 0x0h | phase delay is 1 clock period of the divided clock |
| | | | phase delay is Phdel1[4:0]+1 clock period of the divided clock | |
| | | | 0x1Fh | phase delay is 32 clock periods of the divided clock |
| 2:0 | Phoff1 | phase-off time of | 0x0h | phase-off time is 1 clock period of the divided clock |
| | [2:0] output1 | output1 | | phase-off time is Phoff1[2:0] clock period of the divided clock |
| | | | 0x7h | phase-off time is 7 clock periods of the divided clock |

 Table 11.
 Phase-off time and phase delay of output 1, address 0x0Dh

Note: To obtain the best performance of the internal slope compensation, keep the settings of the delay between the phases as close to 32 as possible.

8.2.6 Control loop parameter setting

The ASL1500SHN is able to operate with a wide range of external components and offers wide range of operating frequencies. To achieve maximum performance for each set of operation conditions, set the control loop parameters in accordance with the external components and operating frequency.

| Bit | Symbol | Description | Value | Function |
|-----|------------|-----------------|-------|--|
| 7:4 | | reserved | 0000 | reserved; should remain cleared for future use |
| 3:0 | Prop1[3:0] | proportional | 0x0h | proportional factor output 1 is 0.05 |
| | | factor output 1 | | proportional factor output 1 is Prop1[3:0]*0.05+0.05 |
| | | | 0xFh | proportional factor output 1 is 0.8 |

Table 12. Loop filter proportional configuration, address 0x11h

Table 13. Loop filter integral configuration, address 0x12h

| | | - | - | |
|-----|-------------|-----------------|----------------------------------|---|
| Bit | Symbol | Description | Value | Function |
| 7:4 | | reserved | 0000 | reserved; should remain cleared for future use |
| 3:0 | Integ1[3:0] | integral factor | 0x0h | integral factor output 1 is 0.005 |
| | | output 1 | | integral factor output 1 is Integ1[3:0]*0.005+0.005 |
| | | 0xFh | integral factor output 1 is 0.08 | |

Table 14. Slope compensation configuration, address 0x13h

| Bit | Symbol | Description | Value | Function |
|-----|--------------|---------------------------------|-------|---|
| 7:4 | | reserved | 0000 | reserved; should remain cleared for future use |
| 3:0 | Slpcmp1[3:0] | slope | 0x0h | slope compensation factor output 1 = 112 k Ω |
| | | compensation factor output 1 | 0x1h | slope compensation factor output 1 = 84 k Ω |
| | | | 0x2h | slope compensation factor output 1 = 70 k Ω |
| | | | 0x4h | slope compensation factor output 1 = 56 k Ω |
| | | | 0x8h | slope compensation factor output 1 = 28 k Ω |

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| | | | | - |
|-----|------------------------------------|----------------|----------------|--|
| Bit | Symbol | Description | Value | Function |
| 7:2 | | reserved | 0000 | reserved; should remain cleared for future use |
| 1:0 | Slpr1[1:0] | slope resistor | 0x0h | 2'b00 - 250 Ω |
| | configuration for gate driver 1 | • | 0x1h | 2'b01 - 500 Ω |
| | | 0x2h | 2'b10 - 1000 Ω | |
| | | | 0x3h | 2'b11 - 1500 Ω |
| | | | | |

 Table 15.
 Current sense slope resistor configuration, address 0x14h

8.3 Output voltage programmability

The ASL1500SHN provides the possibility to program the output voltage and output overvoltage protection of the output via the SPI interface.

8.3.1 Output voltage target programming

The target output voltage can be programmed via the Output voltage registers. As the ASL1500SHN is a boost converter, the output voltage cannot be lower than the supply voltage minus the drop of the converter diode (Dx in Figure 4).

| Bit | Symbol | Description | Value | Function |
|-----|---------------|----------------|---|--------------------------------------|
| 7:0 | V_Vout_1[7:0] | target voltage | 0x00h | output 1 is turned off |
| | output 1 | | target voltage output 1 = 0.3606 * V_Vout_1[7:0] | |
| | | | 0xFFh | maximum target output voltage = 90 V |

Table 16. Output voltage 1 register, address 0x03h

8.3.2 Output overvoltage protection programming

Due to fast changes in the supply or the output, it is possible that the output voltage is disturbed. To avoid high voltages that may result into damage of attached components, the ASL1500SHN offers a programmable overvoltage protection threshold. Once the output voltage is above this threshold, the gate pin of the output stops toggling. It results in a halt of the energy delivery to the output.

Once the output voltage recovers and is below the threshold again, the gate pin starts toggling again. The regulation loop regulates the output back to the target value.

For stable operation of the device, the limit voltage output register should be programmed around 5 V higher than the output voltage registers.

| Bit | Symbol | Description | Value | Function |
|-----|------------------|---------------|-------|---|
| 7:0 | Vmax_Vout_1[7:0] | limit voltage | 0x00h | output 1 is turned off |
| | output 1 | | | target voltage output 1 = 0.3606 * Vmax_Vout_1[7:0] |
| | | | 0xFFh | maximum output over voltage protection output 1 = 90 V |

Table 17. Limit voltage output 1 register, address 0x05h

8.4 Coil peak current limitation

The ASL1500SHN offers a function to limit peak current inside the coil and therefore to limit the input current for the system. Furthermore this functionality can be used to avoid magnetic saturation of the coils. It also allows some soft start feature to be realized with this function.

With the Max phase current Vout1 register, the maximum peak current for the phase can be configured. Once the voltage between pins SNSLx and SNSHx reaches this level, the gate will be turned off until the next switching cycle. To avoid sub harmonic oscillations when the coil peak current limitation is becoming active, the slope compensation remains active. It reduces the coil peak current towards the end of the switching cycle to ensure stable operation of the system.

In order to avoid that this function interferes with the normal regulation, the limit should be placed well above the max expected current.

| Bit | Symbol | Description | Value | Function |
|-----|------------|--------------|-------|---|
| 7:0 | I_max[7:0] | coil current | 0x00h | no current allowed |
| | | limitation | | maximum peak current = (I_max_per_phase_Vout1 [7:0] * 1.8 V / 256 - 0.24 V) / R _{sense} |
| | | (| | max allowed setting = (128/255*1,8V-0,24) V / R_{sense} |
| | | | | not allowed |
| | | | 0xFFh | not allowed |

Table 18. Maximum phase current Vout1 register, address 0x07h

8.5 Enabling the output voltage

The ASL1500SHN provides one output voltage. In operation mode, the output voltage is turned on with the bit Vout1en.

As soon as the output is turned on, the VGG voltage regulator is turned on. After the gate driver start-up time, the gate driver starts switching, provided the bit VGG_ok is set.

| Bit | Symbol | Description | Value | Function |
|-----|---------|-------------|---|--|
| 7:4 | | reserved | 0000 | reserved; should remain cleared for future use |
| 3 | Cnt_CSB | count chip | 0 chip select low count feature is disabled | |
| | | select time | 1 | chip select low count feature is enabled |
| 2 | | reserved | 0 | reserved; should remain cleared for future use |
| 1 | Vout1en | enable | 0 | output 1 is turned off |
| | | output 1 | 1 | output 1 is turned on when the device is in operation mode |
| 0 | | | 0 | device is in configuration mode - no configuration lock |
| | | done bit | 1 | device is in operation mode - configuration lock is active |

Table 19. Function control register, address 0x00h

8.6 Frequency trimming

To ensure the ASL1500SHN operates inside the specified oscillator frequency range, it is mandatory to adjust the internal oscillator frequency of the device.

To measure the actual internal frequency, the device is measuring the time that the CSB pin is low during an SPI transfer. This time information can be used to adjust the oscillator frequency of the device. The recommended procedure for the time adjustment is shown in Figure 7.



At the start of the sequence, the CSB low count feature is activated. It is done by setting the Cnt_CSB bit high in the frequency trimming control register (bit 3; register 0x00h). The device now measures the time with its internal time domain each time the CSB pin is low. It makes this information available in the CSB count registers. To allow an exact stable reading, set the Cnt_CSB bit low again with an accurately known CSB low time. Setting the bit low freezes the count registers. These registers store the last value, which in this case is the command that sets the Cnt_CSB bit low.

The CSB count registers contain the count of the CSB low time of the last SPI command the CSB low count feature was enabled. CSB count register 1 contains the bits 7 to 0 of the counter, while the CSB count register 2 contains the bits 15:8.

Table 20. CSB count register 1, address 0x41h

| | | • · · · | | |
|-----|--------------|---------------|-------|------------------------|
| Bit | Symbol | Description | Value | Function |
| 7:0 | CSB_cnt[7:0] | CSB count low | | count value (bits 7:0) |

Table 21. CSB count register 2, address 0x42h

| Bit | Symbol | Description | Value | Function |
|-----|---------------|----------------|-------|-------------------------|
| 7:0 | CSB_cnt[15:8] | CSB count high | | count value (bits 15:8) |

The count, the CSB count register returns, should correspond to the real time of the CSB low time. 1 count should correspond with $1/f_{osc_trimmed}$ (see <u>Table 39</u>).

When the count that the CSB count registers return, deviates from the applied CSB low time, the device internal timing must be adjusted by modifying the frequency trimming register.

| Bit | Symbol | Description | Value | Function |
|-----|----------------|---------------------|--------|-----------------------------|
| 7:6 | | reserved | | not allowed |
| 5:0 | Freq_trim[5:0] | frequency trim bits | 010001 | default frequency -33.33 % |
| | | | 010011 | default frequency -30.56 % |
| | | | 010101 | default frequency -27.78 % |
| | | | 010111 | default frequency –25.00 % |
| | | | 011001 | default frequency -22.22 % |
| | | | 011011 | default frequency -19.44 % |
| | | | 011101 | default frequency -16.67 % |
| | | | 011111 | default frequency -13.89 % |
| | | | 000001 | default frequency -11.11 % |
| | | | 000011 | default frequency -8.33 % |
| | | | 000101 | default frequency -5.56 % |
| | | | 000111 | default frequency -2.78 % |
| | | | 001001 | default frequency |
| | | | 001011 | default frequency + 2.78 % |
| | | | 001101 | default frequency + 5.56 % |
| | | | 001111 | default frequency + 8.33 % |
| | | | 110001 | default frequency + 11.11 % |
| | | | 110011 | default frequency + 13.89 % |
| | | | 110101 | default frequency + 16.67 % |
| | | | 110111 | default frequency + 19.44 % |
| | | | 111001 | default frequency + 22.22 % |
| | | | 111011 | default frequency + 25.00 % |
| | | | 111101 | default frequency + 27.78 % |
| | | | 111111 | default frequency + 30.56 % |
| | | | 100001 | default frequency + 33.33 % |
| | | | 100011 | default frequency + 36.11 % |
| | | | others | not allowed |

Table 22. Frequency trimming register, address 0x1Ch

To ensure that the adjustment had the desired effect, restart the procedure and check the count with the new settings in the frequency trimming register.

When the device internal time matches the applied CSB low time, no further adjustment is needed and the trimming procedure is finished.

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8.7 Gate voltage supply

The ASL1500SHN has an integrated linear regulator to generate the supply voltage of the gate driver, which is internally connected to the pin VGG. The voltage generated by the linear regulator can be set via the VGG control register.

| | Table 23. | VGG control | register. | address 0x15h |
|--|-----------|-------------|-----------|---------------|
|--|-----------|-------------|-----------|---------------|

| Bit | Symbol | Description | Value | Function |
|--------------|-----------------|----------------|-------------|----------------------------------|
| 7:0 VGG[7:0] | VGG[7:0] | supply voltage | 0x00h | not allowed |
| | for gate driver | | not allowed | |
| | | | 0x5Dh | maximum output voltage = 10.04 V |
| | | | | (255- VGG[7:0]) * 62 mV |
| | | | 0xB7h | minimum output voltage = 4.46 V |
| | | | | not allowed |
| | | | 0xFFh | not allowed |

The actual value of VGG can deviate from the target setting due to the tolerances of the VGG regulation loop (see $V_{o(reg)acc}$ in Table 38).

When a setting between 0x00h and 0x5Dh is used, the resulting gate driver target voltage exceeds the limiting values of the IC. The limiting values of the VGG pin can also be violated with target settings of 0xA6h to 0x5Dh due to these tolerances. A violation of the limiting values with the actual VGG voltage must be avoided. To ensure that only allowed settings are used for the gate driver target voltage, an immediate read back of the programmed value is required after setting the registers.

If a setting between 0xFFh and 0xB7h is used, the device may not start up VGG. If the device operates, parameters of VGG are not guaranteed.

8.7.1 Gate voltage supply diagnostics

The diagnostic options for the gate voltage supply are:

- VGG available. Details can be found in <u>Section 8.10</u>
- VGG protection active. Details can be found in <u>Section 8.10</u>

8.8 Supply voltage monitoring

The ASL1500SHN is continuously measuring the voltage at pin VBAT, when the output is enabled and bit VGG_ok is set. It allows the system to monitor the supply voltage without additional external components. It also offers the option to put an automatic under- and/or overvoltage protection in place.

Note: The VIN_UV and VIN_OV bits in the status register use the battery voltage measurement. Consequently the VIN_UV and VIN_OV bits are only reliable when the output is enabled.

8.8.1 Battery voltage measurement

The ASL1500SHN is continuously measuring the voltage at pin VBAT. The measurement result is available in the battery voltage register when the output is enabled.

| Ιαμι | Table 24. Dattery Voltage register, address 0.44511 | | | | | | | | |
|------|---|-----------------|-------|---|--|--|--|--|--|
| Bit | Symbol | Description | Value | Function | | | | | |
| 7:0 | V_VBAT[7:0] | battery voltage | 0x00h | battery voltage = 0 V | | | | | |
| | | | | battery voltage = 0.3606 *V_VBAT[7:0] | | | | | |
| | | | 0xFFh | maximum measurable battery voltage = 90 V | | | | | |

Table 24. Battery voltage register, address 0x45h

8.8.2 Undervoltage detection

The ASL1500SHN offers a variable under voltage detection threshold. When the supply voltage drops below this threshold, the undervoltage detect bit is set and Fail silent mode is entered. The gate pin stops toggling and no more power is delivered to the output.

Table 25. Undervoltage threshold register, address 0x1Bh

| Bit | Symbol | Description | Value | Function |
|-----|--|-------------|--|---|
| 7:0 | 7:0 V_VIN_UV[7:0] undervoltage detection threshold | 0x00h | undervoltage detection threshold = 0 V | |
| | | | undervoltage detection threshold = 0.3606 *V_VIN_UV[7:0 | |
| | | | 0xFFh | maximum undervoltage detection threshold = 90 V |

8.8.3 Overvoltage detection

The ASL1500SHN offers a variable overvoltage detection threshold. When the supply voltage rises above this threshold, the overvoltage detect bit is set, and Fail silent mode is entered. The gate pin stops toggling and no more power is delivered to the output.

Table 26. Overvoltage threshold register, address 0x1Ah

| Bit | Symbol | Description | Value | Function |
|-----|---------------|------------------------|-------|---|
| 7:0 | V_VIN_OV[7:0] | overvoltage | 0x00h | overvoltage detection threshold = 0 V |
| | | detection threshold | | overvoltage detection threshold = 0.3606 *V_VIN_OV[7:0 |
| | | | 0xFFh | maximum overvoltage detection threshold = 90 V |

8.9 Junction temperature information

The ASL1500SHN provides a measurement of the IC junction temperature. The measurement information is available in the junction temperature register.

Table 27. Junction temperature register, address 0x46h

| Bit | Symbol | Description | Value | Function |
|-----|--------------------------|-------------|---|---|
| 7:0 | T_junction[7:0] junction | | device junction temperature below –40 $^\circ\text{C}$ | |
| | | temperature | 0x18h | device junction temperature = $-40 \degree C$ |
| | | | device junction temperature = T_junction[7:0] * (215/106) °C – 88 °C | |
| | | | 0x82h | device junction temperature = 175 °C |

8.10 Diagnostic information

The diagnostic register contains useful information for diagnostic purposes. Details for each bit can be found in the following subchapters.

| Bit | Symbol | Description | Value | Function | | | | | |
|-----|----------------------------|-----------------------------|-------|---|--|--|--|--|--|
| 7 | Vout1_ok | ut1_ok Vout1 regulated 0 | | Vout1 is deviating from the target value | | | | | |
| | | | 1 | Vout1 is regulated to the target value | | | | | |
| 6 | | reserved | 0 | Reserved; should remain clear for future use | | | | | |
| 5 | VGG_ok | VGG regulation OK | 0 | VGG is not available | | | | | |
| | | | 1 | VGG is available | | | | | |
| 4 | Tj_err | Tj_err device temperature 0 | | device temperature below T _{sd(otp)} | | | | | |
| | | is too high | 1 | device temperature above T _{sd(otp)} | | | | | |
| 3 | 3 VIN_UV VIN under voltage | | 0 | no under voltage at VIN detected | | | | | |
| | | | 1 | under voltage at VIN detected | | | | | |
| 2 | VIN_OV | VIN over voltage | 0 | no over voltage at VIN detected | | | | | |
| | | | 1 | over voltage at VIN detected | | | | | |
| 1 | SPI_err | SPI error | 0 | last SPI command was executed correctly | | | | | |
| | | | 1 | last SPI command was erroneous and has been discarded | | | | | |
| 0 | VGG_err | VGG error | 0 | VGG overload protection not active | | | | | |
| | | | 1 | VGG overload protection has turned on and VGG i deactivated | | | | | |

 Table 28.
 Undervoltage threshold register, address 0x0Fh

8.10.1 Bit VIN_OV

The bit VIN_OV depends on the battery monitoring functionality as described in <u>Section 8.8</u>. It indicates that the device has detected an overvoltage condition and entered Fail silent mode. A write access to the diagnostic register or when the Off mode has been entered, clears the bit. Independent of the clearing of the bit, the device stays in Fail silent mode.

8.10.2 Bit VIN_UV

The bit VIN_UV depends on the battery monitoring functionality as described in <u>Section 8.8</u>. It indicates that the device has detected an undervoltage condition and entered Fail silent mode. A write access to the diagnostic register or when the Off mode has been entered, clears the bit. Independent of the clearing of the bit, the device stays in Fail silent mode.

8.10.3 Bit SPI_err

The device is evaluating all SPI accesses to the device for the correctness of the commands. When the command is not allowed, the SPI_err bit is set.

A write access to the diagnostic register or when the Off mode is entered, clears the bit.

8.10.4 Bit Tj_err

The bit Tj_err indicates that the junction temperature has exceeded the maximum allowable temperature, and the device has entered Fail silent mode. A write access to the diagnostic register, or once Off mode has been entered, clears the bit. The device stays in Fail silent mode irrespective of the clearing of the bit. After leaving the OFF mode (at IC start-up), it is possible that bit Tj_err is set. To avoid wrong diagnostics, clear the diagnostic register before it is evaluated.

8.10.5 Bit VGG_err

Bit VGG_err is set when the gate driver does not reach the VGG_ok _window (when V_{VGG} is within range) within the regulator voltage start-up error time. Once bit VGG_err is set, it indicates that an error on the gate driver has been detected and the device has entered Fail silent mode. A write access to the diagnostic register, or once Off mode has been entered, clears the bit. The device stays in Fail silent mode irrespective of the clearing of the bit.

8.10.6 Bit VGG_ok

The bit VGG_ok indicates that the gate driver is regulated to the target voltage and allows the gate driver to drive the gate driver pin. If the gate driver is outside the VGG_ok window after $t_{startup}$, and V_{VGG} is within range, the device clears VGG_ok bit and enters Fail silent mode.

8.10.7 Bit Vout1_ok

The bit Vout1_ok indicates whether the output voltage is regulated to the target value or deviating from the target value. The bit is set, as soon as the output is within the Vout_ok window (when V_O is within the range) for more than Vout t_{fltr} . The bit is cleared when the output is outside the Vout_ok window for more than Vout t_{fltr} .

8.11 SPI

The ASL1500SHN uses an SPI interface to communicate with an external microcontroller. The SPI interface can be used for setting the LEDs current, reading and writing the control register.

8.11.1 Introduction

The Serial Peripheral Interface (SPI) provides the communication link with the microcontroller, supporting multi-slave operations. The SPI is configured for full duplex data transfer, so status information is returned when new control data is shifted in. The interface also offers a read-only access option, allowing the application to read back the registers without changing the register content.

The SPI uses four interface signals for synchronization and data transfer:

- CSB SPI chip select; active LOW
- SCLK SPI clock default level is LOW due to low-power concept
- SDI SPI data input
- SDO SPI data output floating when pin CSB is HIGH

Bit sampling is performed on the falling clock edge and data is shifted on the rising clock edge as illustrated in Figure 8.

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The data bits of the ASL1500SHN are arranged in registers of one-byte length. Each register is assigned to a 7-bit address. For writing into a register, 2 bytes must be sent to the LED driver. The first byte is an identifier byte that consists of the 7-bit address and one read-only bit. For writing, the read-only bit must be set to 0. The second byte is the data that is written into the register. So an SPI access consists of at least 16 bit.

Figure 9 together with Table 29 and Table 30 demonstrate the SPI frame format.



| Table 29. | SPI frame format for a transition to the device |
|-----------|---|
|-----------|---|

| Bit | Symbol | Description | Value | Function |
|------|--------|--------------|-------|------------------|
| 15 | b15 | R/W bits | 0 | write access |
| | | | 1 | read access |
| 14:8 | b14:8 | address bits | | selected address |
| 7:0 | b7:0 | data bits | | transmitted data |

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| Bit | Symbol | Description | Value | Function ^[1] | | | | | |
|------|--------|---------------------|-------|--|--|--|--|--|--|
| 8:15 | b8:15 | diagnostic register | | content of diagnostic register | | | | | |
| 7:0 | b7:0 | data bits | | when previous command was a valid read command, content of the register that is supposed to be read | | | | | |
| | | | | when previous command was a valid write command, new content of the register that was supposed to be written | | | | | |

Table 30. SPI frame format for a transition from the device

[1] The first SPI command after leaving the Off mode, will return 0x00h.

The Master initiates the command sequence. The sequence begins with CSB pin pulled low and lasts until it is asserted high.

The ASL1500SHN also tolerates SPI accesses with a multiple of 16 bits. It allows a daisy chain configuration of the SPI.





During the SPI data transfer, the identifier byte and the actual content of the addressed registers is returned via the SDO pin. The same happens for pure read accesses. Here the read-only bit must be set on logic 1. The content of the data bytes that are transmitted to the ASL1500SHN is ignored.

The ASL1500SHN monitors the number of data bits that are transmitted. If the number is not 16, or a multiple of 16, then a write access is ignored and the SPI error indication bit is set.

8.11.2 Typical use case illustration (Write/Read)

Consider a daisy chain scheme with one master connected to 4 slaves in daisy chain fashion. The following commands are performed during one sequence (first sequence):

- Write data 0xFF to register 0x1A Slave 1
- Read from register 0x02 of Slave 2
- Write data 0xAF to register 0x2F of Slave 3
- Read from register 0x44 of Slave 4

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8.11.3 Diagnostics for the SPI interface

The device is evaluating all SPI access to the device for the correctness of the commands. When the command is not allowed, the SPI_err bit is set. The conditions that are considered as erratic accesses are:

- SPI write is attempted to a read-only location or reserved location
- SPI read is attempted from a reserved location
- SPI command does not consist of a multiple of 16 clock counts

If an SPI access is considered to be erratic, no modifications to a SPI register are made. The access after the erratic SPI command returns the diagnostic register and zero in the data field.

For details about the SPI_err bit, see <u>Section 8.10.3</u>.

8.12 Register map

The addressable register space amounts to 128 registers from 0x00 to 0x7F. They are separated in two groups as shown in <u>Table 31</u>. The register mapping is shown in <u>Table 32</u>, <u>Table 33</u>, <u>Table 34</u> and <u>Table 35</u>. The functional description of each bit can be found in the dedicated chapter.

Table 31. Register space grouping

| Address range | Description | Content |
|---------------|----------------------|------------------------|
| 0x00 0x1F | control registers | control registers |
| 0x20 0x7F | diagnostic registers | diagnostic information |

8.12.1 Control registers

Table 32 provides an overview of the control registers and their reset value.

 Table 32.
 Control register group overview

| Address | Name | Reset value | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|---------|--------------------------------------|-------------|------------|----------------|---|----|------------|-------|------------------------|--------|--|
| 0x00h | function control | 0x00h | - | - | - | - | Cnt_CSB | - | Vout1en ^[1] | Cfg_dn | |
| 0x01h | gate driver enable | 0x00h | - | - | - | - | - | - | - | EN_G12 | |
| 0x03h | (03h target voltage output 1 0x00h | | | V_Vout_1[7:0] | | | | | | | |
| 0x05h | limit voltage output 1 | 0x00h | | | | Vr | nax_Vout_1 | [7:0] | | | |
| 0x07h | maximum phase current Vout1 | 0x46h | I_max[7:0] | | | | | | | | |
| 0x1Ch | frequency trimming 0x09h register | | | Freq_trim[5:0] | | | | | | | |

[1] Bit is locked with bit Cfg_dn is high. When bit Cfg_dn is low, bits can be changed. Read is always possible.

[2] If the gate driver is enabled when bits Cfg_dn and VGG_ok are set high, it can be turned on and off during operation of the system. The gate driver, disabled when bits Cfg_dn and VGG_ok are set high, remains off, even when the gate enable bit is set high later.

8.12.2 Configuration registers

<u>Table 33</u> provides an overview of the configuration registers. The configuration registers inside the control block can only be written in configuration mode. In the other modes, this register can only be read.

| Address | Name | Reset value | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|--|----------------|--------|---|---|--------------|-------------|---------|---------|---------|
| 0x02h | gate driver output | 0x00h | - | - | - | - | - | - | - | O_G1 |
| 0x09h | clock divider for output 1 | 0x0Fh | | | | | Clkdiv1[7 | :0] | | |
| 0x0Bh | internal phases output 1 | 0x0Fh | - | - | - | - | EN_P4_1 | EN_P3_1 | EN_P2_1 | EN_P1_1 |
| 0x0Ch | internal phases output 2 | 0x0Fh | - | - | - | - | EN_P4_2 | EN_P3_2 | EN_P2_2 | EN_P1_2 |
| 0x0Dh | 0x0Dh phase off and delay output 1 | | Phdel1 | | | | Phoff1 | | | 1 |
| 0x0Fh | gate driver phase | 0x00h | - | - | - | - | - | - | - | O_GP1 |
| 0x10h | phase selection configuration | 0xE4h | - | 1 | | - | - | 1 | Ph | sel1 |
| 0x11h | loop filter proportional configuration | 0x00h | | | - | | Prop1[3:0] | | | |
| 0x12h | loop filter integral configuration | 0x00h | | | - | | Integ1[3:0] | | | |
| 0x13h | 0x13h slope compensation configuration | | - | | | Slpcmp1[3:0] | | | | |
| 0x14h | current sense slope resistor configuration | 0x00h | - | | | - | - | | Slpr | 1[1:0] |

Table 33. Configuration register group overview

| Table 55. | configuration register group overviewcontinued | | | | | | | | | |
|-----------|--|----------------|---------------|---------------|---|---|---|---|---|---|
| Address | Name | Reset value | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x15h | VGG control | 0xFFh | | VGG[7:0] | | | | | | |
| 0x1Ah | over voltage detection threshold | 0xFFh | | V_VIN_OV[7:0] | | | | | | |
| 0x1Bh | under voltage detection threshold | 0x00h | V_VIN_UV[7:0] | | | | | | | |

Table 33. Configuration register group overview ...continued

8.12.3 Internal registers

The ASL1500SHN uses the SPI registers to control some internal functions. In order to avoid any unintended behavior of the device, do not modify these registers but leave them all at their default value.

Table 34.Internal register overview

| Address | Name | Reset value | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|-------------|-------------|---|---|---|---|---|---|---|---|
| 0x04h | Internal 1 | 0x00h | - | - | - | - | - | - | - | - |
| 0x06h | Internal 2 | 0x00h | - | - | - | - | - | - | - | - |
| 0x08h | Internal 3 | 0x46h | - | - | - | - | - | - | - | - |
| 0x0Ah | Internal 4 | 0x0Fh | - | - | - | - | - | - | - | - |
| 0x0Eh | Internal 5 | 0x39h | - | - | - | - | - | - | - | - |
| 0x19h | Internal 6 | 0x82h | - | - | - | - | - | - | - | - |
| 0x25h | Internal 7 | 0x27h | - | - | - | - | - | - | - | - |
| 0x26h | Internal 8 | 0x3Bh | - | - | - | - | - | - | - | - |
| 0x2Fh | Internal 9 | 0xE8h | - | - | - | - | - | - | - | - |
| 0x30h | Internal 10 | 0x09h | - | - | - | - | - | - | - | - |

8.12.4 Diagnostic registers

The ASL1500SHN provides diagnostic data via some SPI registers. These registers are read only, but error bits can be cleared via a write access to the register.

| Table 35. D | Diagnostic | register | group | overview |
|-------------|------------|----------|-------|----------|
|-------------|------------|----------|-------|----------|

| Address | Name | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----------------------|-----------------|---|--------|--------|--------|--------|---------|---------|
| 0x41h | CSB count low | CSB_cnt[7:0] | | | | | | | |
| 0x42h | CSB count high | CSB_cnt[15:8] | | | | | | | |
| 0x45h | battery voltage | V_VBAT[7:0] | | | | | | | |
| 0x46h | junction temperature | T_junction[7:0] | | | | | | | |
| 0x5Fh | diagnostic Register | Vout1_ok | - | VGG_ok | Tj_err | VIN_UV | VIN_OV | SPI_err | VGG_err |

9. Limiting values

Table 36. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------------|--------------------------------------|---|------|------|------|
| V _{BAT} | battery supply voltage | EN = low | -0.3 | +60 | V |
| | | EN = high | -0.3 | +40 | V |
| V _{VCC} | voltage on pin VCC | | -0.3 | +5.5 | V |
| V _{GND} | ground supply voltage | voltage between ground pins | -0.6 | +0.6 | V |
| V _{FBx} | voltage on feedback pins | FB1 | -0.3 | +90 | V |
| Vo | output voltage | programmed target voltage according to register 0x03h | 10 | +80 | V |
| V _{I(dig)} | digital input voltage | voltage on digital pins SDO, SDI, CSB, SCLK and EN | -0.3 | +5.5 | V |
| V _{VGG} | voltage on pin VGG | | -0.3 | +10 | V |
| V _{sense} | sense voltage | voltage on sense pins SNH1 and SNL1 | -0.3 | +0.3 | V |
| V _G | voltage on gate pin | G1 | -0.3 | +10 | V |
| V _{ic} | voltage on internally connected pins | i.c. | -0.3 | +1.8 | V |
| Tj | junction temperature | | -40 | +175 | °C |
| T _{stg} | storage temperature | | -55 | +175 | °C |
| V _{ESD} | electrostatic discharge voltage | HBM[1] | I | I | |
| | | at any pin | -2 | +2 | kV |
| | | at pin VBAT with 100 nF at pin | -6 | +6 | kV |
| | | CDM[2] | | | |
| | | at any pin | -500 | +500 | V |

[1] Human Body Model (HBM): according to AEC-Q100-002 (100 pF, 1.5 k $\Omega)$

[2] Charged Device Model (CDM): according to AEC-Q100-011 (field Induced charge; 4 pF).

10. Thermal characteristics

Table 37.Thermal characteristics

| Symbol | Parameter | Conditions | Тур | Unit |
|-----------------|--------------------|--------------------------------------|-----|------|
| R _{th} | thermal resistance | HVQFN32 package JEDEC ^[1] | 37 | K/W |

 According to JEDEC JESD51-2, JESD51-5 and JESD51-7 at natural convection on 2s2p board. Board with two inner copper layers (thickness: 35 μm) and thermal via array under the exposed pad connected to the first inner copper layer.

11. Static characteristics

Table 38. Static characteristics

Min and Max values are specified for the following conditions: $V_{BAT} = 5.5 \text{ V}$ to 40 V, $V_{EN} = 4.5 \text{ V}$ to 5.5 V, $V_{VCC} = 4.5 \text{ V}$ to 5.5 V and $T_j = -40 \text{ °C}$ to +175 °C^[1]. All voltages are defined with respect to ground, positive currents flow into the IC. Typical values are given at $V_{VIN} = 40 \text{ V}$. $V_{EN} = 5 \text{ V}$, $V_{VCC} = 5 \text{ V}$ and $T_j = 25 \text{ °C}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|--------------------------|---|---|--------------------------|-----|--------------------------|------|
| Supply pin | Vbat | | | | | |
| I _{DD} | supply current | operating; no load on VGG; Gate pins low; one phase; one output | 5 | 13 | - | mA |
| | | operating; no load on VGG; Gate pins low | - | 20 | - | mA |
| I _{off} | off-state current | EN = low | - | - | 5 | μA |
| V _{th(det)pon} | power-on detection threshold voltage | | - | - | 4.5 | V |
| Supply pin | VCC | | | | | |
| I _{VCC} | supply current on pin VCC | operating | - | - | 250 | μA |
| Pin EN | | | | _ | | |
| I _{EN} | current on pin EN | operating | - | - | 2 | mA |
| Output volt | age | | | | | |
| V _{O(acc)} | output voltage accuracy | deviation from target set value | -0.03 × Vout1 - 0.721 | - | +0.03 × Vout1 + 0.721 | V |
| Vo | output voltage | bit Vout_ok is set when V _O is within the range with respect to the target value | -5.4 | - | +2.4 | V |
| Regulated v | voltage output | | | | | |
| V _{VGG} | voltage on pin VGG | $V_{BAT} \geq V_{VGG} + V_{do(reg)VGG}$ | 4.46 | - | 10.04 | V |
| | | bit VGG_ok is set when V_{VGG} is within the range regarding the target value | -2.4 | - | +2.4 | V |
| V _{do(reg)} VGG | regulator dropout voltage on pin VGG | $I_{reg} \le 50$ mA; regulator in saturation | - | 0.5 | 1.0 | V |
| | | $I_{reg} \le 160 \text{ mA}$; regulator in saturation | - | 1.6 | 3.2 | V |
| V _{reg(acc)VGG} | regulator voltage | 25 °C to T _{j(max)} | -5 | - | +5 | % |
| | accuracy on pin VGG | –40 °C to +25 °C | -7 | - | +5 | % |
| Serial perip | heral interface inputs; pin | s SDI, SCLK and CSB | | | | |
| V _{th(sw)} | switching threshold voltage | | $0.3 \times V_{VCC}$ | - | $0.7 \times V_{VCC}$ | V |
| R _{pd(int)SCLK} | internal pull-down resistance on pin SCLK | | 40 | - | 80 | kΩ |
| R _{pd(int)CSB} | internal pull-down resistance on pin CSB | | 40 | - | 80 | kΩ |
| R _{pd(int)SDI} | internal pull-down resistance on pin SDI | | 40 | - | 80 | kΩ |

Table 38. Static characteristics ... continued

Min and Max values are specified for the following conditions: $V_{BAT} = 5.5 \text{ V}$ to 40 V, $V_{EN} = 4.5 \text{ V}$ to 5.5 V, $V_{VCC} = 4.5 \text{ V}$ to 5.5 V and $T_j = -40 \text{ °C}$ to +175 °C^[1]. All voltages are defined with respect to ground, positive currents flow into the IC. Typical values are given at $V_{VIN} = 40 \text{ V}$. $V_{EN} = 5 \text{ V}$, $V_{VCC} = 5 \text{ V}$ and $T_j = 25 \text{ °C}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|----------------------|---|---|----------------------------------|-----|----------------------------------|------|
| Serial peri | pheral interface data output | ; pin SDO | I. | | | |
| V _{OH} | HIGH-level output voltage | I_{OH} = -4 mA; V_{VCC} = 4.5 V to 5.5 V | $V_{VCC}-0.4$ | - | - | V |
| V _{OL} | LOW-level output voltage | I_{OL} = 4 mA; V_{VCC} = 4.5 V to 5.5 V | - | - | 0.4 | V |
| I _{LOZ} | OFF-state output leakage current | $V_{CSB} = V_{VCC}; V_O = 0 V \text{ to } V_{VCC}$ | -5 | - | +5 | μA |
| Temperatu | ire protection | 1 | 1 | | | |
| ΔT_j | junction temperature variation | measurement provided via register 0x46h; $T_j = 130 \text{ °C}$ | -20 | - | +20 | °C |
| T _{sd(otp)} | overtemperature protection shutdown temperature | | 150 | 175 | 200 | °C |
| Vbat moni | toring | ! | 1 | | 1 | |
| ΔV_{BAT} | battery voltage accuracy | accuracy of V_{BAT} measurement | $-0.035 \times V_{BAT} - 0.3606$ | - | $+0.035 \times V_{BAT} + 0.3606$ | V |

[1] All parameters are guaranteed over the virtual junction temperature range by design. Factory testing uses correlated test conditions to cover the specified temperature and power supply voltage range.

12. Dynamic characteristics

Table 39. Dynamic characteristics

Min and Max values are specified for the following conditions: $V_{VIN} = 10 \text{ V}$ to 80 V, $V_{EN} = 4.5 \text{ V}$ to 5.5 V, $V_{VCC} = 4.5 \text{ V}$ to 5.5 V and $T_j = -40 \text{ °C}$ to +175 °C^[1]. All voltages are defined with respect to ground, positive currents flow into the IC. Typical values are given at $V_{VIN} = 40 \text{ V}$. $V_{EN} = 5 \text{ V}$, $V_{VCC} = 5 \text{ V}$ and $T_j = 25 \text{ °C}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---|---|--|-----|------|-----|------|
| f _{DCDC} | DC-to-DC converter frequency | | 120 | - | 700 | kHz |
| f _{(DCDC)acc} | DC-to-DC converter frequency accuracy | operating, trimmed | -5 | - | +5 | % |
| f _{osc} | oscillator frequency | internal oscillator, untrimmed | 130 | - | 250 | MHz |
| | | target frequency for trimmed operation | - | 180 | - | MHz |
| Serial perip | oheral interface timing; pins CSE | 3, SCLK, SDI and SDO | | | | |
| f _{clk(int)} /f _{SPI} | Internal clock frequency to SPI clock frequency ratio | ratio between internal clock and SPI clock | - | 20:1 | - | 1 |
| t _{cy(clk)} | clock cycle time | | 250 | - | - | ns |
| t _{SPILEAD} | SPI enable lead time | | 50 | | | ns |
| t _{SPILAG} | SPI enable lag time | | 50 | - | - | ns |
| t _{clk(H)} | clock HIGH time | | 125 | | | ns |
| t _{clk(L)} | clock LOW time | | 125 | - | - | ns |
| t _{su(D)} | data input set-up time | | 50 | | | ns |
| t _{h(D)} | data input hold time | | 50 | - | - | ns |
| t _{v(Q)} | data output valid time | pin SDO; C _L = 20 pF | - | | 130 | ns |
| t _{WH(S)} | chip select pulse width HIGH | | 250 | - | | ns |
| | | | | | | |

Table 39. Dynamic characteristics ...continued

Min and Max values are specified for the following conditions: $V_{VIN} = 10 \text{ V}$ to 80 V, $V_{EN} = 4.5 \text{ V}$ to 5.5 V, $V_{VCC} = 4.5 \text{ V}$ to 5.5 V and $T_j = -40 \text{ °C}$ to +175 °C[1]. All voltages are defined with respect to ground, positive currents flow into the IC. Typical values are given at $V_{VIN} = 40 \text{ V}$. $V_{EN} = 5 \text{ V}$, $V_{VCC} = 5 \text{ V}$ and $T_j = 25 \text{ °C}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---------------------------|------------------------------|--|-----|------|-----|------|
| Gate drive | r characteristics for pin G1 | | I | | | |
| t _{ch(G)} | gate charge time | 20 % to 80 %; V _{VGG} = 7.5 V; C _{gate} = 2000 pF | - | - | 30 | ns |
| t _{dch(G)} | gate discharge time | 80 % to 20 %; V _{VGG} = 7.5 V; C _{gate} = 2000 pF | - | - | 14 | ns |
| Regulated | voltage | | | | | |
| t _{startup} | start-up error time | of VGG; f _{osc} = 180 MHz | - | 2.5 | - | ms |
| t _{err(startup)} | error detection time | ction time for VGG during operation; f _{osc} = 180 MHz | | 31.5 | - | μs |
| t _{fltr(ov)} | output voltage filter time | for bit Vout1_ok and Vout2_ok; f _{osc} = 180 MHz | - | 31.5 | - | μs |

[1] All parameters are guaranteed over the virtual junction temperature range by design. Factory testing uses correlated test conditions to cover the specified temperature and power supply voltage range.



13. Application information

Figure 14 provides an example for the ASL1500SHN in a typical 2-phase Boost converter IC with 1 output voltage.



14. Test information

14.1 Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q100 Rev-H - *Failure mechanism-based stress test qualification for integrated circuits*, and is suitable for use in automotive applications.

15. Package outline



Fig 15. Package outline HVQFN32

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16. Revision history

Table 40. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes | | | |
|----------------|--|--------------------------------|---------------------|----------------------|--|--|--|
| ASL1500SHN v.4 | 20171026 | Product data sheet | - | ASL1500SHN v.3 | | | |
| Modifications: | <u>Section 8.7</u>: clarified exceeding of limiting values | | | | | | |
| | Formula for voltage conversion updated | | | | | | |
| | <u>Table 38</u>: values of output voltage accuracy updated | | | | | | |
| | <u>Table 38</u>: values of regulator voltage accuracy on pin VGG updated | | | | | | |
| | • <u>Table 39</u> : da | ata output valid time updated | | | | | |
| ASL1500SHN v.3 | 20160413 | Product data sheet | - | ASL1500SHN v.2 | | | |
| Modifications: | Minor corrections made to Figure 3 "State diagram" on page 6. | | | | | | |
| | • Text has been corrected and aligned with the ASLxxxxSHN series of data sheets. | | | | | | |
| ASL1500SHN v.2 | 20150925 | Product data sheet | - | ASL1500SHN v.1 | | | |
| Modifications: | Minor correct | ctions made to Figure 2, Figur | re 3 and Figure 14. | | | | |
| | Text has been | en corrected and aligned with | the ASLxxxxSHN set | ries of data sheets. | | | |
| | A number of symbols have been upgraded to NXP standards. | | | | | | |
| | Specification status upgraded to Product data sheet. | | | | | | |
| ASL1500SHN v.1 | 20150624 | Preliminary data sheet | - | - | | | |
| | | 1 | 1 | L | | | |

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|--------------------------------|--|---|--|--|
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- [2] The term 'short data sheet' is explained in section "Definitions"
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