Product data sheet

1. General description

The HEF4520B-Q100 is a dual 4-bit internally synchronous binary counter with two clock inputs (nCP0 and n $\overline{CP1}$), buffered outputs from all four bit positions (nQ0 to nQ3) and an asynchronous master reset input (nMR). The counter advances on either the LOW-to-HIGH transition of nCP0 if n $\overline{CP1}$ is HIGH or the HIGH-to-LOW transition of n $\overline{CP1}$ if nCP0 is LOW. Either nCP0 or n $\overline{CP1}$ may be used as the clock input to the counter and the other clock input may be used as a clock enable input. A HIGH on nMR resets the counter (nQ0 to nQ3 = LOW) independent of nCP0 and nCP1. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V_{DD} .

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
 - Specified from -40 °C to +85 °C
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
 - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2000 V
 - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1000 V

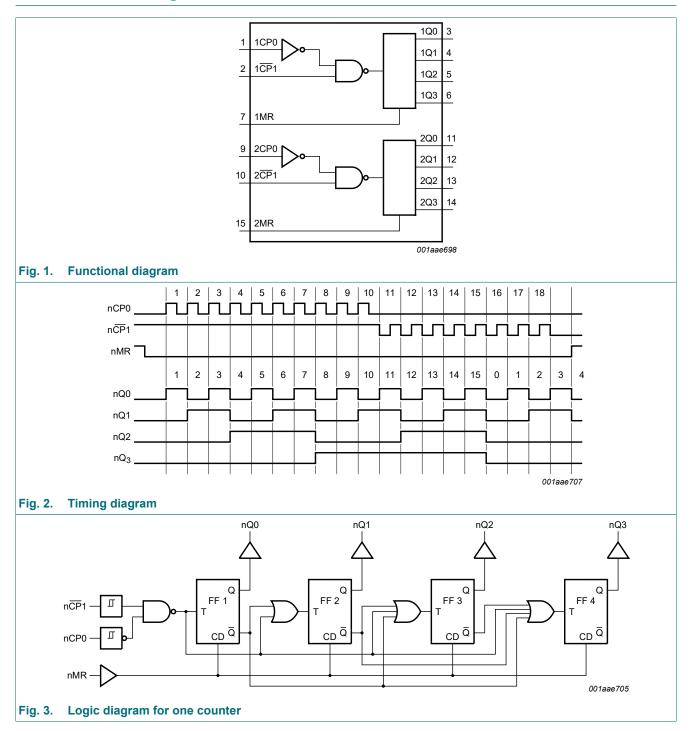
3. Ordering information

Table 1. Ordering information

Type number	Package						
	Temperature range	Name	Description	Version			
HEF4520BT-Q100	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1			

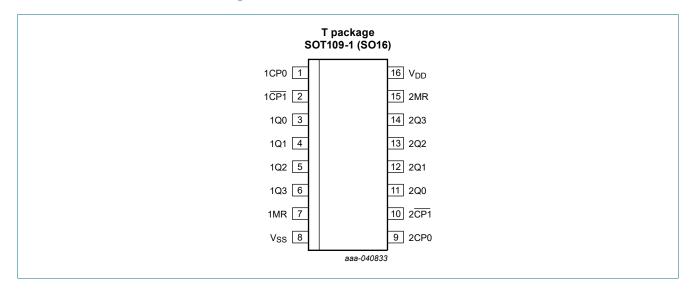


4. Functional diagram



5. Pinning information

5.1. Pinning



5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
1CP0, 2CP0	1, 9	clock input (LOW-to-HIGH triggered)
1CP1, 2CP1	2, 10	clock input (HIGH-to-LOW triggered)
1Q0, 1Q1, 1Q2, 1Q3	3, 4, 5, 6	output
1MR, 2MR	7, 15	master reset input
V _{SS}	8	ground supply voltage
2Q0, 2Q1, 2Q2, 2Q3	11, 12, 13, 14	output
V_{DD}	16	supply voltage

6. Functional description

Table 3. Function table

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care; \ \uparrow = positive-going \ transition; \ \downarrow = negative-going \ transition.$

nCP0	nCP1	nMR	Mode
↑	Н	L	counter advances
L	\downarrow	L	counter advances
↓	X	L	no change
X	↑	L	no change
↑	L	L	no change
Н	\downarrow	L	no change
Х	X	Н	nQ0 to nQ3 = LOW

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to $V_{\rm SS}$ = 0 V (ground).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	$V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature	per output	-65	+150	°C
T _{amb}	ambient temperature		-40	+85	°C
P _{tot}	total power dissipation	SO16 package	-	500	mW
Р	power dissipation		-	100	mW

8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{DD}	supply voltage		3	-	15	V
VI	input voltage		0	-	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	V _{DD} = 5 V	-	-	3.75	μs/V
		V _{DD} = 10 V	-	-	0.5	μs/V
		V _{DD} = 15 V	-	-	0.08	μs/V

9. Static characteristics

Table 6. Static characteristics

 V_{SS} = 0 V; V_I = V_{SS} or V_{DD} unless otherwise specified.

Symbol Parameter		Conditions	V_{DD}	T _{amb} =	-40 °C	T _{amb} =	25 °C	T _{amb} = 85 °C		Unit
				Min	Max	Min	Max	Min	Max	
V _{IH}	HIGH-level input	I _O < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
	voltage		10 V	7.0	-	7.0	-	7.0	-	V
		15 V	11.0	-	11.0	-	11.0	-	V	
V_{IL}	LOW-level input	I _O < 1 μA	5 V	_	1.5	-	1.5	-	1.5	V
	voltage		10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level output	I _O < 1 μA;	5 V	4.95	-	4.95	-	4.95	-	V
	voltage	$V_I = V_{SS}$ or V_{DD}	10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V _{OL}	LOW-level output	I _O < 1 μΑ;	5 V	-	0.05	-	0.05	-	0.05	V
	voltage	$V_I = V_{SS}$ or V_{DD}	10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	-40 °C	T _{amb} =	= 25 °C	T _{amb} =	85 °C	Unit
				Min	Max	Min	Max	Min	Max	
I _{OH}	HIGH-level output	V _O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
	current	V _O = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V _O = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I _{OL}	LOW-level output	V _O = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
	current	V _O = 0.5 V	10 V	1.3	-	1.1	-	0.9	-	mA
		V _O = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
I _I	input leakage current	V _{DD} = 15 V	15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
I _{DD}	supply current	I _O = 0 A;	5 V	-	20	-	20	-	150	μΑ
		$V_I = V_{SS}$ or V_{DD}	10 V	-	40	-	40	-	300	μΑ
			15 V	-	80	-	80	-	600	μΑ
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

10. Dynamic characteristics

Table 7. Dynamic characteristics

 V_{SS} = 0 V; T_{amb} = 25 °C; unless otherwise specified. For test circuit see Fig. 5.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula [1]	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	nCP0, nCP1 to nQn;	5 V	83 ns + (0.55 ns/pF)C _L	-	110	220	ns
	propagation delay	see Fig. 4	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		nMR to nQn; see Fig. 4	5 V	48 ns + (0.55 ns/pF)C _L	-	75	150	ns
			10 V	24 ns + (0.23 ns/pF)C _L	_	35	70	ns
			15 V	17 ns + (0.16 ns/pF)C _L	_	25	50	ns
t _{PLH}	LOW to HIGH	nCP0, nCP1 to nQn;	5 V	83 ns + (0.55 ns/pF)C _L	-	110	220	ns
	propagation delay	see Fig. 4	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
t _t	transition time	nQn; see Fig. 4	5 V	10 ns + (1.00 ns/pF)C _L	_	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	_	20	40	ns
t _W	pulse width	nCP0 input LOW;	5 V		60	30	-	ns
		minimum width; see Fig. 4	10 V		30	15	-	ns
		300 <u>1 lg. 4</u>	15 V		20	10	-	ns
		nCP1 input HIGH;	5 V		60	30	-	ns
		minimum width; see Fig. 4	10 V		30	15	-	ns
		300 <u>1 lg. 4</u>	15 V		20	10	-	ns
		nMR input HIGH; minimum width; see Fig. 4	5 V		30	15	-	ns
			10 V		20	10	-	ns
		<u> 1 іу. т</u>	15 V		16	8	-	ns

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula [1]	Min	Тур	Max	Unit
t _{su}	set-up time	nCP0 to nCP1;	5 V		50	25	-	ns
		see Fig. 4	10 V		30	15	-	ns
			15 V		20	10	-	ns
	nCP1 to nCP0; see Fig. 4	The state of the s	5 V		50	25	-	ns
		10 V		30	15	-	ns	
			15 V		20	10	-	ns
t _{rec}	recovery time	ime see <u>Fig. 4</u>	5 V		50	25	-	ns
			10 V		30	15	-	ns
			15 V		20	10	-	ns
f _{max}	maximum frequency		5 V		8	16	-	MHz
			10 V		15	30	-	MHz
			15 V		20	40	-	MHz

^[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

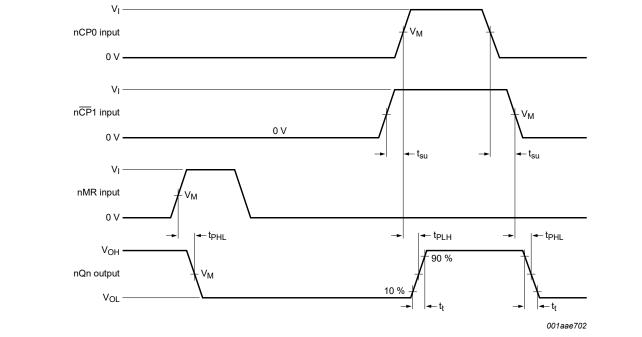
Table 8. Dynamic power dissipation P_D

 P_D can be calculated from the formulas shown. V_{SS} = 0 V; t_r = t_f \leq 20 ns; T_{amb} = 25 °C.

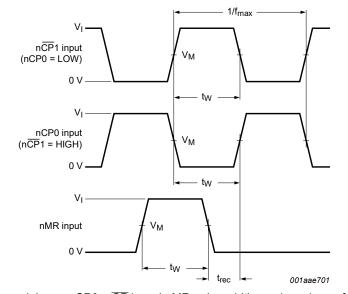
Symbol	Parameter	V_{DD}	Typical formula for P _D (μW)	Where:
P_D	dynamic power	5 V	. (0 2, 55	f _i = input frequency in MHz,
	dissipation	dissipation $P_D = 3800 \times f_i + \Sigma (f_0 \times C_L) \times V_{DD}^2$		f _o = output frequency in MHz, C _L = output load capacitance in pF,
		15 V	$P_D = 10200 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$	V_{DD} = supply voltage in V, $\Sigma(f_0 \times C_L)$ = sum of the outputs.

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10.1. Waveforms and test circuit



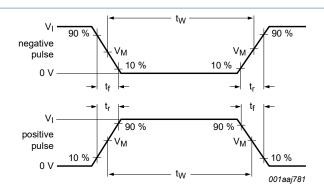
a. nCP0 and nCP1 set-up times, propagation delays and output transition times



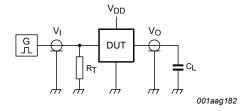
b. nMR recovery time, minimum nCP0, nCP1, and nMR pulse widths and maximum frequency Measurement points are given in Table 9.

The logic levels V_{OH} and V_{OL} are typical output voltage levels that occur with the output load.

Fig. 4. Waveforms showing measurements for switching times



a. Input waveforms



b.Test circuit

Test data is given in Table 9.

Definitions for test circuit:

C_L = Load capacitance including jig and probe capacitance;

 R_T = Termination resistance should be equal to output impedance Z_o of the pulse generator.

Fig. 5. Test circuit for measuring switching times

Table 9. Measurement points and test data

Supply voltage	Input	nput			
V_{DD}	VI	V _M	t _r , t _f	C _L	
5 V to 15 V	V_{DD}	0.5 × V _I	≤ 20 ns	50 pF	

11. Package outline

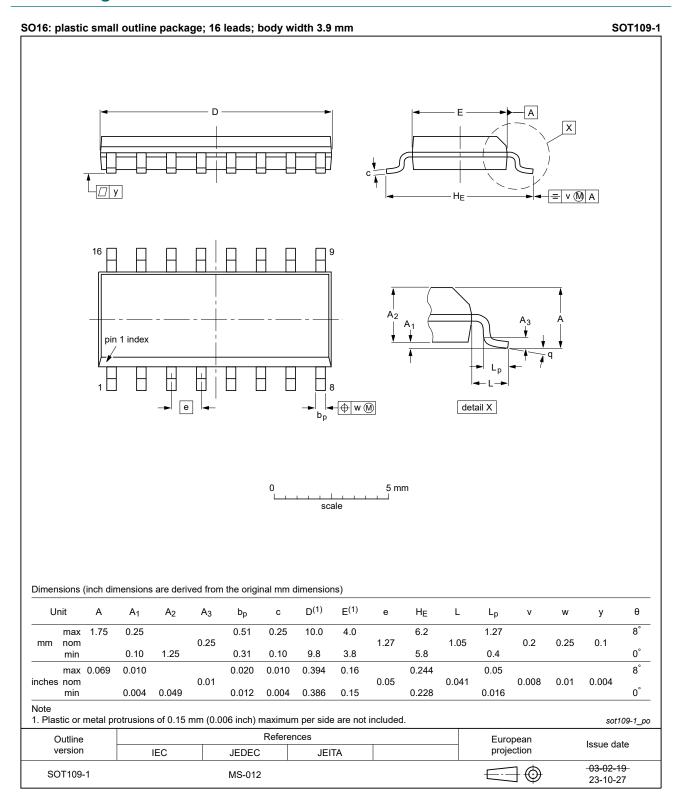


Fig. 6. Package outline SOT109-1 (SO16)

Product data sheet

12. Abbreviations

Table 10. Abbreviations

and terrandictions					
Acronym	Description				
ANSI	American National Standards Institute				
CDM	Charged Device Model				
DUT Device Under Test					
ESD	ElectroStatic Discharge				
ESDA	ElectroStatic Discharge Association				
HBM Human Body Model					
JEDEC Joint Electron Device Engineering Council					

13. Revision history

Table 11. Revision history

Table 11. Nevision history						
Document ID	Release date	Data sheet status	Change notice	Supersedes		
HEF4520B_Q100 v.3	20240819	Product data sheet	-	HEF4520B_Q100 v.2		
Modifications:	 <u>Section 2</u>: ESD specification updated according to the latest JEDEC standard. <u>Fig. 6</u>: Aligned SO package outline drawing to JEDEC MS-012 Revision history corrected. 					
HEF4520B_Q100 v.2	20220301	Product specification	-	HEF4520B_Q100 v.1		
Modifications	Section 1, Section 2, and Section 12 updated.					
HEF4520B_Q100 v.1	20170314	Product specification	-	-		

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14. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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