

Data sheet for SINAMICS G120X

Article No.: 6SL3220-1YC22-0UB0

Client order no. : Order no. : Offer no. : Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	200 240 V +10 %	-20 %
Line frequency	47 63 Hz	
Rated voltage	200V IEC	240V NEC
Rated current (LO)	20.80 A	20.80 A
Rated current (HO)	16.30 A	16.30 A
Output		
Number of phases	3 AC	
Rated voltage	200V IEC	240V NEC 1)
Rated power (LO)	5.50 kW	7.50 hp
Rated power (HO)	4.00 kW	5.00 hp
Rated current (LO)	22.00 A	22.00 A
Rated current (HO)	17.50 A	17.50 A
Rated current (IN)	22.80 A	
Max. output current	29.70 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	
Overload capability		

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

Communication

 $150\%\,x$ base load current IH for 60 s within a 600 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos\phi$	0.96	
Efficiency η	0.96	
Sound pressure level (1m)	67 dB	
Power loss 3)	0.269 kW	
Filter class (integrated)	Unfiltered	
EMC category (with accessories)	without	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	

Communication

USS, Modbus RTU, BACnet MS/TP



Item no. : Consignment no. : Project :

Inputs / outputs		
Standard digital inputs		
Number	6	
Switching level: 0 → 1	11 V	
Switching level: $1 \rightarrow 0$	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number	1	
Digital outputs		
Number as relay changeover contact	2	
Output (resistive load)	DC 30 V, 5.0 A	
Number as transistor	0	
Analog / digital inputs		
Number	2 (Differential input)	
Resolution	10 bit	
Switching threshold as digital input		
0 → 1	4 V	
1 → 0	1.6 V	
Analog outputs		
Number	1 (Non-isolated output)	

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5\,^{\circ}\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



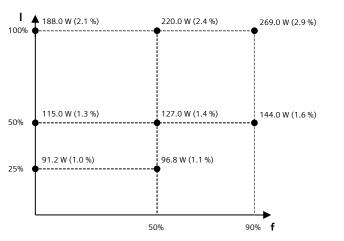
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Ambient	conditions
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.018 m ³ /s (0.653 ft ³ /s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-20 45 °C (-4 113 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-25 55 °C (-13 131 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Conn	ections
Signal cable	
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)
Line side	
Version	screw-type terminal
Conductor cross-section	1.50 16.00 mm ² (AWG 16 AWG 6)
Motor end	
Version	Screw-type terminals
Conductor cross-section	1.50 16.00 mm ² (AWG 16 AWG 6)
DC link (for braking resistor)	
PE connection	On housing with M4 screw
Max. motor cable length	
Shielded	150 m (492.13 ft)
Unshielded	300 m (984.25 ft)

Mechanical data		
Degree of protection	IP20 / UL open type	
Frame size	FSC	
Net weight	7.1 kg (15.65 lb)	
Dimensions		
Width	140 mm (5.51 in)	
Height	295 mm (11.61 in)	
Depth	218 mm (8.58 in)	
Standards		
Compliance with standards	UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH	
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

 $^{^{1)}}$ The output current and HP ratings are valid for the voltage range 220V-240V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.