Part Number

Step Angle

Frame Size

Current

Holding Torque

Number of Leads

Resistance Rotor Inertia

Connection

Body Length (Dim. A)



WO-4118S-04S

1.34 in (34 mm)

0.67 Amps/Phase

42 oz-in (0.3 Nm) 9.9 Ohms/Phase

0.18 oz-in²

4

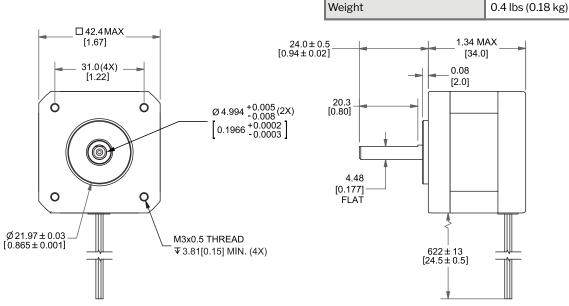
Serial

1.8°

NEMA 17



DIMENSIONS



PERFORMANCE CURVE

4118S-04S 24VDC, 0.67 Amps/Phase, Bipolar, 1/2 Stepping 40 0.30 35 0.25 30 0.20 25 20 0.15 15 0.10 10 0.05 1000 2000 2500 3000 3500 4000 Speed (pps) 10

Speed (rps)

OPERATING SPECIFICATIONS

Radial Play	0.001" max @ 1 lbs load
End Play	0.003" max @ 2 lbs load
Shaft Run Out	0.002" TIR
Concentricity of Mounting Pilot to Shaft	0.003" TIR
Perpendicularity of Shaft to Mounting Face	0.003" TIR
Max Axial Load	6 lbs
Maximum Case Temperature	80 C
Ambient Temperature	-20° to 50° C
Storage Temperature	-20° to 100° C
Humidity Range	85% or less, non-condensing
Magnet Wire Insulation	Class B 130° C
Insulation Resistance	100MΩ at 500 VDC
Dielectric Strength	500 VAC for 1 minute

WIRING TABLE

COLOR	FUNCTION
Red	A+ Phase
Blue	A- Phase
Green	B + Phase
Black	B- Phase

OPERATION & USAGE TIPS



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe brake.



Do not hold motor by lead wires.



Do not exceed the rated current; this will burn the motor

 ${\sf FAILURE\ TO\ COMPLY\ WITH\ THESE\ RECOMMENDATIONS\ WILL\ VOID\ ALL\ WARRANTY\ TERMS}$

RECOMMENDED



Microstepping Driver



Single Axis Controller + Driver **R256-RO**

Motion Control, Solved.

MOTOR ENGINEERING & MANUFACTURING







Small Batch to OEM Volume Production

