$Email: sales@linengineering.com \mid techsupport@linengineering.com$ 

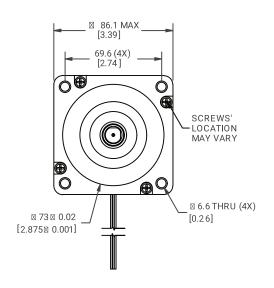
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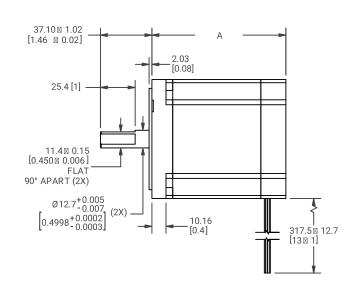


## **MOTOR SPECIFICATIONS**

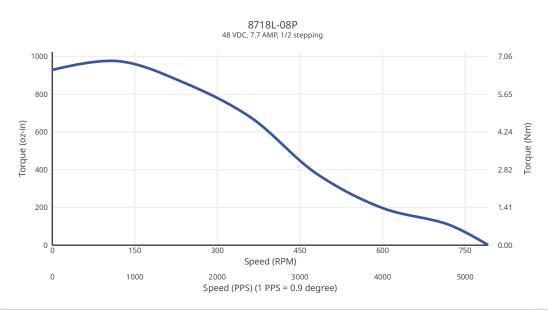
Part Number	WO-8718L-08P
Step Angle	1.8°
Frame Size	3.39 in (86 mm)
"A" Body Length	5.0 in (127.0 mm)
Current (Amps/Phase)	7.7
Holding Torque	1288.67 oz-in (9.1 N-m)
Resistance (Ohms/Phase)	0.3
Rotor Inertia	21.9 oz-in² (4005 g-cm²)
Number of Leads	4
Connection	Bipolar
Weight	8.45 lbs (3.83 kg)

# **DIMENSIONS**





## **PERFORMANCE CURVE**



#### **OPERATING SPECIFICATIONS**

Radial Play	0.001 in @ 1.00 lbs (0.03 mm @ 0.45 kg)
End Play	0.003 in @ 3.00 lbs (0.08 mm @ 1.36 kg)
Shaft Run Out	0.05 TIR (0.002 TIR)
Concentricity of Mounting Pilot to Shaft	0.08 TIR (0.003 TIR)
Perpendicularity of Mounting Pilot to Face	0.08 TIR (0.003 TIR)
Max Radial Load at Dimension "K" from mounting face	39.00 lbs (17.69 kg)
Dimension"K"	0.90 in (22.86 mm)
Max Axial Load	25.00 lbs (11.34 kg)
Maximum Case Temperature	176°F (80°C) Maximum
Ambient Temperature	-4 to 122°F (-20°C to 50°C)
Storage Temperature	-4 to 212°F (-20°C to 100°C)
Humidity Range (%)	85% or less, non-condensing
Magnet Wire Insulation	Class B 266°F (130°C)
Insulation Resistance	100M Ohm at 500 VCD
Dielectric Strength	900 VCD for 1 min.

#### **WIRING TABLE**

COLOR	FUNCTION
Red	A+ Phase
Blue	A- Phase
Green	B + Phase
Black	B- Phase

### **OPERATION & USAGE TIPS**



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



Do not disconnect motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe brake.



Do not hold motor by lead wires.



Do not exceed the rated current; this wil burn the motor.

FAILURE TO COMPLY WITH THESE RECOMMENDATIONS WILL VOID ALL WARRANTY TERMS

# Motion Control, Solved.

**MOTOR ENGINEERING & MANUFACTURING** 







