

Data sheet for SINAMICS G120X

Article No.: 6SL3220-1YH48-0UB0

Client order no. : Order no.: Offer no. : Remarks:

Rated data		
Input		
Number of phases	3 AC	
Line voltage	500 690 V +10 %	-20 %
Line frequency	47 63 Hz	
Rated voltage	690V IEC	600V NEC
Rated current (LO)	138.00 A	138.00 A
Rated current (HO)	131.60 A	131.60 A
Output		
Number of phases	3 AC	
Rated voltage	690V IEC	600V NEC 1)
Rated power (LO)	132.00 kW	150.00 hp
Rated power (HO)	110.00 kW	125.00 hp
Rated current (LO)	144.00 A	144.00 A
Rated current (HO)	125.00 A	125.00 A
Rated current (IN)	148.00 A	
Max. output current	195.00 A	
Pulse frequency	2 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	
Overload capability		

Overload	capabi	litv

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor $\cos\phi$	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss 3)	2.670 kW	
Filter class (integrated)	Unfiltered	
EMC category (with accessories)	without	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	

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Commu	nica	ition

Communication

USS, Modbus RTU, BACnet MS/TP



Item no. : Consignment no. : Project :

Inputs /	outputs
Standard digital inputs	
Number	6
Switching level: $0 \rightarrow 1$	11 V
Switching level: $1 \rightarrow 0$	5 V
Max. inrush current	15 mA
Fail-safe digital inputs	
Number	1
Digital outputs	
Number as relay changeover contact	2
Output (resistive load)	DC 30 V, 5.0 A
Number as transistor	0
Analog / digital inputs	
Number	2 (Differential input)
Resolution	10 bit
Switching threshold as digital input	
0 → 1	4 V

PTC/ KTY interface

Analog outputs Number

 $1 \rightarrow 0$

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V

1 (Non-isolated output)

Closed-loop control techniques	
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



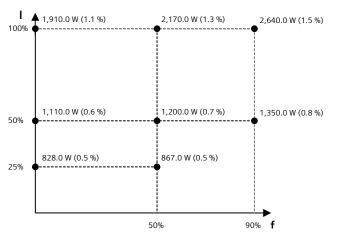
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Ambient conditions	
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.153 m ³ /s (5.403 ft ³ /s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-20 45 °C (-4 113 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-25 55 °C (-13 131 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Co	onnections
Signal cable	
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)
Line side	
Version	M10 screw
Conductor cross-section	35.00 2 x 120.00 mm ² (AWG 1 AWG 2 x 4/0)
Motor end	
Version	M10 screw
Conductor cross-section	35.00 2 x 120.00 mm ² (AWG 1 AWG 2 x 4/0)
DC link (for braking resistor)	
PE connection	M10 screw
Max. motor cable length	
Shielded	300 m (984.25 ft)
Unshielded	450 m (1,476.38 ft)

Mecha	nical data
Degree of protection	IP20 / UL open type
Frame size	FSF
Net weight	66.5 kg (146.61 lb)
Dimensions	
Width	305 mm (12.01 in)
Height	709 mm (27.91 in)
Depth	369 mm (14.53 in)
Sta	ndards
Compliance with standards	UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾ The output current and HP ratings are valid for the voltage range 550V-600V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.