
Si47xx PROGRAMMING GUIDE

1. Introduction

This document provides an overview of the programming requirements for the Si4704/05/06/3x AM/FM/SW/LW receiver. The hardware control interface and software commands are detailed along with several examples of the required steps to configure the device for various modes of operation.

2. Overview

This family of products is programmed using commands and responses. To perform an action, the system controller writes a command byte and associated arguments, causing the device to execute the given command. The device will, in turn, provide a response depending on the type of command that was sent. Section "4. Commands and Responses" on page 5 and Section "5. Commands and Properties" on page 6 describe the procedures for using commands and responses and provide complete lists of commands, properties, and responses.

The device has a slave control interface that allows the system controller to send commands to and receive responses from the device using one of three serial protocols (or bus modes): 2-wire mode (I²C and SMBUS compatible), 3-wire mode, or SPI mode.

Section "6. Control Interface" on page 123 describes the control interface in detail.

Section "7. Powerup" on page 131 describes options for the sequencing of VDD and VIO power supplies, selection of the desired bus mode, provision of the reference clock, RCLK, and sending of the POWER_UP command.

Section "8. Powerdown" on page 138 describes sending the POWER_DOWN command and removing VDD and VIO power supplies as necessary.

Section "9. Digital Audio Interface" on page 139 describes the digital audio format supported and how to operate the device in digital mode.

Section "10. Timing" on page 142 describes the CTS (Clear to Send) timing indicating when the command has been accepted and in most cases completed execution, and the STC (Seek/Tune Complete) timing indicating when the Seek/Tune commands have completed execution.

Section "11. Programming Examples" on page 146 provides flowcharts and step-by-step procedures for programming the device.

Table 1. Product Family Function

| Part Number | General Description | FM Receiver | AM Receiver | SW/LW Receiver | RDS | High Performance RDS | RPS | Digital Input | Digital Output | Embedded FM antenna | AEC-Q100 Qualified | Package Size (mm) |
|---|-------------------------------|-------------|-------------|----------------|-----|----------------------|-----|---------------|--------------------|---------------------|--------------------|-------------------|
| Si4702 | FM Receiver | ✓ | | | | | | | | | | 3x3 |
| Si4703 | FM Receiver with RDS | ✓ | | | ✓ | | | | | | | 3x3 |
| Si4704 | FM Receiver | ✓ | | | | | | | Not e ¹ | ✓ | | 3x3 |
| Si4705 | FM Receiver with RDS | ✓ | | | ✓ | Note ₂ | | | ✓ | ✓ | | 3x3 |
| Si4706 ³ | High Performance RDS Receiver | ✓ | | | ✓ | ✓ | | | ✓ | ✓ | | 3x3 |
| Si4708 | FM Receiver | ✓ | | | | | | | | | | 2.5x2.5 |
| Si4709 | FM Receiver with RDS | ✓ | | | ✓ | | | | | | | 2.5x2.5 |
| Si4730 | AM/FM Receiver | ✓ | ✓ | | | | | | | | | 3x3 |
| Si4731 | AM/FM Receiver with RDS | ✓ | ✓ | | ✓ | Note ₂ | | | ✓ | | | 3x3 |
| Si4732 ⁴ | AM/SW/LW/FM Receiver with RDS | ✓ | ✓ | ✓ | ✓ | ✓ | | | ✓ | | | SOIC16 |
| Si4734 | AM/SW/LW/FM Receiver | ✓ | ✓ | ✓ | | | | | | | | 3x3 |
| Si4735 | AM/SW/LW/FM Receiver with RDS | ✓ | ✓ | ✓ | ✓ | Note ₂ | | | ✓ | | | 3x3 |
| Notes: 1. Digital Output is available in Si4704-D60 and later. 2. High Performance RDS is available in Si4705/31/35 and later, Si4732. 3. Si4706 is covered under NDA. 4. Si4732-A10 has the same firmware FMRX component and AM_SW_LW RX component as that of Si4735-D60, so Si4732-A10 is considered as the most recent revision as D60, and the Si4735-D60 related descriptions in Appendix A and Appendix B also apply to Si4732-A10 if not specified. | | | | | | | | | | | | |

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3. Terminology

- $\overline{\text{SEN}}$ —Serial enable pin, active low; used as device select in 3-wire and SPI operation and address selection in 2-wire operation.
- SDIO—Serial data in/data out pin.
- SCLK—Serial clock pin.
- $\overline{\text{RST}}$ or RSTb—Reset pin, active low
- RCLK—External reference clock
- GPO—General purpose output
- CTS—Clear to send
- STC—Seek/Tune Complete
- NVM—Non-volatile internal device memory
- Device—Refers to the AM/FM/SW/LW Receiver
- System Controller—Refers to the system microcontroller
- CMD—Command byte
- COMMANDn—Command register (16-bit) in 3-Wire mode (n = 1 to 4)
- ARGn—Argument byte (n = 1 to 7)
- STATUS—Status byte
- RESPn—Response byte (n = 1 to 15)
- RESPONSEn—Response register (16-bit) in 3-Wire mode (n = 1 to 8)

4. Commands and Responses

Commands control actions, such as power up, power down, or tune to a frequency, and are one byte in size. Arguments are specific to a given command and are used to modify the command. For example, after the FM_TUNE_FREQ command, arguments are required to set the tune frequency. Arguments are one byte in size, and each command may require up to seven arguments. Responses provide the system controller status information and are returned after a command and its associated arguments are issued. All commands return a one byte status indicating interrupt state and clear-to-send the next command. Commands may return up to 15 additional response bytes. A complete list of commands is available in “5. Commands and Properties”.

Table 2 shows an example of tuning to a frequency using the FM_TUNE_FREQ command. This command requires that a command and three arguments be sent and returns one status byte. The table is broken into three columns. The first column lists the action taking place: command (CMD), argument (ARG), status (STATUS), or response (RESP). The second column lists the data byte or bytes in hexadecimal that are being sent or received. An arrow preceding the data indicates data being sent from the device to the system controller. The third column describes the action.

Table 2. Using the FM_TUNE_FREQ Command

| Action | Data | Description |
|--------|-------|--------------------------------------|
| CMD | 0x20 | FM_TUNE_FREQ |
| ARG1 | 0x00 | |
| ARG2 | 0x27 | Set frequency to 101.1 MHz |
| ARG3 | 0x7E | |
| ARG4 | 0x00 | Set antenna tuning capacitor to auto |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

Properties are special command arguments used to modify the default device operation and are generally configured immediately after power-up. An example of a property is REFCLK_FREQ. A complete list of properties is available in Section “5. Commands and Properties”.

Table 3 shows an example of setting the REFCLK frequency using the REFCLK_FREQ property by sending the SET_PROPERTY command and five argument bytes. ARG1 of the SET_PROPERTY command is always 0x00. ARG2 and ARG3 are used to select the property number, PROP (0x0201 in this example), and ARG4 and ARG5 are used to set the property value, PROPD (0x8000 or 32768 Hz in the example).

Table 3. Using the SET_PROPERTY Command

| Action | Data | Description |
|--------------|-------|-----------------------------------|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x02 | REFCLK_FREQ |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x80 | 32768 Hz |
| ARG5 (PROPD) | 0x00 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

The implementation of the command and response procedures in the system controller differs for each of the three bus modes. Section “6. Control Interface” on page 123 details the required bit transactions on the control bus for each of the bus modes.

5. Commands and Properties

There are two different components for these product families:

1. FM Receiver component
2. AM/SW/LW component

The following two subsections list all the commands and properties used by each of the component.

5.1. Commands and Properties for the FM/RDS Receiver (Si4704/05/06/3x)

Tables 4 and 5 summarize the commands and properties for the FM/RDS Receiver component applicable to Si4704/05/06/3x.

Table 4. FM/RDS Receiver Command Summary

| Cmd | Name | Description | Available In |
|--|-----------------|---|----------------------------|
| 0x01 | POWER_UP | Power up device and mode selection. | All |
| 0x10 | GET_REV | Returns revision information on the device. | All |
| 0x11 | POWER_DOWN | Power down device. | All |
| 0x12 | SET_PROPERTY | Sets the value of a property. | All |
| 0x13 | GET_PROPERTY | Retrieves a property's value. | All |
| 0x14 | GET_INT_STATUS | Reads interrupt status bits. | All |
| 0x15 | PATCH_ARGS* | Reserved command used for patch file downloads. | All |
| 0x16 | PATCH_DATA* | Reserved command used for patch file downloads. | All |
| 0x20 | FM_TUNE_FREQ | Selects the FM tuning frequency. | All |
| 0x21 | FM_SEEK_START | Begins searching for a valid frequency. | All |
| 0x22 | FM_TUNE_STATUS | Queries the status of previous FM_TUNE_FREQ or FM_SEEK_START command. | All |
| 0x23 | FM_RSQ_STATUS | Queries the status of the Received Signal Quality (RSQ) of the current channel. | All |
| 0x24 | FM_RDS_STATUS | Returns RDS information for current channel and reads an entry from RDS FIFO. | Si4705/06, Si4731/32/35 |
| 0x27 | FM_AGC_STATUS | Queries the current AGC settings | All |
| 0x28 | FM_AGC_OVERRIDE | Override AGC setting by disabling and forcing it to a fixed value | All |
| 0x80 | GPIO_CTL | Configures GPO1, 2, and 3 as output or Hi-Z. | All |
| 0x81 | GPIO_SET | Sets GPO1, 2, and 3 output level (low or high). | All |
| *Note: Commands PATCH_ARGS and PATCH_DATA are only used to patch firmware. For information on applying a patch file, see "7.2. Powerup from a Component Patch" on page 132. | | | |

Table 5. FM/RDS Receiver Property Summary

| Prop | Name | Description | Default | Available In |
|--------|----------------------------|--|---------|---|
| 0x0001 | GPO_IEN | Enables interrupt sources. | 0x0000 | All |
| 0x0102 | DIGITAL_OUTPUT_FORMAT | Configure digital audio outputs. | 0x0000 | Si4704-D60 and later, Si4705/06, Si4731/32/35, Si4730/34-D60 and later |
| 0x0104 | DIGITAL_OUTPUT_SAMPLE_RATE | Configure digital audio output sample rate. | 0x0000 | Si4704-D60 and later, Si4705/06, Si4731/32/35, Si4730/34-D60 and later |
| 0x0201 | REFCLK_FREQ | Sets frequency of reference clock in Hz. The range is 31130 to 34406 Hz, or 0 to disable the AFC. Default is 32768 Hz. | 0x8000 | All |
| 0x0202 | REFCLK_PRESCALE | Sets the prescaler value for RCLK input. | 0x0001 | All |
| 0x1100 | FM_DEEMPHASIS | Sets deemphasis time constant. Default is 75 μ s. | 0x0002 | All |
| 0x1102 | FM_CHANNEL_FILTER | Selects bandwidth of channel filter applied at the demodulation stage. | 0x0001 | Si4706 Si4705/31/35-D50, and later, Si4732 |
| | | | 0x0000 | Si4704/30/34-D50 and later |
| 0x1105 | FM_BLEND_STEREO_THRESHOLD | Selects bandwidth of channel filter applied at the demodulation stage. | 0x0031 | Si470x |
| 0x1106 | FM_BLEND_MONO_THRESHOLD | Sets RSSI threshold for mono blend (Full mono below threshold, blend above threshold). To force stereo set this to 0. To force mono set this to 127. Default value is 30 dB μ V. | 0x001E | Si470x |
| 0x1107 | FM_ANTENNA_INPUT | Selects the antenna type and the pin to which it is connected. | 0x0000 | Si4704/05/06 |
| 0x1108 | FM_MAX_TUNE_ERROR | Sets the maximum freq error allowed before setting the AFC rail (AFCRL) indicator. Default value is 20 kHz. | 0x001E | All |
| | | | 0x0014 | All others |
| 0x1200 | FM_RSQ_INT_SOURCE | Configures interrupt related to Received Signal Quality metrics. | 0x0000 | All |

Table 5. FM/RDS Receiver Property Summary (Continued)

| Prop | Name | Description | Default | Available In |
|--------|-------------------------------|---|---------|--|
| 0x1201 | FM_RSQ_SNR_HI_THRESHOLD | Sets high threshold for SNR interrupt. | 0x007F | All |
| 0x1202 | FM_RSQ_SNR_LO_THRESHOLD | Sets low threshold for SNR interrupt. | 0x0000 | All |
| 0x1203 | FM_RSQ_RSSI_HI_THRESHOLD | Sets high threshold for RSSI interrupt. | 0x007F | All |
| 0x1204 | FM_RSQ_RSSI_LO_THRESHOLD | Sets low threshold for RSSI interrupt. | 0x0000 | All |
| 0x1205 | FM_RSQ_MULTIPATH_HI_THRESHOLD | Sets high threshold for multipath interrupt. | 0x007F | Si4706-D50, Si4704/05/30/31/34/35-D50, and later, Si4732 |
| 0x1206 | FM_RSQ_MULTIPATH_LO_THRESHOLD | Sets low threshold for multipath interrupt. | 0x0000 | Si4706-D50, Si4704/05/30/31/34/35-D50, and later, Si4732 |
| 0x1207 | FM_RSQ_BLEND_THRESHOLD | Sets the blend threshold for blend interrupt when boundary is crossed. | 0x0081 | All |
| 0x1300 | FM_SOFT_MUTE_RATE | Sets the attack and decay rates when entering and leaving soft mute. | 0x0040 | Si4706 |
| 0x1301 | FM_SOFT_MUTE_SLOPE | Configures attenuation slope during soft mute in dB attenuation per dB SNR below the soft mute SNR threshold. Default value is 2. | 0x0002 | Si4704/05/06/3x-D50 and later, Si4732 |
| 0x1302 | FM_SOFT_MUTE_MAX_ATTENUATION | Sets maximum attenuation during soft mute (dB). Set to 0 to disable soft mute. Default is 16 dB. | 0x0010 | All |
| 0x1303 | FM_SOFT_MUTE_SNR_THRESHOLD | Sets SNR threshold to engage soft mute. Default is 4 dB. | 0x0004 | All |
| 0x1304 | FM_SOFT_MUTE_RELEASE_RATE | Sets soft mute release rate. Smaller values provide slower release, and larger values provide faster release. The default is 8192 (approximately 8000 dB/s) | 0x2000 | Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732 |

Table 5. FM/RDS Receiver Property Summary (Continued)

| Prop | Name | Description | Default | Available In |
|--------|--------------------------------|---|---------|---|
| 0x1305 | FM_SOFT_MUTE_ATTACK_RATE | Sets soft mute attack rate. Smaller values provide slower attack, and larger values provide faster attack. The default is 8192 (approximately 8000 dB/s) | 0x2000 | Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732 |
| 0x1400 | FM_SEEK_BAND_BOTTOM | Sets the bottom of the FM band for seek. Default is 8750 (87.5 MHz). | 0x222E | All |
| 0x1401 | FM_SEEK_BAND_TOP | Sets the top of the FM band for seek. Default is 10790 (107.9 MHz). | 0x2A26 | All |
| 0x1402 | FM_SEEK_FREQ_SPACING | Selects frequency spacing for FM seek. Default value is 10 (100 kHz). | 0x000A | All |
| 0x1403 | FM_SEEK_TUNE_SNR_THRESHOLD | Sets the SNR threshold for a valid FM Seek/Tune. Default value is 3 dB. | 0x0003 | All |
| 0x1404 | FM_SEEK_TUNE_RSSI_THRESHOLD | Sets the RSSI threshold for a valid FM Seek/Tune. Default value is 20 dB μ V. | 0x0014 | All |
| 0x1500 | FM_RDS_INT_SOURCE | Configures RDS interrupt behavior. | 0x0000 | Si4705/06, Si431/32/35 |
| 0x1501 | FM_RDS_INT_FIFO_COUNT | Sets the minimum number of RDS groups stored in the receive FIFO required before RDSRECV is set. | 0x0000 | Si4705/06, Si431/32/35 |
| 0x1502 | FM_RDS_CONFIG | Configures RDS setting. | 0x0000 | Si4705/06, Si431/32/35 |
| 0x1503 | FM_RDS_CONFIDENCE | Sets the confidence level threshold for each RDS block. | 0x1111 | Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732 |
| 0x1800 | FM_BLEND_RSSI_STEREO_THRESHOLD | Sets RSSI threshold for stereo blend. (Full stereo above threshold, blend below threshold.) To force stereo, set this to 0. To force mono, set this to 127. Default value is 49 dB μ V. | 0x0031 | Si4706-D50, Si4705/31/35-D50 and later, Si4732 |

Table 5. FM/RDS Receiver Property Summary (Continued)

| Prop | Name | Description | Default | Available In |
|--------|-------------------------------|--|---------|--|
| 0x1801 | FM_BLEND_RSSI_MONO_THRESHOLD | Sets RSSI threshold for mono blend (Full mono below threshold, blend above threshold). To force stereo, set this to 0. To force mono, set this to 127. Default value is 30 dB μ V. | 0x001E | Si4706-D50, Si4705/31/35 -D50 and later, Si4732 |
| 0x1802 | FM_BLEND_RSSI_ATTACK_RATE | Sets the stereo to mono attack rate for RSSI based blend. Smaller values provide slower attack and larger values provide faster attack. The default is 4000 (approximately 16 ms). | 0x0FA0 | Si4706-D50, Si4705/31/35 -D50 and later, Si4732 |
| 0x1803 | FM_BLEND_RSSI_RELEASE_RATE | Sets the mono to stereo release rate for RSSI based blend. Smaller values provide slower release and larger values provide faster release. The default is 400 (approximately 164 ms). | 0x0190 | Si4706-D50, Si4705/31/35 -D50 and later, Si4732 |
| 0x1804 | FM_BLEND_SNR_STEREO_THRESHOLD | Sets SNR threshold for stereo blend (Full stereo above threshold, blend below threshold). To force stereo, set this to 0. To force mono, set this to 127. Default value is 27 dB. | 0x001B | Si4704/05-D50 and later, Si4706-D50 and later, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1805 | FM_BLEND_SNR_MONO_THRESHOLD | Sets SNR threshold for mono blend (Full mono below threshold, blend above threshold). To force stereo, set this to 0. To force mono, set this to 127. Default value is 14 dB. | 0x000E | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1806 | FM_BLEND_SNR_ATTACK_RATE | Sets the stereo to mono attack rate for SNR based blend. Smaller values provide slower attack and larger values provide faster attack. The default is 4000 (approximately 16 ms). | 0x0FA0 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |

Table 5. FM/RDS Receiver Property Summary (Continued)

| Prop | Name | Description | Default | Available In |
|--------|-------------------------------------|---|---------|--|
| 0x1807 | FM_BLEND_SNR_RELEASE_RATE | Sets the mono to stereo release rate for SNR based blend. Smaller values provide slower release and larger values provide faster release. The default is 400 (approximately 164 ms). | 0x0190 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1808 | FM_BLEND_MULTIPATH_STEREO_THRESHOLD | Sets multipath threshold for stereo blend (Full stereo below threshold, blend above threshold). To force stereo, set this to 100. To force mono, set this to 0. Default value is 20. | 0x0014 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1809 | FM_BLEND_MULTIPATH_MONO_THRESHOLD | Sets Multipath threshold for mono blend (Full mono above threshold, blend below threshold). To force stereo, set to 100. To force mono, set to 0. The default is 60. | 0x003C | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x180A | FM_BLEND_MULTIPATH_ATTACK_RATE | Sets the stereo to mono attack rate for Multipath based blend. Smaller values provide slower attack and larger values provide faster attack. The default is 4000 (approximately 16 ms). | 0x0FA0 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x180B | FM_BLEND_MULTIPATH_RELEASE_RATE | Sets the mono to stereo release rate for Multipath based blend. Smaller values provide slower release and larger values provide faster release. The default is 40 (approximately 1.64 s). | 0x0028 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1A00 | FM_HICUT_SNR_HIGH_THRESHOLD | Sets the SNR level at which hi-cut begins to band limit. Default value is 24. | 0x0018 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1A01 | FM_HICUT_SNR_LOW_THRESHOLD | Sets the SNR level at which hi-cut reaches maximum band limiting. Default value is 15. | 0x000F | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |

Table 5. FM/RDS Receiver Property Summary (Continued)

| Prop | Name | Description | Default | Available In |
|--------|--------------------------------------|--|---------|--|
| 0x1A02 | FM_HICUT_ATTACK_RATE | Sets the rate at which hi-cut lowers the cut-off frequency. Default value is 20000 (approximately 3 ms) | 0x4E20 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1A03 | FM_HICUT_RELEASE_RATE | Sets the rate at which hi-cut increases the cut-off frequency. Default value is 20. (approximately 3.3 s) | 0x0014 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1A04 | FM_HICUT_MULTIPATH_TRIGGER_THRESHOLD | Sets the MULTIPATH level at which hi-cut begins to band limit. Default value is 20. | 0x0014 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1A05 | FM_HICUT_MULTIPATH_END_THRESHOLD | Sets the MULTIPATH level at which hi-cut reaches maximum band limiting. Default value is 60. | 0x003C | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x1A06 | FM_HICUT_CUTOFF_FREQUENCY | Sets the maximum band limit frequency for hi-cut and also sets the maximum audio frequency. Default value is 0 (disabled). | 0x0000 | Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D60 and later, Si4732 |
| 0x4000 | RX_VOLUME | Sets the output volume. | 0x003F | All |
| 0x4001 | RX_HARD_MUTE | Mutes the audio output. L and R audio outputs may be muted independently. | 0x0000 | All |

Table 6. Status Response for the FM/RDS Receiver

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

| Bit | Name | Function |
|-----|----------|--|
| 7 | CTS | Clear to Send. 0 = Wait before sending next command. 1 = Clear to send next command. |
| 6 | ERR | Error. 0 = No error 1 = Error |
| 5:4 | Reserved | Values may vary. |
| 3 | RSQINT | Received Signal Quality Interrupt. 0 = Received Signal Quality measurement has not been triggered. 1 = Received Signal Quality measurement has been triggered. |
| 2 | RDSINT | Radio Data System (RDS) Interrupt (Si4705/31/32/35 Only). 0 = Radio data system interrupt has not been triggered. 1 = Radio data system interrupt has been triggered. |
| 1 | Reserved | Values may vary. |
| 0 | STCINT | Seek/Tune Complete Interrupt. 0 = Tune complete has not been triggered. 1 = Tune complete has been triggered. |

5.1.1. FM/RDS Receiver Commands

Command 0x01. POWER_UP

Initiates the boot process to move the device from powerdown to powerup mode. The boot can occur from internal device memory or a system controller downloaded patch. To confirm that the patch is compatible with the internal device library revision, the library revision should be confirmed by issuing the POWER_UP command with FUNC = 15 (query library ID). The device returns the response, including the library revision, and then moves into powerdown mode. The device can then be placed in powerup mode by issuing the POWER_UP command with FUNC = 0 (FM Receive) and the patch may be applied (See Section "7.2. Powerup from a Component Patch" on page 132).

The POWER_UP command configures the state of ROUT (pin 13, Si4732 pin 16) and LOUT (pin 14, Si4732 pin 1) for analog audio mode and GPO2/INT (pin 18, Si4732 pin 3) for interrupt operation. For the Si4705/31/32/35, the POWER_UP command also configures the state of GPO3/DCLK (pin 17, Si4732 pin 2), DFS (pin 16, Si4732 pin 1), and DOUT (pin 15, Si4732 pin 16) for digital audio mode. The command configures GPO2/INT interrupts (GPO2OEN) and CTS interrupts (CTSIEN). If both are enabled, GPO2/INT is driven high during normal operation and low for a minimum of 1 μ s during the interrupt. The CTSIEN bit is duplicated in the GPO_IEN property. The command is complete when the CTS bit (and optional interrupt) is set.

Note: To change function (e.g. FM RX to AM RX), issue POWER_DOWN command to stop current function; then, issue POWER_UP to start new function.

Note: Delay at least 500 ms between powerup command and first tune command to wait for the oscillator to stabilize if XOSCEN is set and crystal is used as the RCLK.

Available in: All

Command Arguments: Two

Response Bytes: None (FUNC = 0), Seven (FUNC = 15)

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-------------|---------|-------|--------|-----------|----|----|----|
| CMD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | CTSIEN | GPO2OEN | PATCH | XOSCEN | FUNC[3:0] | | | |
| ARG2 | OPMODE[7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|---------|---|
| 1 | 7 | CTSIEN | CTS Interrupt Enable. 0 = CTS interrupt disabled. 1 = CTS interrupt enabled. |
| 1 | 6 | GPO2OEN | GPO2 Output Enable. 0 = GPO2 output disabled. 1 = GPO2 output enabled. |
| 1 | 5 | PATCH | Patch Enable. 0 = Boot normally. 1 = Copy NVM to RAM, but do not boot. After CTS has been set, RAM may be patched. |

| ARG | Bit | Name | Function |
|-----|-----|-------------|---|
| 1 | 4 | XOSCEN | Crystal Oscillator Enable. 0 = Use external RCLK (crystal oscillator disabled). 1 = Use crystal oscillator (RCLK and GPO3/DCLK with external 32.768 kHz crystal and OPMODE=00000101). See Si47xx Data Sheet Application Schematic for external BOM details. |
| 1 | 3:0 | FUNC[3:0] | Function. 0 = FM Receive. 1–14 = Reserved. 15 = Query Library ID. |
| 2 | 7:0 | OPMODE[7:0] | Application Setting. 00000101 = Analog audio outputs (LOUT/ROUT). 00001011 = Digital audio output (DCLK, LOUT/DFS, ROUT/DIO) (Si4704/05/21/31/35/37/39/41/43/45/84/85 FMRX component 2.0 or later with XOSCEN = 0) 10110000 = Digital audio outputs (DCLK, DFS, DIO) (Si4704/05/31/35 FMRX component 2.0 or later with XOSCEN = 0). 10110101 = Analog and digital audio outputs (LOUT/ROUT and DCLK, DFS, DIO) (Si4704/05/31 FMRX component 2.0 or later with XOSCEN = 0). |

Response (FUNC = 0, FM Receive)

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

Response (FUNC = 15, Query Library ID)

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|----------------|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | PN[7:0] | | | | | | | |
| RESP2 | FWMAJOR[7:0] | | | | | | | |
| RESP3 | FWMINOR[7:0] | | | | | | | |
| RESP4 | RESERVED[7:0] | | | | | | | |
| RESP5 | RESERVED[7:0] | | | | | | | |
| RESP6 | CHIPREV[7:0] | | | | | | | |
| RESP7 | LIBRARYID[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------|---|
| 1 | 7:0 | PN[7:0] | Final 2 digits of part number (HEX). |
| 2 | 7:0 | FWMAJOR[7:0] | Firmware Major Revision (ASCII). |
| 3 | 7:0 | FWMINOR[7:0] | Firmware Minor Revision (ASCII). |

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|---|-----|----------------|---------------------------|
| 4 | 7:0 | RESERVED[7:0] | Reserved, various values. |
| 5 | 7:0 | RESERVED[7:0] | Reserved, various values. |
| 6 | 7:0 | CHIPREV[7:0] | Chip Revision (ASCII). |
| 7 | 7:0 | LIBRARYID[7:0] | Library Revision (HEX). |

Command 0x10. GET_REV

Returns the part number, chip revision, firmware revision, patch revision and component revision numbers. The command is complete when the CTS bit (and optional interrupt) is set. This command may only be sent when in powerup mode.

Available in: All

Command arguments: None

Response bytes: Fifteen (Si4705/06 only), Eight (Si4704/3x)

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|--------------------------|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | PN[7:0] | | | | | | | |
| RESP2 | FWMAJOR[7:0] | | | | | | | |
| RESP3 | FWMINOR[7:0] | | | | | | | |
| RESP4 | PATCH _H [7:0] | | | | | | | |
| RESP5 | PATCH _L [7:0] | | | | | | | |
| RESP6 | CMPMAJOR[7:0] | | | | | | | |
| RESP7 | CMPMINOR[7:0] | | | | | | | |
| RESP8 | CHIPREV[7:0] | | | | | | | |
| RESP10 | Reserved | | | | | | | |
| RESP11 | Reserved | | | | | | | |
| RESP12 | Reserved | | | | | | | |
| RESP13 | Reserved | | | | | | | |
| RESP14 | Reserved | | | | | | | |
| RESP15 | CID[7:0] (Si4705 only) | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------|--------------------------------------|
| 1 | 7:0 | PN[7:0] | Final 2 digits of Part Number (HEX). |
| 2 | 7:0 | FWMAJOR[7:0] | Firmware Major Revision (ASCII). |
| 3 | 7:0 | FWMINOR[7:0] | Firmware Minor Revision (ASCII). |
| 4 | 7:0 | PATCH _H [7:0] | Patch ID High Byte (HEX). |
| 5 | 7:0 | PATCH _L [7:0] | Patch ID Low Byte (HEX). |
| 6 | 7:0 | CMPMAJOR[7:0] | Component Major Revision (ASCII). |
| 7 | 7:0 | CMPMINOR[7:0] | Component Minor Revision (ASCII). |
| 8 | 7:0 | CHIPREV[7:0] | Chip Revision (ASCII). |
| 15 | 7:0 | CID[7:0] | CID (Si4705/06 only). |

Command 0x11. POWER_DOWN

Moves the device from powerup to powerdown mode. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. Note that only the POWER_UP command is accepted in powerdown mode. **If the system controller writes a command other than POWER_UP when in powerdown mode, the device does not respond. The device will only respond when a POWER_UP command is written. GPO pins are powered down and not active during this state. For optimal power down current, GPO2 must be either internally driven low through GPIO_CTL command or externally driven low.**

Note: In FMRX component 1.0, a reset is required when the system controller writes a command other than POWER_UP when in powerdown mode.

Note: The following describes the state of all the pins when in powerdown mode:

GPIO1, GPIO2, and GPIO3 = 0

ROUT, LOUT, DOUT, DFS = HiZ

Available in: All

Command arguments: None

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

Command 0x12. SET_PROPERTY

Sets a property shown in Table 5, “FM/RDS Receiver Property Summary,” on page 7. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. See Figure 25, “CTS and SET_PROPERTY Command Complete tCOMP Timing Model,” on page 143 and Table 31, “Command Timing Parameters for the FM Receiver,” on page 144.

Available in: All

Command Arguments: Five

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|--------------------------|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG2 | PROP _H [7:0] | | | | | | | |
| ARG3 | PROP _L [7:0] | | | | | | | |
| ARG4 | PROPD _H [7:0] | | | | | | | |
| ARG5 | PROPD _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|--------------------------|--|
| 1 | 7:0 | Reserved | Always write to 0. |
| 2 | 7:0 | PROP _H [7:0] | Property High Byte. This byte in combination with PROP _L is used to specify the property to modify. |
| 3 | 7:0 | PROP _L [7:0] | Property Low Byte. This byte in combination with PROP _H is used to specify the property to modify. |
| 4 | 7:0 | PROPD _H [7:0] | Property Value High Byte. This byte in combination with PROPD _L is used to set the property value. |
| 5 | 7:0 | PROPD _L [7:0] | Property Value Low Byte. This byte in combination with PROPD _H is used to set the property value. |

Command 0x13. GET_PROPERTY

Gets a property as shown in Table 5, “FM/RDS Receiver Property Summary,” on page 7. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Available in: All

Command arguments: Three

Response bytes: Three

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-------------------------|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG2 | PROP _H [7:0] | | | | | | | |
| ARG3 | PROP _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|-------------------------|---|
| 1 | 7:0 | Reserved | Always write to 0. |
| 2 | 7:0 | PROP _H [7:0] | Property High Byte. This byte in combination with PROP _L is used to specify the property to get. |
| 3 | 7:0 | PROP _L [7:0] | Property Low Byte. This byte in combination with PROP _H is used to specify the property to get. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|--------------------------|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| RESP2 | PROPD _H [7:0] | | | | | | | |
| RESP3 | PROPD _L [7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------|---|
| 1 | 7:0 | Reserved | Always returns 0. |
| 2 | 7:0 | PROPD _H [7:0] | Property Value High Byte. This byte in combination with PROPD _L represents the requested property value. |
| 3 | 7:0 | PROPD _L [7:0] | Property Value High Byte. This byte in combination with PROPD _H represents the requested property value. |

Command 0x14. GET_INT_STATUS

Updates bits 6:0 of the status byte. This command should be called after any command that sets the STCINT, RDSINT, or RSQINT bits. When polling this command should be periodically called to monitor the STATUS byte, and when using interrupts, this command should be called after the interrupt is set to update the STATUS byte. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be set when in powerup mode.

Available in: All

Command arguments: None

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

Command 0x20. FM_TUNE_FREQ

Sets the FM Receive to tune a frequency between 64 and 108 MHz in 10 kHz units. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The ERR bit (and optional interrupt) is set if an invalid argument is sent. Note that only a single interrupt occurs if both the CTS and ERR bits are set. The optional STC interrupt is set when the command completes. The STCINT bit is set only after the GET_INT_STATUS command is called. This command may only be sent when in powerup mode. The command clears the STC bit if it is already set. See Figure 24, “CTS and STC Timing Model,” on page 142 and Table 31, “Command Timing Parameters for the FM Receiver,” on page 144.

FM: LO frequency is 128 kHz above RF for RF frequencies \leq 90 MHz and 128 kHz below RF for RF frequencies $>$ 90 MHz. For example, LO frequency is 80.128 MHz when tuning to 80.00 MHz.

Note: For FMRX components 2.0 or earlier, tuning range is 76–108 MHz.

Note: Fast bit is supported in FMRX components 4.0 or later.

Note: Freeze bit is supported in FMRX components 4.0 or later.

Available in: All

Command arguments: Four

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-------------------------|----|----|----|----|----|--------|------|
| CMD | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | FREEZE | FAST |
| ARG2 | FREQ _H [7:0] | | | | | | | |
| ARG3 | FREQ _L [7:0] | | | | | | | |
| ARG4 | ANTCAP[7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|-------------------------|--|
| 1 | 7:1 | Reserved | Always write to 0. |
| 1 | 1 | FREEZE | Freeze Metrics During Alternate Frequency Jump. If set will cause the blend, hicut, and softmute to transition as a function of the associated attack/release parameters rather than instantaneously when tuning to alternate frequency. |
| 1 | 0 | FAST | FAST Tuning. If set, executes fast and invalidated tune. The tune status will not be accurate. |
| 2 | 7:0 | FREQ _H [7:0] | Tune Frequency High Byte. This byte in combination with FREQ _L selects the tune frequency in 10 kHz. In FM mode the valid range is from 6400 to 10800 (64–108 MHz). |
| 3 | 7:0 | FREQ _L [7:0] | Tune Frequency Low Byte. This byte in combination with FREQ _H selects the tune frequency in 10 kHz. In FM mode the valid range is from 6400 to 10800 (64–108 MHz). |
| 4 | 7:0 | ANTCAP[7:0] | Antenna Tuning Capacitor (valid only when using TXO/LPI pin as the antenna input). This selects the value of the antenna tuning capacitor manually, or automatically if set to zero. The valid range is 0 to 191. Automatic capacitor tuning is recommended. Note: When tuned manually, the varactor is offset by four codes. For example, if the varactor is set to a value of 5 manually, when read back the value will be 1. The four codes (1pf) delta accounts for the capacitance at the chip. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

Command 0x21. FM_SEEK_START

Begins searching for a valid frequency. Clears any pending STCINT or RSQINT interrupt status. The CTS bit (and optional interrupt) is set when it is safe to send the next command. RSQINT status is only cleared by the RSQ status command when the INTACK bit is set. The ERR bit (and optional interrupt) is set if an invalid argument is sent. Note that only a single interrupt occurs if both the CTS and ERR bits are set. The optional STC interrupt is set when the command completes. The STCINT bit is set only after the GET_INT_STATUS command is called. This command may only be sent when in powerup mode. The command clears the STCINT bit if it is already set. See Figure 24, “CTS and STC Timing Model,” on page 142 and Table 31, “Command Timing Parameters for the FM Receiver,” on page 144.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|--------|------|----|----|
| CMD | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | SEEKUP | WRAP | 0 | 0 |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 7:4 | Reserved | Always write to 0. |
| 1 | 3 | SEEKUP | Seek Up/Down. Determines the direction of the search, either UP = 1, or DOWN = 0. |
| 1 | 2 | WRAP | Wrap/Halt. Determines whether the seek should Wrap = 1, or Halt = 0 when it hits the band limit. |
| 1 | 1:0 | Reserved | Always write to 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

Command 0x22. FM_TUNE_STATUS

Returns the status of FM_TUNE_FREQ or FM_SEEK_START commands. The command returns the current frequency, RSSI, SNR, multipath, and the antenna tuning capacitance value (0-191). The command clears the STCINT interrupt bit when INTACK bit of ARG1 is set. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Available in: All

Command arguments: One

Response bytes: Seven

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|----|----|--------|--------|
| CMD | 0 | 0 | 1 | 0 | 0 | 0 | 1 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | CANCEL | INTACK |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 7:2 | Reserved | Always write to 0. |
| 1 | 1 | CANCEL | Cancel seek. If set, aborts a seek currently in progress. |
| 1 | 0 | INTACK | Seek/Tune Interrupt Clear. If set, clears the seek/tune complete interrupt status indicator. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-------------------------------------|-----|----|----|--------|--------|-------|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | BLTF | X | X | X | X | X | AFCRL | VALID |
| RESP2 | READFREQ _H [7:0] | | | | | | | |
| RESP3 | READFREQ _L [7:0] | | | | | | | |
| RESP4 | RSSI[7:0] | | | | | | | |
| RESP5 | SNR[7:0] | | | | | | | |
| RESP6 | MULT[7:0] | | | | | | | |
| RESP7 | READANTCAP[7:0] (Si4704/05/06 only) | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|-----------------------------|---|
| 1 | 7 | BLTF | Band Limit. Reports if a seek hit the band limit (WRAP = 0 in FM_START_SEEK) or wrapped to the original frequency (WRAP = 1). |
| 1 | 6:2 | Reserved | Always returns 0. |
| 1 | 1 | AFCRL | AFC Rail Indicator. Set if the AFC rails. |
| 1 | 0 | VALID | Valid Channel. Set if the channel is currently valid as determined by the seek/tune properties (0x1403, 0x1404, 0x1108) and would have been found during a Seek. |
| 2 | 7:0 | READFREQ _H [7:0] | Read Frequency High Byte. This byte in combination with READFREQ _L returns frequency being tuned (10 kHz). |
| 3 | 7:0 | READFREQ _L [7:0] | Read Frequency Low Byte. This byte in combination with READFREQ _H returns frequency being tuned (10 kHz). |
| 4 | 7:0 | RSSI[7:0] | Received Signal Strength Indicator. This byte contains the receive signal strength when tune is complete (dBμV). |
| 5 | 7:0 | SNR[7:0] | SNR. This byte contains the SNR metric when tune is complete (dB). |
| 6 | 7:0 | MULT[7:0] | Multipath. This byte contains the multipath metric when tune is complete. Multipath indicator is available only for Si4706-D50 and Si4704/05/30/31/34/35-D50 and later, and Si4732. |
| 7 | 7:0 | READANTCAP [7:0] | Read Antenna Tuning Capacitor (Si4704/05/06 only). This byte contains the current antenna tuning capacitor value. |

Command 0x23. FM_RSQ_STATUS

Returns status information about the received signal quality. The command returns the RSSI, SNR, frequency offset, and stereo blend percentage. It also indicates valid channel (VALID), soft mute engagement (SMUTE), and AFC rail status (AFCRL). This command can be used to check if the received signal is above the RSSI high threshold as reported by RSSIHINT, or below the RSSI low threshold as reported by RSSILINT. It can also be used to check if the signal is above the SNR high threshold as reported by SNRHINT, or below the SNR low threshold as reported by SNRLINT. For the Si4706, it can be used to check if the detected multipath is above the multipath high threshold as reported by MULTHINT, or below the multipath low threshold as reported by MULTLINT. If the PILOT indicator is set, it can also check whether the blend has crossed a threshold as indicated by BLENDINT. The command clears the RSQINT, BLENDINT, SNRHINT, SNRLINT, RSSIHINT, RSSILINT, MULTHINT, and MULTLINT interrupt bits when INTACK bit of ARG1 is set. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Available in: All

Command arguments: One

Response bytes: Seven

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|----|----|----|--------|
| CMD | 0 | 0 | 1 | 0 | 0 | 0 | 1 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | INTACK |

| ARG | Bit | Name | Function |
|-----|-----|--------|--|
| 1 | 0 | INTACK | Interrupt Acknowledge. 0 = Interrupt status preserved. 1 = Clears RSQINT, BLENDINT, SNRHINT, SNRLINT, RSSIHINT, RSSILINT, MULTHINT, MULTLINT. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|--------------|--------------|----------|----------|---------|---------|----------|-----------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | BLENDINT | X | MULTHINT | MULTLINT | SNRHINT | SNRLINT | RSSIHINT | RSSIILINT |
| RESP2 | X | X | X | X | SMUTE | X | AFCRL | VALID |
| RESP3 | PILOT | STBLEND[6:0] | | | | | | |
| RESP4 | RSSI[7:0] | | | | | | | |
| RESP5 | SNR[7:0] | | | | | | | |
| RESP6 | MULT[7:0] | | | | | | | |
| RESP7 | FREQOFF[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------|--|
| 1 | 7 | BLENDINT | Blend Detect Interrupt. 0 = Blend is within the Blend threshold settings. 1 = Blend goes above or below the Blend threshold settings. |
| 1 | 5 | MULTHINT | Multipath Detect High (Si4706-D50 and Si4704/05/30/31/34/35-D50 and later and Si4732 only). 0 = Detected multipath value has not exceeded above the Multipath high threshold. 1 = Detected multipath value has exceeded above the Multipath high threshold. |
| 1 | 4 | MULTLINT | Multipath Detect Low (Si4706-D50 and Si4704/05/30/31/34/35-D50 and later and Si4732 only). 0 = Detected multipath value has not fallen below the Multipath low threshold. 1 = Detected multipath value has fallen below the Multipath low threshold. |
| 1 | 3 | SNRHINT | SNR Detect High. 0 = Received SNR has not exceeded above SNR high threshold. 1 = Received SNR has exceeded above SNR high threshold. |
| 1 | 2 | SNRLINT | SNR Detect Low. 0 = Received SNR has not fallen below SNR low threshold. 1 = Received SNR has fallen below SNR low threshold. |
| 1 | 1 | RSSIHINT | RSSI Detect High. 0 = RSSI has not exceeded above RSSI high threshold. 1 = RSSI has exceeded above RSSI high threshold. |
| 1 | 0 | RSSILINT | RSSI Detect Low. 0 = RSSI has not fallen below RSSI low threshold. 1 = RSSI has fallen below RSSI low threshold. |
| 2 | 3 | SMUTE | Soft Mute Indicator. Indicates soft mute is engaged. |
| 2 | 1 | AFCRL | AFC Rail Indicator. Set if the AFC rails. |
| 2 | 0 | VALID | Valid Channel. Set if the channel is currently valid and would have been found during a Seek. |
| 3 | 7 | PILOT | Pilot Indicator. Indicates stereo pilot presence. |
| 3 | 6:0 | STBLEND[6:0] | Stereo Blend Indicator. Indicates amount of stereo blend in% (100 = full stereo, 0 = full mono). |
| 4 | 7:0 | RSSI[7:0] | Received Signal Strength Indicator. Contains the current receive signal strength (0–127 dBμV). |
| 5 | 7:0 | SNR[7:0] | SNR. Contains the current SNR metric (0–127 dB). |
| 6 | 7:0 | MULT[7:0] | Multipath (Si4706-D50 and Si4704/05/30/31/34/35-D50 and later and Si4732 only). Contains the current multipath metric. (0 = no multipath; 100 = full multipath) |
| 7 | 7:0 | FREQOFF[7:0] | Frequency Offset. Signed frequency offset (kHz). |

Command 0x24. FM_RDS_STATUS

Returns RDS information for current channel and reads an entry from the RDS FIFO. RDS information includes synch status, FIFO status, group data (blocks A, B, C, and D), and block errors corrected. This command clears the RDSINT interrupt bit when INTACK bit in ARG1 is set and, if MTFIFO is set, the entire RDS receive FIFO is cleared (FIFO is always cleared during FM_TUNE_FREQ or FM_SEEK_START). The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in power up mode. The FIFO size is 25 groups for FMRX component 2.0 or later, and 14 for FMRX component 1.0.

Notes:

1. FM_RDS_STATUS is supported in FMRX component 2.0 or later.
2. MTFIFO is not supported in FMRX component 2.0.

Available in: Si4705/06, Si4731/32/35

Command arguments: One

Response bytes: Twelve

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|----|------------|--------|--------|
| CMD | 0 | 0 | 1 | 0 | 0 | 1 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | STATUSONLY | MTFIFO | INTACK |

| ARG | Bit | Name | Function |
|-----|-----|------------|---|
| 1 | 2 | STATUSONLY | Status Only. Determines if data should be removed from the RDS FIFO. 0 = Data in BLOCKA, BLOCKB, BLOCKC, BLOCKD, and BLE contain the oldest data in the RDS FIFO. 1 = Data in BLOCKA will contain the last valid block A data received for the current frequency. Data in BLOCKB will contain the last valid block B data received for the current frequency. Data in BLE will describe the bit errors for the data in BLOCKA and BLOCKB. |
| 1 | 1 | MTFIFO | Empty FIFO 0 = If FIFO not empty, read and remove oldest FIFO entry. 1 = Clear RDS Receive FIFO. |
| 1 | 0 | INTACK | Interrupt Acknowledge 0 = RDSINT status preserved. 1 = Clears RDSINT. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|--------------|--------------|--------|---------------|-------------|---------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | X | X | RDSNEWBLOCKB | RDSNEWBLOCKA | X | RDSSYNCFFOUND | RDSSYNCLOST | RDSRECV |
| RESP2 | X | X | X | X | X | GRPLOST | X | RDSSYNC |

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| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|------------------|-----------|----|----|-----------|----|-----------|----|
| RESP3 | RDSFIFOUSED[7:0] | | | | | | | |
| RESP4 | BLOCKA[15:8] | | | | | | | |
| RESP5 | BLOCKA[7:0] | | | | | | | |
| RESP6 | BLOCKB[15:8] | | | | | | | |
| RESP7 | BLOCKB[7:0] | | | | | | | |
| RESP8 | BLOCKC[15:8] | | | | | | | |
| RESP9 | BLOCKC[7:0] | | | | | | | |
| RESP10 | BLOCKD[15:8] | | | | | | | |
| RESP11 | BLOCKD[7:0] | | | | | | | |
| RESP12 | BLEA[1:0] | BLEB[1:0] | | | BLEC[1:0] | | BLED[1:0] | |

| RESP | Bit | Name | Function |
|------|-----|---------------|--|
| 1 | 5 | RDSNEWBLOCKB | RDS New Block B. 1 = Valid Block B data has been received. |
| 1 | 4 | RDSNEWBLOCKA | RDS New Block A. 1 = Valid Block A data has been received. |
| 1 | 2 | RDSSYNCFFOUND | RDS Sync Found. 1 = Found RDS synchronization. |
| 1 | 1 | RDSSYNCLOST | RDS Sync Lost. 1 = Lost RDS synchronization. |
| 1 | 0 | RDSRECV | RDS Received. 1 = FIFO filled to minimum number of groups set by RDSFIFOCNT. |
| 2 | 2 | GRPLOST | Group Lost. 1 = One or more RDS groups discarded due to FIFO overrun. |
| 2 | 0 | RDSSYNC | RDS Sync. 1 = RDS currently synchronized. |
| 3 | 7:0 | RDSFIFOUSED | RDS FIFO Used. Number of groups remaining in the RDS FIFO (0 if empty). If non-zero, BLOCKA-BLOCKD contain the oldest FIFO entry and RDSFIFOUSED decrements by one on the next call to RDS_FIFO_STATUS (assuming no RDS data received in the interim). |
| 4 | 7:0 | BLOCKA[15:8] | RDS Block A. Block A group data from oldest FIFO entry if STATUSONLY is 0. Last valid Block A data if STATUSONLY is 1 (Si4706-D50 and Si4705/31/35-D50 and later and Si4732 only). |
| 5 | 7:0 | BLOCKA[7:0] | |
| 6 | 7:0 | BLOCKB[15:8] | RDS Block B. Block B group data from oldest FIFO entry if STATUSONLY is 0. Last valid Block B data if STATUSONLY is 1 (Si4706-D50 and Si4705/31/35-D50 and later and Si4732 only). |
| 7 | 7:0 | BLOCKB[7:0] | |

| RESP | Bit | Name | Function |
|------|-----|--------------|--|
| 8 | 7:0 | BLOCKC[15:8] | RDS Block C. Block C group data from oldest FIFO entry. |
| 9 | 7:0 | BLOCKC[7:0] | |
| 10 | 7:0 | BLOCKD[15:8] | RDS Block D. Block D group data from oldest FIFO entry. |
| 11 | 7:0 | BLOCKD[7:0] | |
| 12 | 7:6 | BLEA[1:0] | RDS Block A Corrected Errors. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 12 | 5:4 | BLEB[1:0] | RDS Block B Corrected Errors. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 12 | 3:2 | BLEC[1:0] | RDS Block C Corrected Errors. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 12 | 1:0 | BLED[1:0] | RDS Block D Corrected Errors. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |

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Command 0x27. FM_AGC_STATUS

Returns the AGC setting of the device. The command returns whether the AGC is enabled or disabled and it returns the LNA Gain index. This command may only be sent when in powerup mode.

Available in: All

Command arguments: None

Response bytes: Two

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 1 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|--------------------------|--------|--------|----|--------------------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |
| RESP1 | X | X | X | X | X | X | X | READ_RF- AGCDIS |
| RESP2 | X | X | X | READ_LNA_GAIN_INDEX[4:0] | | | | |

| RESP | Bit | Name | Function |
|------|-----|---------------------|--|
| 1 | 0 | READ_RFAGCDIS | This bit indicates whether the RF AGC is disabled or not 0 = RF AGC is enabled 1 = RF AGC is disabled |
| 2 | 4:0 | READ_LNA_GAIN_INDEX | These bits returns the value of the LNA GAIN index 0 = Minimum attenuation (max gain) 1 – 25 = Intermediate attenuation 26 = Maximum attenuation (min gain) Note: The max index is subject to change |

Command 0x28. FM_AGC_OVERRIDE

Overrides AGC setting by disabling the AGC and forcing the LNA to have a certain gain that ranges between 0 (minimum attenuation) and 26 (maximum attenuation). This command may only be sent when in powerup mode.

Available in: All

Command arguments: Two

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|---------------------|----|----|----|----------|
| CMD | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 0 |
| ARG1 | X | X | X | X | X | X | X | RFAGCDIS |
| ARG2 | X | X | X | LNA_GAIN_INDEX[4:0] | | | | |

| ARG | Bit | Name | Function |
|-----|-----|----------------|---|
| 1 | 0 | RFAGCDIS | This bit selects whether the RF AGC is disabled or not 0 = RF AGC is enabled 1 = RF AGC is disabled |
| 2 | 4:0 | LNA_GAIN_INDEX | These bits set the value of the LNA GAIN index 0 = Minimum attenuation (max gain) 1 – 25 = Intermediate attenuation 26 = Maximum attenuation (min gain) Note: the max index is subject to change |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|--------|--------|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | RDSINT | X | STCINT |

Command 0x80. GPIO_CTL

Enables output for GPO1, 2, and 3. GPO1, 2, and 3 can be configured for output (Hi-Z or active drive) by setting the GPO1OEN, GPO2OEN, and GPO3OEN bit. The state (high or low) of GPO1, 2, and 3 is set with the GPIO_SET command. To avoid excessive current consumption due to oscillation, GPO pins should not be left in a high impedance state. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. The default is all GPO pins set for high impedance.

Notes:

1. GPIO_CTL is fully supported in FMRX component 2.0 or later. Only bit GPO3OEN is supported in FMRX component 1.0.
2. The use of GPO2 as an interrupt pin and/or the use of GPO3 as DCLK digital clock input will override this GPIO_CTL function for GPO2 and/or GPO3 respectively.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|---------|---------|---------|----|
| CMD | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | GPO3OEN | GPO2OEN | GPO1OEN | 0 |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 7:4 | Reserved | Always write 0. |
| 1 | 3 | GPO3OEN | GPO3 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 2 | GPO2OEN | GPO2 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 1 | GPO1OEN | GPO1 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 0 | Reserved | Always write 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|--------|--------|--------|
| STATUS | CTS | ERR | X | X | X | RDSINT | ASQINT | STCINT |

Command 0x81. GPIO_SET

Sets the output level (high or low) for GPO1, 2, and 3. GPO1, 2, and 3 can be configured for output by setting the GPO1OEN, GPO2OEN, and GPO3OEN bit in the GPIO_CTL command. To avoid excessive current consumption due to oscillation, GPO pins should not be left in a high impedance state. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is all GPO pins set for high impedance.

Note: GPIO_SET is fully-supported in FMRX component 2.0 or later. Only bit GPO3LEVEL is supported in FMRX component 1.0.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|-----------|-----------|-----------|----|
| CMD | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | GPO3LEVEL | GPO2LEVEL | GPO1LEVEL | 0 |

| ARG | Bit | Name | Function |
|-----|-----|-----------|--|
| 1 | 7:4 | Reserved | Always write 0. |
| 1 | 3 | GPO3LEVEL | GPO3 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 2 | GPO2LEVEL | GPO2 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 1 | GPO1LEVEL | GPO1 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 0 | Reserved | Always write 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|--------|--------|--------|
| STATUS | CTS | ERR | X | X | X | RDSINT | ASQINT | STCINT |

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5.1.2. FM/RDS Receiver Properties

Property 0x0001. GPO_IEN

Configures the sources for the GPO2/ $\overline{\text{INT}}$ interrupt pin. Valid sources are the lower 8 bits of the STATUS byte, including CTS, ERR, RSQINT, RDSINT (Si4705/31/32/35 only), and STCINT bits. The corresponding bit is set before the interrupt occurs. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The CTS interrupt enable (CTSIEN) can be set with this property and the POWER_UP command. The state of the CTSIEN bit set during the POWER_UP command can be read by reading this property and modified by writing this property. This property may only be set or read when in powerup mode.

Errata:RSQIEN is non-functional on FMRX component 2.0.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|--------|--------|----|--------|--------|--------|----|----|--------|--------|----|--------|
| Name | 0 | 0 | 0 | 0 | RSQREP | RDSREP | 0 | STCREP | CTSIEN | ERRIEN | 0 | 0 | RSQIEN | RDSIEN | 0 | STCIEN |

| Bit | Name | Function |
|-------|----------|---|
| 15:12 | Reserved | Always write to 0. |
| 11 | RSQREP | RSQ Interrupt Repeat. 0 = No interrupt generated when RSQINT is already set (default). 1 = Interrupt generated even if RSQINT is already set. |
| 10 | RDSREP | RDS Interrupt Repeat (Si4705/31/35 and Si4732 Only). 0 = No interrupt generated when RDSINT is already set (default). 1 = Interrupt generated even if RDSINT is already set. |
| 9 | Reserved | Always write to 0. |
| 8 | STCREP | STC Interrupt Repeat. 0 = No interrupt generated when STCINT is already set (default). 1 = Interrupt generated even if STCINT is already set. |
| 7 | CTSIEN | CTS Interrupt Enable. After PowerUp, this bit reflects the CTSIEN bit in ARG1 of PowerUp Command. 0 = No interrupt generated when CTS is set. 1 = Interrupt generated when CTS is set. |
| 6 | ERRIEN | ERR Interrupt Enable. 0 = No interrupt generated when ERR is set (default). 1 = Interrupt generated when ERR is set. |
| 5:4 | Reserved | Always write to 0. |
| 3 | RSQIEN | RSQ Interrupt Enable. 0 = No interrupt generated when RSQINT is set (default). 1 = Interrupt generated when RSQINT is set. |
| 2 | RDSIEN | RDS Interrupt Enable (Si4705/31/35 and Si4732 Only). 0 = No interrupt generated when RDSINT is set (default). 1 = Interrupt generated when RDSINT is set. |
| 1 | Reserved | Always write to 0. |
| 0 | STCIEN | Seek/Tune Complete Interrupt Enable. 0 = No interrupt generated when STCINT is set (default). 1 = Interrupt generated when STCINT is set. |

Property 0x0102. DIGITAL_OUTPUT_FORMAT

Configures the digital audio output format. Configuration options include DCLK edge, data format, force mono, and sample precision.

Available in: Si4704-D60 and later, Si4705/06, Si4731/32/35, Si4730/34-D60 and later

Default: 0x0000

Note: DIGITAL_OUTPUT_FORMAT is supported in FM receive component 2.0 or later.

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|----|----|----|----|----|----|---|---|-------|------------|---|---|---|-------|------------|---|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OFALL | OMODE[3:0] | | | | OMONO | OSIZE[1:0] | |

| Bit | Name | Function |
|------|------------|--|
| 15:8 | Reserved | Always write to 0. |
| 7 | OFALL | Digital Output DCLK Edge. 0 = use DCLK rising edge 1 = use DCLK falling edge |
| 6:3 | OMODE[3:0] | Digital Output Mode. 0000 = I ² S 0110 = Left-justified 1000 = MSB at second DCLK after DFS pulse 1100 = MSB at first DCLK after DFS pulse |
| 2 | OMONO | Digital Output Mono Mode. 0 = Use mono/stereo blend (per blend thresholds) 1 = Force mono |
| 1:0 | OSIZE[1:0] | Digital Output Audio Sample Precision. 0 = 16-bits 1 = 20-bits 2 = 24-bits 3 = 8-bits |

Property 0x0104. DIGITAL_OUTPUT_SAMPLE_RATE

Enables digital audio output and configures digital audio output sample rate in samples per second (sps). When DOSR[15:0] is 0, digital audio output is disabled. The over-sampling rate must be set in order to satisfy a minimum DCLK of 1 MHz. To enable digital audio output, program DOSR[15:0] with the sample rate in samples per second. **The system controller must establish DCLK and DFS prior to enabling the digital audio output else the device will not respond and will require reset. The sample rate must be set to 0 before the DCLK/DFS is removed. FM_TUNE_FREQ command must be sent after the POWER_UP command to start the internal clocking before setting this property.**

Note: DIGITAL_OUPTUT_SAMPLE_RATE is supported in FM receive component 2.0 or later.

Available in: Si4704-D60 and later, Si4705/06, Si4731/32/35, Si4730/34-D60 and later

Default: 0x0000 (digital audio output disabled)

Units: sps

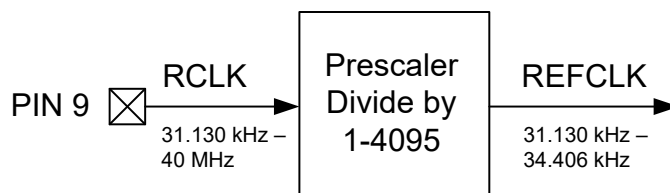
Range: 32–48 ksps, 0 to disable digital audio output

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Name | DOSR[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|------------|--|
| 15:0 | DOSR[15:0] | Digital Output Sample Rate. 32–48 ksps. 0 to disable digital audio output. |

Property 0x0201. REFCLK_FREQ

Sets the frequency of the REFCLK from the output of the prescaler. The REFCLK range is 31130 to 34406 Hz (32768 \pm 5% Hz) in 1 Hz steps, or 0 (to disable AFC). For example, an RCLK of 13 MHz would require a prescaler value of 400 to divide it to 32500 Hz REFCLK. The reference clock frequency property would then need to be set to 32500 Hz. RCLK frequencies between 31130 Hz and 40 MHz are supported, however, there are gaps in frequency coverage for prescaler values ranging from 1 to 10, or frequencies up to 311300 Hz. The following table summarizes these RCLK gaps.

**Figure 1. REFCLK Prescaler****Table 7. RCLK Gaps**

| Prescaler | RCLK Low (Hz) | RCLK High (Hz) |
|-----------|---------------|----------------|
| 1 | 31130 | 34406 |
| 2 | 62260 | 68812 |
| 3 | 93390 | 103218 |
| 4 | 124520 | 137624 |
| 5 | 155650 | 172030 |
| 6 | 186780 | 206436 |
| 7 | 217910 | 240842 |
| 8 | 249040 | 275248 |
| 9 | 280170 | 309654 |
| 10 | 311300 | 344060 |

The RCLK must be valid 10 ns before sending and 20 ns after completing the FM_TUNE_FREQ and FM_SEEK_START commands. In addition, the RCLK must be valid at all times for proper AFC operation. The RCLK may be removed or reconfigured at other times. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 32768 Hz.

Available in: All

Default: 0x8000 (32768)

Units: 1 Hz

Step: 1 Hz

Range: 31130–34406

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | REFCLKF[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|---------------|---|
| 15:0 | REFCLKF[15:0] | Frequency of Reference Clock in Hz. The allowed REFCLK frequency range is between 31130 and 34406 Hz (32768 \pm 5%), or 0 (to disable AFC). |

Property 0x0202. REFCLK_PRESCALE

Sets the number used by the prescaler to divide the external RCLK down to the internal REFCLK. The range may be between 1 and 4095 in 1 unit steps. For example, an RCLK of 13 MHz would require a prescaler value of 400 to divide it to 32500 Hz. The reference clock frequency property would then need to be set to 32500 Hz. The RCLK must be valid 10 ns before sending and 20 ns after completing the FM_TUNE_FREQ and FM_TUNE_START commands. In addition, the RCLK must be valid at all times for proper AFC operation. The RCLK may be removed or reconfigured at other times. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 1.

Available in: All
Default: 0x0001
Step: 1
Range: 1–4095

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|----------|---------------|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | RCLK SEL | REFCLKP[11:0] | | | | | | | | | | | |

| Bit | Name | Function |
|-------|---------------|--|
| 15:13 | Reserved | Always write to 0. |
| 12 | RCLKSEL | RCLKSEL. 0 = RCLK pin is clock source. 1 = DCLK pin is clock source. |
| 11:0 | REFCLKP[11:0] | Prescaler for Reference Clock. Integer number used to divide clock frequency down to REFCLK frequency. The allowed REFCLK frequency range is between 31130 and 34406 Hz (32768 5%), or 0 (to disable AFC). |

Property 0x1100. FM_DEEMPHASIS

Sets the FM Receive de-emphasis to 50 or 75 μ s. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 75 μ s.

Available in: All

Default: 0x0002

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|-------------|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DEEMPH[1:0] | |

| Bit | Name | Function |
|------|-------------|---|
| 15:2 | Reserved | Always write to 0. |
| 1:0 | DEEMPH[1:0] | FM De-Emphasis. 10 = 75 μ s. Used in USA (default) 01 = 50 μ s. Used in Europe, Australia, Japan 00 = Reserved 11 = Reserved |

Property 0x1102. FM_CHANNEL_FILTER

Selects bandwidth of channel filter applied at the demodulation stage. Default is automatic which means the device automatically selects proper channel filter. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 1.

Available in: Si4706, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x0001 (Si4706, Si4705/31/35-D50 and later, Si4732)

0x0000 (Si4704/30/34-D50 and later)

Range: 0–4

Note: Automatic channel filter setting is not supported in FMRX component 3.0.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|----------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | FMCHFILT[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-------------------|---|
| 15:0 | FM_CHANNEL_FILTER | 0 = Automatically select proper channel filter. 1 = Force wide (110 kHz) channel filter. 2 = Force narrow (84 kHz) channel filter. 3 = Force narrower (60 kHz) channel filter. 4 = Force narrowest (40 kHz) channel filter. |

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Property 0x1107. FM_ANTENNA_INPUT

Selects what type of antenna and what pin it is connected to. Default is 0 which means the antenna used is a headphone (long) antenna and it is connected to the FMI pin. Setting the FMTXO bit to 1 means that the antenna used is an embedded (short) antenna and it is connected to the TXO/LPI pin.

Note: To assure proper tuning, the FM_TUNE_FREQ command should be issued immediately after this property is changed.

Available in: Si4704/05/06

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|-------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FMTXO |

| Bit | Name | Function |
|------|----------|---|
| 15:1 | Reserved | Always write to 0 |
| 0 | FMTXO | Selects what type of antenna and which pin it is connected to: 0 = Use FMI pin for headphone (long) antenna 1 = Use TXO/LPI pin for embedded (short) antenna |

Property 0x1108. FM_MAX_TUNE_ERROR

Sets the maximum freq error allowed before setting the AFC rail indicator (AFCRL). The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 20 kHz.

Available in: All

Default: 0x0014 (all others)

Units: kHz

Step: 1

Range: 0–255

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|-------------------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | | | | | | | FMMAXTUNEERR[7:0] |

| Bit | Name | Function |
|------|--------------|---|
| 15:8 | Reserved | Always write to 0. |
| 7:0 | FMMAXTUNEERR | FM Maximum Tuning Frequency Error. Maximum tuning error allowed before setting the AFC Rail Indicator ON. Specified in units of kHz. Default is 20 kHz. |

Property 0x1200. FM_RSQ_INT_SOURCE

Configures interrupt related to Received Signal Quality metrics. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|-----------|----|-----------|-----------|---------|---------|----------|----------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | BLEN-DIEN | 0 | MULT-HIEN | MULT-LIEN | SNRHIEN | SNRLIEN | RSSIHIEN | RSSILIEN |

| Bit | Name | Function |
|------|----------|--|
| 15:8 | Reserved | Always write to 0. |
| 7 | BLENDIEN | Interrupt Source Enable: Blend. Enable blend as the source of interrupt which the threshold is set by FM_RSQ_BLEND_THRESHOLD. |
| 6 | Reserved | Always write to 0. |
| 5 | MULTHIEN | Interrupt Source Enable: Multipath High (Si4706-D50, Si4704/05/30/31/34/35-D50 and later and Si4732 only). Enable Multipath high as the source of interrupt which the threshold is set by FM_RSQ_MULTIPATH_HI_THRESHOLD. |
| 4 | MULTLIEN | Interrupt Source Enable: Multipath Low (Si4706-D50, Si4704/05/30/31/34/35-D50 and later and Si4732 only). Enable Multipath low as the source of interrupt which the threshold is set by FM_RSQ_MULTIPATH_LO_THRESHOLD. |
| 3 | SNRHIEN | Interrupt Source Enable: SNR High. Enable SNR high as the source of interrupt which the threshold is set by FM_RSQ_SNR_HI_THRESHOLD. |
| 2 | SNRLIEN | Interrupt Source Enable: SNR Low. Enable SNR low as the as the source of interrupt which the threshold is set by FM_RSQ_SNR_LO_THRESHOLD. |
| 1 | RSSIHIEN | Interrupt Source Enable: RSSI High. Enable RSSI high as the source of interrupt which the threshold is set by FM_RSQ_RSSI_HI_THRESHOLD. |
| 0 | RSSILIEN | Interrupt Source Enable: RSSI Low. Enable RSSI low as the source of interrupt which the threshold is set by FM_RSQ_RSSI_LO_THRESHOLD. |

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Property 0x1201. FM_RSQ_SNR_HI_THRESHOLD

Sets high threshold which triggers the RSQ interrupt if the SNR is above this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 127dB.

Available in: All

Default: 0x007F

Units: dB

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNRH[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | SNRH | FM RSQ SNR High Threshold. Threshold which triggers the RSQ interrupt if the SNR is above this threshold. Specified in units of dB in 1 dB steps (0–127). Default is 127 dB. |

Property 0x1202. FM_RSQ_SNR_LO_THRESHOLD

Sets low threshold which triggers the RSQ interrupt if the SNR is below this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0 dB.

Available in: All

Default: 0x0000

Units: dB

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNRL[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | SNRL | FM RSQ SNR Low Threshold. Threshold which triggers the RSQ interrupt if the SNR is below this threshold. Specified in units of dB in 1 dB steps (0–127). Default is 0 dB. |

Property 0x1203. FM_RSQ_RSSI_HI_THRESHOLD

Sets high threshold which triggers the RSQ interrupt if the RSSI is above this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 127 dBμV.

Available in: All

Default: 0x007F

Units: dBμV

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RSSIH[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | RSSIH | FM RSQ RSSI High Threshold. Threshold which triggers the RSQ interrupt if the RSSI is above this threshold. Specified in units of dBμV in 1 dB steps (0–127). Default is 127 dBμV. |

Property 0x1204. FM_RSQ_RSSI_LO_THRESHOLD

Sets low threshold which triggers the RSQ interrupt if the RSSI is below this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0 dBμV.

Available in: All

Default: 0x0000

Units: dBμV

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RSSIL[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | RSSIL | FM RSQ RSSI Low Threshold. Threshold which triggers the RSQ interrupt if the RSSI is below this threshold. Specified in units of dBμV in 1 dB steps (0–127). Default is 0 dBμV. |

Property 0x1205. FM_RSQ_MULTIPATH_HI_THRESHOLD

Sets the high threshold which triggers the RSQ interrupt if the Multipath level is above this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in power up mode. The value may be the threshold multipath percent (0–100), or 127 to disable the feature.

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x007F

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MULTH[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | MULTH | FM RSQ Multipath High Threshold. Threshold which triggers the RSQ interrupt if the Multipath is above this threshold. Default is 127. |

Property 0x1206. FM_RSQ_MULTIPATH_LO_THRESHOLD

Sets the low threshold which triggers the RSQ interrupt if the Multipath level is below this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in power up mode. The default is 0.

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x0000

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MULTL[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:7 | Reserved | Always write to 0 |
| 6:0 | MULTL | FM RSQ Multipath Low Threshold. Threshold which triggers the RSQ interrupt if the Multipath is below this threshold. Default is 0. |

Property 0x1207. FM_RSQ_BLEND_THRESHOLD

Sets the blend threshold for blend interrupt when boundary is crossed. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 1%.

Available in: All

Default: 0x0081

Units: %

Step: 1

Range: 0–100

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|-------|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PILOT | BLEND[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:8 | Reserved | Always write to 0. |
| 7 | PILOT | Pilot Indicator. This bit has to be set to 1 (there has to be a pilot present) in order for FM_RSQ_BLEND_THRESHOLD to trigger an interrupt. Without a pilot tone, the part is always in full mono mode and never goes into blend. |
| 6:0 | BLEND | FM RSQ Blend Threshold. This is a boundary cross threshold. If the blend cross from above to below, or the other way around from below to above this threshold, it will trigger an interrupt. Specified in units of % in 1% steps (0–100). Default is 1%. |

Property 0x1300. FM_SOFT_MUTE_RATE

Sets the attack and decay rates when entering and leaving soft mute. Lower values increase rates, and higher values decrease rates. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0x0040.

Available in: Si4706, Si4704/05

Default: 64

Step: 1

Range: 1—255

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|-------------|----|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SMRATE[7:0] | | | | | | | |

Property 0x1301. FM_SOFT_MUTE_SLOPE

Configures attenuation slope during soft mute in dB attenuation per dB SNR below the soft mute SNR threshold. Soft mute attenuation is the minimum of $SMSLOPE \times (SMTHR - SNR)$ and $SMATTN$. The recommended $SMSLOPE$ value is $CEILING(SMATTN/SMTHR)$. $SMATTN$ and $SMTHR$ are set via the $FM_SOFT_MUTE_MAX_ATTENUATION$ and $FM_SOFT_MUTE_SNR_THRESHOLD$ properties. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in power up mode. The default soft mute slope property setting is 2 dB/dB in supported devices. The soft mute slope is not configurable in Si4704/05/3x-B20 devices (those with FMRX component 2.0) and is 2 dB/dB.

Available in: Si4704/05/06/3x-D50 and later, Si4732

Default: 0x0002

Range: 0–63

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|--------------|----|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SMSLOPE[7:0] | | | | | | | |

Property 0x1302. FM_SOFT_MUTE_MAX_ATTENUATION

Sets maximum attenuation during soft mute (dB). Set to 0 to disable soft mute. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 16 dB.

Available in: All

Default: 0x0010

Units: dB

Step: 1

Range: 0–31

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|-------------|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SMATTN[4:0] | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:5 | Reserved | Always write to 0. |
| 4:0 | SMATTN | FM Soft Mute Maximum Attenuation. Set maximum attenuation during soft mute. If set to 0, then soft mute is disabled. Specified in units of dB in 1 dB steps (0–31). Default is 16 dB. |

Property 0x1303. FM_SOFT_MUTE_SNR_THRESHOLD

Sets SNR threshold to engage soft mute. Whenever the SNR for a tuned frequency drops below this threshold, the FM reception will go in soft mute, provided soft mute max attenuation property is non-zero. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 4 dB.

Available in: All

Default: 0x0004

Units: dB

Step: 1

Range: 0–15

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|------------|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SMTHR[3:0] | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:4 | Reserved | Always write to 0. |
| 3:0 | SMTHR | FM Soft Mute SNR Threshold. Threshold which will engage soft mute if the SNR falls below this. Specified in units of dB in 1 dB steps (0–15). Default is 4 dB. |

Property 0x1304. FM_SOFT_MUTE_RELEASE_RATE

Sets the soft mute release rate. Smaller values provide slower release and larger values provide faster release. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 8192 (approximately 8000 dB/s).

Release Rate (dB/s) = RELEASE[14:0]/1.024

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x2000

Range: 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|---------------|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | RELEASE[14:0] | | | | | | | | | | | | | | |

Property 0x1305. FM_SOFT_MUTE_ATTACK_RATE

Sets the soft mute attack rate. Smaller values provide slower attack and larger values provide faster attack. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 8192 (approximately 8000 dB/s).

Attack Rate (dB/s) = ATTACK[14:0]/1.024

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x2000

Range: 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|--------------|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | ATTACK[14:0] | | | | | | | | | | | | | | |

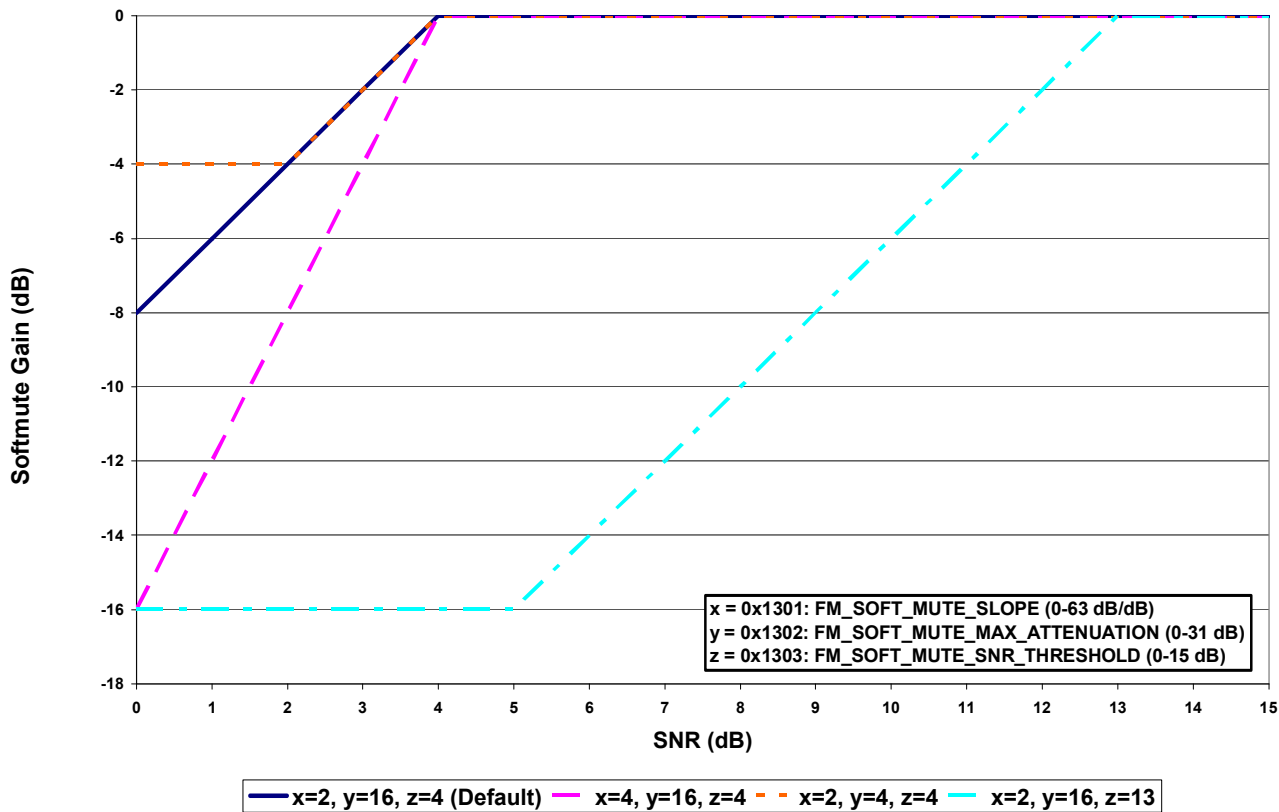


Figure 2. Softmute Gain (dB)

Property 0x1400. FM_SEEK_BAND_BOTTOM

Sets the bottom of the FM band for seek. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 87.5 MHz.

Available in: All

Default: 0x222E

Units: 10 kHz

Step: 50 kHz

Range: 64–108 MHz

Note: For FMRX components 2.0 or earlier, range is 76–108 MHz.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|----------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | FMSKFREQ[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:0 | FMSKFREQ | FM Seek Band Bottom Frequency. Selects the bottom of the FM Band during Seek. Specified in units of 10 kHz. Default is 8750 (87.5 MHz). |

Property 0x1401. FM_SEEK_BAND_TOP

Sets the top of the FM band for seek. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 107.9 MHz.

Available in: All

Default: 0x2A26

Units: 10 kHz

Step: 50 kHz

Range: 64–108 MHz

Note: For FMRX components 2.0 or earlier, range is 76–108 MHz.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | FMSKFREQH[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-----------|---|
| 15:0 | FMSKFREQH | FM Seek Band Top Frequency. Selects the top of the FM Band during Seek. Specified in units of 10 kHz. Default is 10790 (107.9 MHz). |

Property 0x1402. FM_SEEK_FREQ_SPACING

Selects frequency spacing for FM seek. There are only 3 valid values: 5, 10, and 20. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 100 kHz.

Available in: All

Default: 0x000A

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|--------------|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SKSPACE[4:0] | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:5 | Reserved | Always write to 0. |
| 4:0 | SKSPACE | FM Seek Frequency Spacing. Selects the frequency spacing during Seek function. Specified in units of 10 kHz. There are only 3 valid values: 5 (50 kHz), 10 (100 kHz), and 20 (200 kHz). Default is 10. |

Property 0x1403. FM_SEEK_TUNE_SNR_THRESHOLD

Sets the SNR threshold for a valid FM Seek/Tune. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 3 dB.

Available in: All

Default: 0x0003

Units: dB

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SKSNR[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | SKSNR | FM Seek/Tune SNR Threshold. SNR Threshold which determines if a valid channel has been found during Seek/Tune. Specified in units of dB in 1 dB steps (0–127). Default is 3 dB. |

Property 0x1404. FM_SEEK_TUNE_RSSI_THRESHOLD

Sets the RSSI threshold for a valid FM Seek/Tune. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 20 dBμV.

Available in: All

Default: 0x0014

Units: dBμV

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SKRSSI[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | SKRSSI | FM Seek/Tune Received Signal Strength Threshold. RSSI threshold which determines if a valid channel has been found during seek/tune. Specified in units of dBμV in 1 dBμV steps (0–127). Default is 20 dBμV. |

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Property 0x1500. FM_RDS_INT_SOURCE

Configures interrupt related to RDS. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0.

Available in: Si4705/06, Si4731/32/35

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|---------------|---------------|----|---------------|--------------|---------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RDSNEW-BLOCKB | RDSNEW-BLOCKA | 0 | RDSSYNC-FOUND | RDSSYN-CLOST | RDSRECV |

| Bit | Name | Function |
|------|--------------|--|
| 15:6 | Reserved | Always write to 0. |
| 5 | RDSNEWBLOCKB | RDS New Block B Found (Si4706 and Si4705/31/35-D50 and later, and Si4732 only) If set, generate an interrupt when Block B data is found or subsequently changed. |
| 4 | RDSNEWBLOCKA | RDS New Block A Found (Si4706 and Si4705/31/35-D50 and later, and Si4732 only) If set, generate an interrupt when Block A data is found or subsequently changed |
| 3 | Reserved | Always write to 0. |
| 2 | RDSSYNCFOUND | RDS Sync Found. If set, generate RDSINT when RDS gains synchronization. |
| 1 | RDSSYNCLOST | RDS Sync Lost. If set, generate RDSINT when RDS loses synchronization. |
| 0 | RDSRECV | RDS Received. If set, generate RDSINT when RDS FIFO has at least FM_RDS_INT_FIFO_COUNT entries. |

Property 0x1501. FM_RDS_INT_FIFO_COUNT

Sets the minimum number of RDS groups stored in the RDS FIFO before RDSRECV is set. The maximum value is 25 for FRMX component 2.0 or later, and 14 for FMRX component 1.0. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. Default is 0.

Note: FM_RDS_INT_FIFO_COUNT is supported in FMRX component 2.0 or later.

Available in: Si4705/06, Si4731/32/35

Default: 0x0000

Range: 0–25

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | | | | | | |

| Bit | Name | Function |
|-----|------------|--|
| 7:0 | RDSFIFOCNT | RDS FIFO Count. Minimum number of RDS groups stored in the RDS FIFO before RDSRECV is set. |

Property 0x1502. FM_RDS_CONFIG

Configures RDS settings to enable RDS processing (RDSEN) and set RDS block error thresholds. When a RDS Group is received, all block errors must be less than or equal the associated block error threshold for the group to be stored in the RDS FIFO. If blocks with errors are permitted into the FIFO, the block error information can be reviewed when the group is read using the FM_RDS_STATUS command. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0x0000.

Note: FM_RDS_CONFIG is supported in FMRX component 2.0 or later.

Available in: Si4705/06, Si4731/32/35

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-------------|-----|-------------|-----|-------------|-----|-------------|----|----|----|----|----|----|----|----|-------|
| Name | BLETHA[1:0] | | BLETHB[1:0] | | BLETHC[1:0] | | BLETHD[1:0] | | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RDSEN |

| Bit | Name | Function |
|-------|-------------|--|
| 15:14 | BLETHA[1:0] | Block Error Threshold BLOCKA. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 13:12 | BLETHB[1:0] | Block Error Threshold BLOCKB. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 11:10 | BLETHC[1:0] | Block Error Threshold BLOCKC. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 9:8 | BLETHD[1:0] | Block Error Threshold BLOCKD. 0 = No errors. 1 = 1–2 bit errors detected and corrected. 2 = 3–5 bit errors detected and corrected. 3 = Uncorrectable. |
| 0 | RDSEN | RDS Processing Enable. 1 = RDS processing enabled. |

Recommended Block Error Threshold options:

2,2,2,2 = No group stored if any errors are uncorrected.

3,3,3,3 = Group stored regardless of errors.

0,0,0,0 = No group stored containing corrected or uncorrected errors.

3,2,3,3 = Group stored with corrected errors on B, regardless of errors on A, C, or D.

Property 0x1503. FM_RDS_CONFIDENCE

Selects the confidence level requirement for each RDS block. A higher confidence requirement will result in fewer decoder errors (% of blocks with BLE<3 that contains incorrect information) but more block errors (% of blocks with BLE=3). The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0x1111.

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x1111

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|------------------|-----|----|----|--------------------|----|----|----|------------------|----|----|----|
| Name | X | X | X | X | CONFIDENCEB[3:0] | | | | CONFIDENCECEC[3:0] | | | | CONFIDENCED[3:0] | | | |

| Bit | Name | Function |
|------|---------------|---|
| 11:8 | CONFIDENCEB | Selects decoder error rate threshold for Block B. |
| 7:4 | CONFIDENCECEC | Selects decoder error rate threshold for Block C. |
| 3:0 | CONFIDENCED | Selects decoder error rate threshold for Block D. |

Property 0x1800. FM_BLEND_RSSI_STEREO_THRESHOLD

Sets RSSI threshold for stereo blend (Full stereo above threshold, blend below threshold). To force stereo, set to 0. To force mono, set to 127. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 49 dB μ V.

Available in: Si4706-D50, Si4740/41/42/43/44/45, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x0031

Units: dB μ V

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | STRTHRESH[6:0] | | | | | | |

Property 0x1801. FM_BLEND_RSSI_MONO_THRESHOLD

Sets RSSI threshold for mono blend (Full mono below threshold, blend above threshold). To force stereo, set this to 0. To force mono, set this to 127. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 30 dB μ V.

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x001E

Units: dB μ V

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MONOTHRESH[6:0] | | | | | | |

Property 0x1802. FM_BLEND_RSSI_ATTACK_RATE

Sets the stereo to mono attack rate for RSSI based blend. Smaller values provide slower attack and larger values provide faster attack. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 4000 (approximately 16 ms). $ATTACK[15:0] = 65536/time$, where time is the desired transition time in ms.

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x0FA0

Step: 1

Range: 0 (disabled), 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|--------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | ATTACK[15:0] | | | | | | | | | | | | | | | |

Property 0x1803. FM_BLEND_RSSI_RELEASE_RATE

Sets the mono to stereo release rate for RSSI based blend. Smaller values provide slower release and larger values provide faster release. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 400 (approximately 164 ms). $\text{RELEASE}[15:0] = 65536/\text{time}$, where time is the desired transition time in ms.

Available in: Si4706-D50, Si4704/05/30/31/34/35-D50 and later, Si4732

Default: 0x0190

Step: 1

Range: 0 (disabled), 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | RELEASE[15:0] | | | | | | | | | | | | | | | |

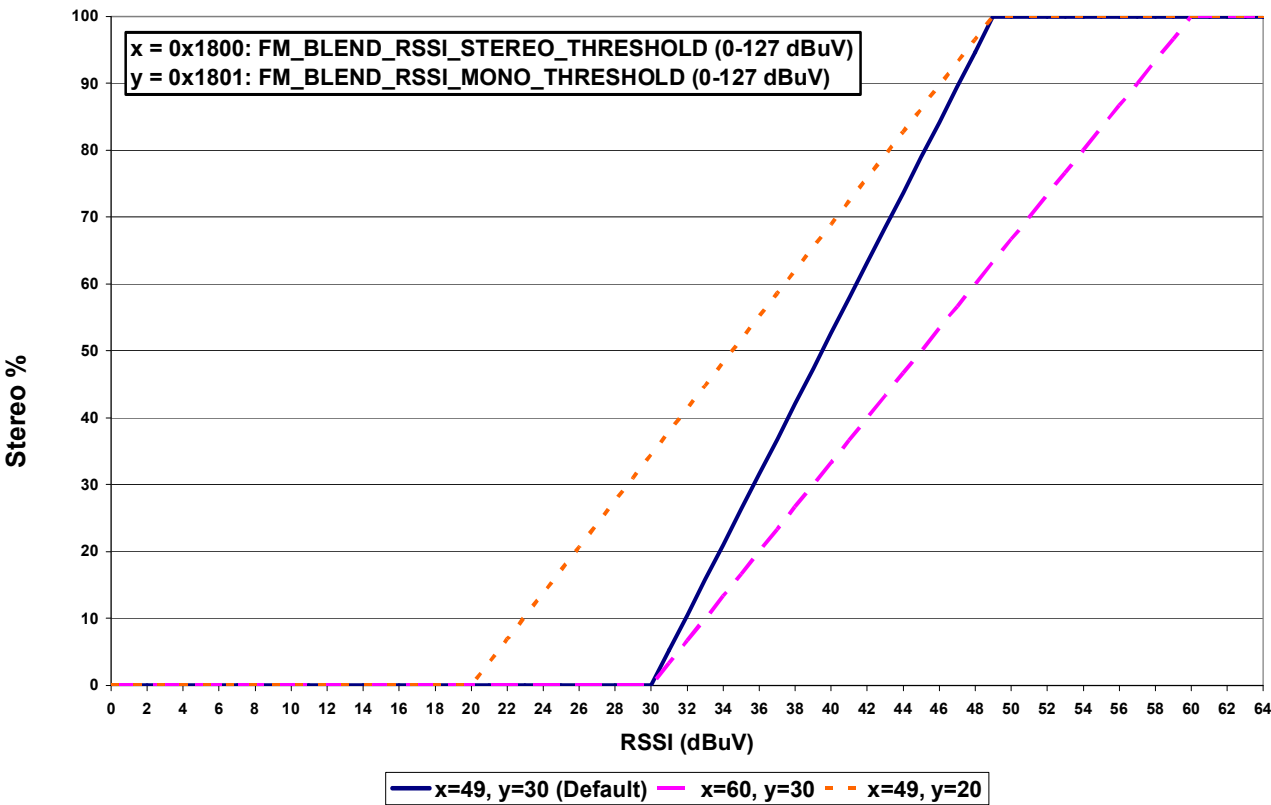


Figure 3. RSSI Blend

Property 0x1804. FM_BLEND_SNR_STEREO_THRESHOLD

Sets SNR threshold for stereo blend (Full stereo above threshold, blend below threshold). To force stereo, set this to 0. To force mono, set this to 127. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 27 dB.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x001B

Units: dB

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | STRTHRESH[6:0] | | | | | | |

Property 0x1805. FM_BLEND_SNR_MONO_THRESHOLD

Sets SNR threshold for mono blend (Full mono below threshold, blend above threshold). To force stereo, set to 0. To force mono, set to 127. The CTS bit (and optional interrupt) is set when it is safe to send the next command.

This property may only be set or read when in powerup mode. The default is 14 dB.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x000E

Units: dB

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MONOTHRESH[6:0] | | | | | | |

Property 0x1806. FM_BLEND_SNR_ATTACK_RATE

Sets the stereo to mono attack rate for SNR based blend. Smaller values provide slower attack and larger values provide faster attack. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 4000 (approximately 16 ms). $\text{ATTACK}[15:0] = 65536/\text{time}$, where time is the desired transition time in ms.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0FA0

Step: 1

Range: 0 (disabled), 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|--------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | ATTACK[15:0] | | | | | | | | | | | | | | | |

Property 0x1807. FM_BLEND_SNR_RELEASE_RATE

Sets the mono to stereo release rate for SNR based blend. Smaller values provide slower release and larger values provide faster release. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 400 (approximately 164 ms). $\text{RELEASE}[15:0] = 65536/\text{time}$, where time is the desired transition time in ms.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0190

Step: 1

Range: 0 (disabled), 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | RELEASE[15:0] | | | | | | | | | | | | | | | |

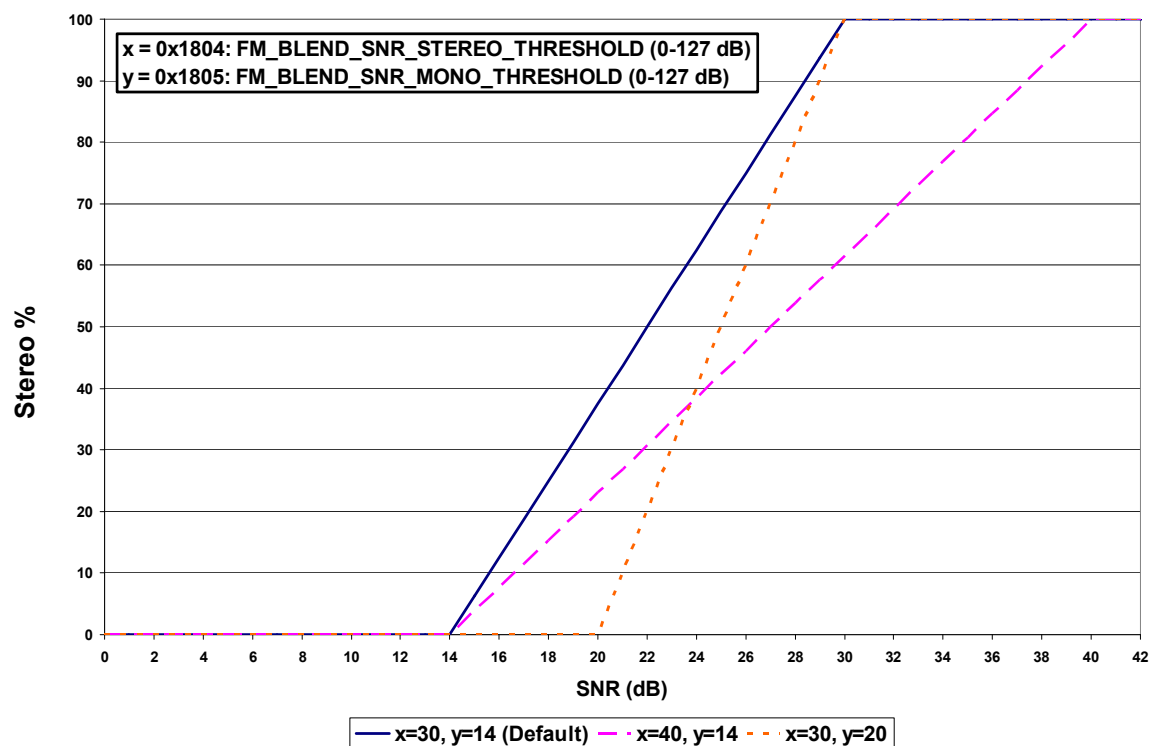


Figure 4. SNR Blend

Property 0x1808. FM_BLEND_MULTIPATH_STEREO_THRESHOLD

Sets Multipath threshold for stereo blend (Full stereo below threshold, blend above threshold). To force stereo, set to 100. To force mono, set to 0. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 20.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0014

Step: 1

Range: 0–100

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | STRTHRESH[6:0] | | | | | | |

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Property 0x1809. FM_BLEND_MULTIPATH_MONO_THRESHOLD

Sets Multipath threshold for mono blend (Full mono above threshold, blend below threshold). To force stereo, set to 100. To force mono, set to 0. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 60.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x003C

Step: 1

Range: 0–100

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MONOTHRESH[6:0] | | | | | | |

Property 0x180A. FM_BLEND_MULTIPATH_ATTACK_RATE

Sets the stereo to mono attack rate for Multipath based blend. Smaller values provide slower attack and larger values provide faster attack. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 4000 (approximately 16 ms). $ATTACK[15:0] = 65536/time$, where time is the desired transition time in ms.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0FA0

Step: 1

Range: 0 (disabled), 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|--------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | ATTACK[15:0] | | | | | | | | | | | | | | | |

Property 0x180B. FM_BLEND_MULTIPATH_RELEASE_RATE

Sets the mono to stereo release rate for Multipath based blend. Smaller values provide slower release and larger values provide faster release. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 40 (approximately 1.64 s). $\text{RELEASE}[15:0] = 65536/\text{time}$, where time is the desired transition time in ms.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0028

Step: 1

Range: 0 (disabled), 1–32767

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | RELEASE[15:0] | | | | | | | | | | | | | | | |

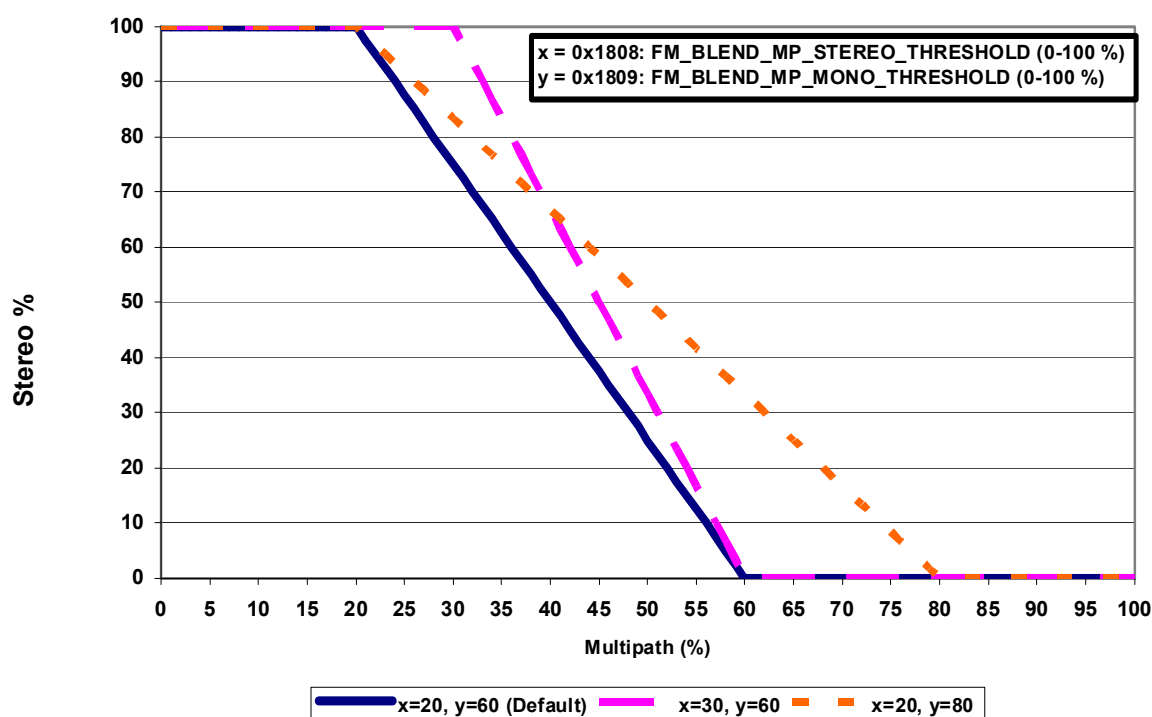


Figure 5. MP Blend

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Property 0x1A00. FM_HICUT_SNR_HIGH_THRESHOLD

Sets the SNR level at which hi-cut begins to band limit. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 24 dB.

Available in: Si4704/05-D50 and later, Si4706-D50 and later, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0018

Range: 0–127

Note: Was property 0x180C in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|---------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNR_HIGH[6:0] | | | | | | |

Property 0x1A01. FM_HICUT_SNR_LOW_THRESHOLD

Sets the SNR level at which hi-cut reaches maximum band limiting. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 15 dB.

Available in: Si4704/05-D50 and later, Si4706-D50 and later, Si4730/31/34/35-D50 and later, Si4732

Default: 0x000F

Range: 0–127

Note: Was property 0x180D in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|--------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNR_LOW[6:0] | | | | | | |

Property 0x1A02. FM_HICUT_ATTACK_RATE

Sets the rate at which hi-cut lowers the transition frequency. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 20000 (approximately 3 ms).

ATTACK[15:0] = 65536/time, where time is the desired transition time in ms.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x4E20

Range: 0 (disabled), 1–32767

Note: Was property 0x180E in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|--------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | ATTACK[15:0] | | | | | | | | | | | | | | | |

Property 0x1A03. FM_HICUT_RELEASE_RATE

Sets the rate at which hi-cut increases the transition frequency. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 20 (approximately 3.3 s).

$\text{RELEASE}[15:0] = 65536/\text{time}$, where time is the desired transition time in ms.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0014

Range: 0 (disabled), 1–32767

Note: Was property 0x180F in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | RELEASE[15:0] | | | | | | | | | | | | | | | |

Property 0x1A04. FM_HICUT_MULTIPATH_TRIGGER_THRESHOLD

Sets the MULTIPATH level at which hi-cut begins to band limit. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 20%.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x0014

Range: 0–100

Note: Was property 0x1810 in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|-------------------|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MULT_TRIGGER[6:0] | | | | | |

Property 0x1A05. FM_HICUT_MULTIPATH_END_THRESHOLD

Sets the MULTIPATH level at which hi-cut reaches maximum band limiting. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 60%.

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default: 0x003C

Range: 0–100

Note: Was property 0x1811 in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|---------------|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MULT_END[6:0] | | | | | |

Property 0x1A06. FM_HICUT_CUTOFF_FREQUENCY

Sets the maximum band limit frequency for hi-cut and also sets the maximum audio frequency. The CTS bit (optional interrupt) is set when it is safe to send the next command. This property may only be set or read in POWERUP mode. The default is 0(disabled).

Available in: Si4704/05-D50 and later, Si4706-D50, Si4730/31/34/35-D50 and later, Si4732

Default 0x0000

Range: 0–7 (maximum band limit frequency for Hi-Cut)

0–7 (maximum audio frequency)

Note: Was property 0x1812 in FW2.B. The maximum audio frequency was not programmable in FW2.B.

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-----|-----|-----|-----|-----|-----|----|----|----|----------------------------|----|----|----|----------------|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | MAXIMUM AUDIO FREQ[2:0] | | | 0 | FREQUENCY[2:0] | | |

| Bit | Name | Function |
|-----|---------------------------------|---|
| 6:4 | MAXIMUM AUDIO FREQUENCY[2:0] | Maximum Audio Frequency. 0 = Maximum Audio transition frequency = Max Audio BW 1 = Maximum Audio transition frequency = 2 kHz 2 = Maximum Audio transition frequency = 3 kHz 3 = Maximum Audio transition frequency = 4 kHz 4 = Maximum Audio transition frequency = 5 kHz 5 = Maximum Audio transition frequency = 6 kHz 6 = Maximum Audio transition frequency = 8 kHz 7 = Maximum Audio transition frequency = 11 kHz |
| 2:0 | FREQUENCY[2:0] | Frequency. 0 = Hi-Cut disabled 1 = Hi-cut transition frequency = 2 kHz 2 = Hi-cut transition frequency = 3 kHz 3 = Hi-cut transition frequency = 4 kHz 4 = Hi-cut transition frequency = 5 kHz 5 = Hi-cut transition frequency = 6 kHz 6 = Hi-cut transition frequency = 8 kHz 7 = Hi-cut transition frequency = 11 kHz |

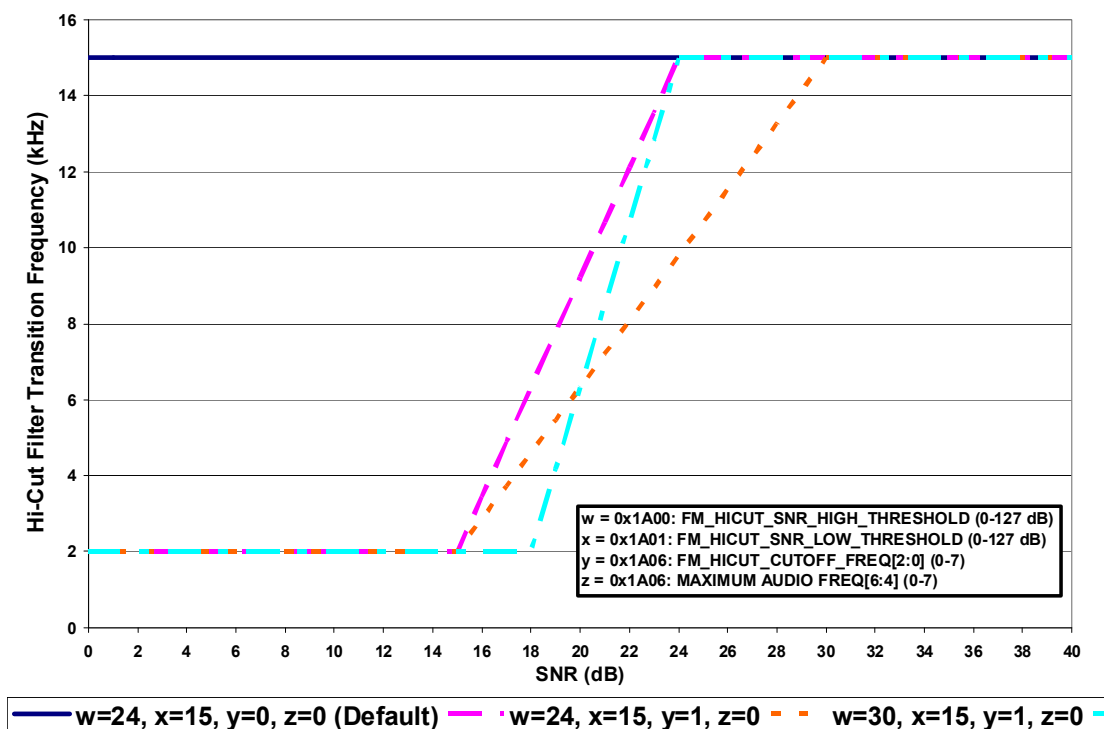


Figure 6. HiCut Controlled by SNR Metric

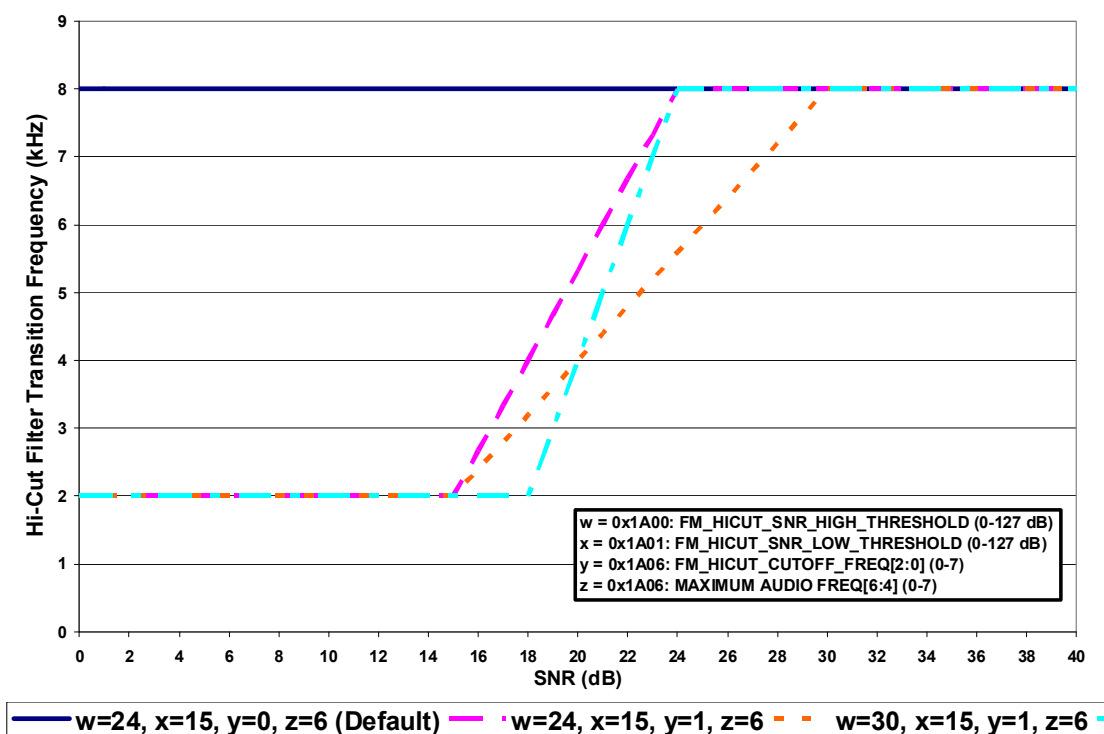


Figure 7. HiCut Controlled by SNR Metric with Maximum Audio Frequency 8 kHz

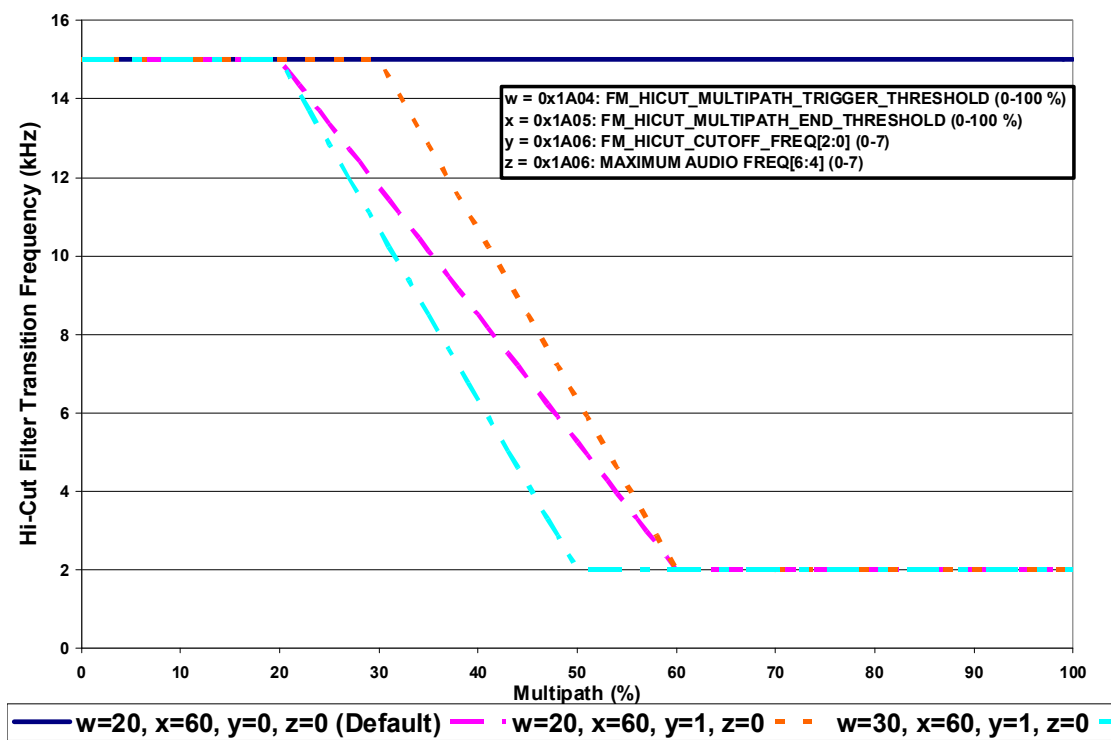


Figure 8. HiCut Controlled by Multipath Metric

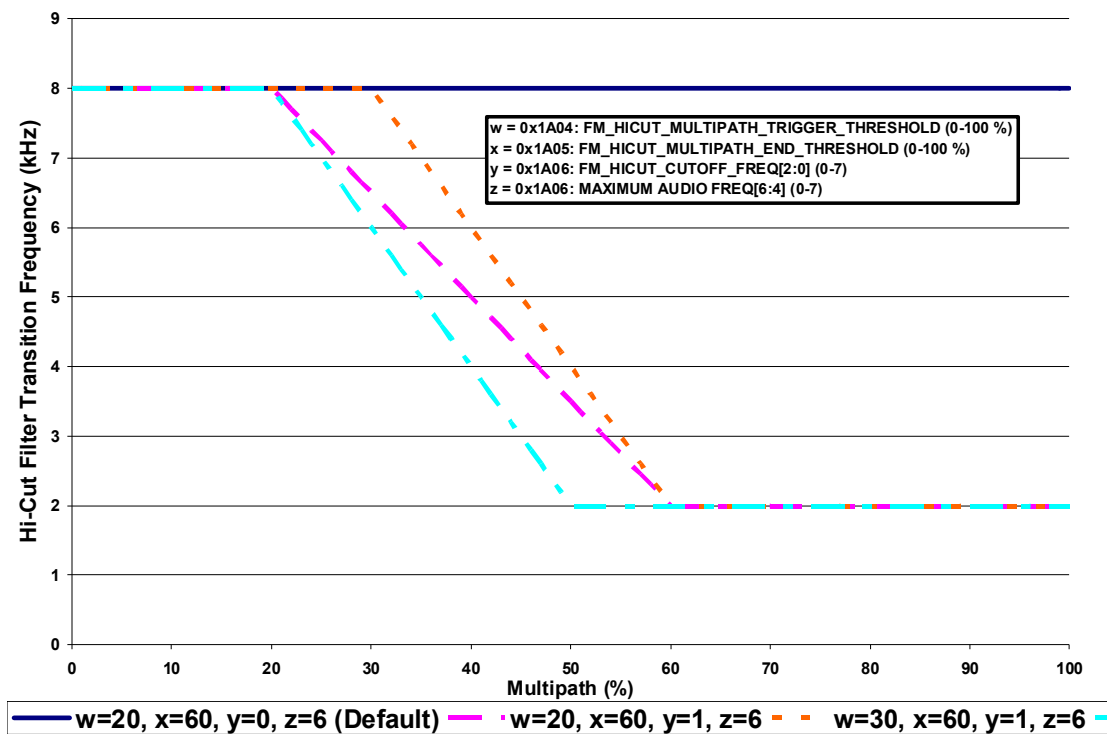


Figure 9. HiCut Controlled by Multipath Metric with Maximum Audio Frequency 8 kHz

Property 0x4000. RX_VOLUME

Sets the audio output volume. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 63.

Available in: All

Default: 0x003F

Step: 1

Range: 0–63

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----------|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | VOL[5:0] | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:6 | Reserved | Always write to 0. |
| 5:0 | VOL | Output Volume. Sets the output volume level, 63 max, 0 min. Default is 63. |

Property 0x4001. RX_HARD_MUTE

Mutes the audio output. L and R audio outputs may be muted independently. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is unmute (0x0000).

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|-------|-------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | LMUTE | RMUTE |

| Bit | Name | Function |
|------|----------|-----------------------|
| 15:2 | Reserved | Always write to 0. |
| 1 | LMUTE | Mutes L Audio Output. |
| 0 | RMUTE | Mutes R Audio Output. |

5.2. Commands and Properties for the AM/SW/LW Receiver (Si4730/31/32/34/35)

AM (Medium Wave), SW (Short Wave), and LW (Long Wave) use the same AM_SW_LW component, thus the commands and properties for these functions are the same. For simplicity reason, the commands and properties only have a prefix AM instead of AM_SW_LW. The main difference among AM, SW, and LW is on the frequency range.

The common frequency range and spacing for AM/SW/LW are:

- SW 2.3 MHz to 23 MHz in 5 kHz frequency spacing
- AM in US 520 kHz to 1.71 MHz in 10 kHz frequency spacing
- AM in Asia 522 kHz to 1.71 MHz in 9 kHz frequency spacing
- LW 153 kHz to 279 kHz in 9 kHz frequency spacing

Tables 8 and 9 summarize the commands and properties for the AM/SW/LW Receiver components applicable to Si473x/4x.

Table 8. AM/LW/SW Receiver Command Summary

| Cmd | Name | Description | Available In |
|--|-----------------|--|--------------|
| 0x01 | POWER_UP | Power up device and mode selection. | All |
| 0x10 | GET_REV | Returns revision information on the device. | All |
| 0x11 | POWER_DOWN | Power down device. | All |
| 0x12 | SET_PROPERTY | Sets the value of a property. | All |
| 0x13 | GET_PROPERTY | Retrieves a property's value. | All |
| 0x14 | GET_INT_STATUS | Read interrupt status bits. | All |
| 0x15 | PATCH_ARGS* | Reserved command used for patch file downloads. | All |
| 0x16 | PATCH_DATA* | Reserved command used for patch file downloads. | All |
| 0x40 | AM_TUNE_FREQ | Tunes to a given AM frequency. | All |
| 0x41 | AM_SEEK_START | Begins searching for a valid frequency. | All |
| 0x42 | AM_TUNE_STATUS | Queries the status of the already issued AM_TUNE_FREQ or AM_SEEK_START command. | All |
| 0x43 | AM_RSQ_STATUS | Queries the status of the Received Signal Quality (RSQ) for the current channel. | All |
| 0x47 | AM_AGC_STATUS | Queries the current AGC settings. | All |
| 0x48 | AM_AGC_OVERRIDE | Overrides AGC settings by disabling and forcing it to a fixed value. | All |
| 0x80 | GPIO_CTL | Configures GPO1, 2, and 3 as output or Hi-Z. | All |
| 0x81 | GPIO_SET | Sets GPO1, 2, and 3 output level (low or high). | All |
| *Note: Commands PATCH_ARGS and PATCH_DATA are only used to patch firmware. For information on applying a patch file, see "7.2. Powerup from a Component Patch" on page 132. | | | |

Table 9. AM/SW/LW Receiver Property Summary

| Prop | Name | Description | Default | Available In |
|--------|--------------------------------------|---|---------|--|
| 0x0001 | GPO_IEN | Enables interrupt sources. | 0x0000 | All |
| 0x0102 | DIGITAL_OUTPUT_FORMAT | Configure digital audio outputs | 0x0000 | Si4705/06, Si4731/35, Si4730/34-D60 and later, Si4732 |
| 0x0104 | DIGITAL_OUTPUT_SAMPLE_RATE | Configure digital audio output sample rate | 0x0000 | Si4705/06, Si4731/35, Si4730/34-D60 and later, Si4732 |
| 0x0201 | REFCLK_FREQ | Sets frequency of reference clock in Hz. The range is 31130 to 34406 Hz, or 0 to disable the AFC. Default is 32768 Hz. | 0x8000 | All |
| 0x0202 | REFCLK_PRESCALE | Sets the prescaler value for RCLK input. | 0x0001 | All |
| 0x3100 | AM_DEEMPHASIS | Sets deemphasis time constant. Can be set to 50 μ s. Deemphasis is disabled by default. | 0x0000 | All |
| 0x3102 | AM_CHANNEL_FILTER ¹ | Selects the bandwidth of the channel filter for AM reception. The choices are 6, 4, 3, 2, 2.5, 1.8, or 1 (kHz). The default bandwidth is 2 kHz. | 0x0003 | All |
| 0x3103 | AM_AUTOMATIC_VOLUME_CONTROL_MAX_GAIN | Sets the maximum gain for automatic volume control. | 0x1543 | Si473x-D60 and later, Si4732 |
| 0x3104 | AM_MODE_AFC_SW_PULL_IN_RANGE | Sets the SW AFC pull-in range. | 0x21F7 | Si4734/35-D60 and later, Si4732 |
| 0x3105 | AM_MODE_AFC_SW_LOCK_IN_RANGE | Sets the SW AFC lock-in. | 0x2DF5 | Si4734/35-D60 and later, Si4732 |
| 0x3200 | AM_RSQ_INTERRUPTS | Configures interrupt related to Received Signal Quality metrics. All interrupts are disabled by default. | 0x0000 | All |
| 0x3201 | AM_RSQ_SNR_HIGH_THRESHOLD | Sets high threshold for SNR interrupt. | 0x007F | All |
| 0x3202 | AM_RSQ_SNR_LOW_THRESHOLD | Sets low threshold for SNR interrupt. | 0x0000 | All |
| 0x3203 | AM_RSQ_RSSI_HIGH_THRESHOLD | Sets high threshold for RSSI interrupt. | 0x007F | All |

Notes:

1. The 1 kHz option, 1.8 kHz option, and 100 Hz high-pass Line Noise Rejection filter are supported on Si473x-D60 and later devices and Si4732 device (AM_SW_LW component 3.0 or later).
The 2.5 kHz option is supported on Si473x-D60 and later devices and Si4732 devices (AM_SW_LW component 5.0 or later).
2. Component 1.0 incorrectly reports 0x06B9 (1721 kHz) as default for AM_SEEK_BAND_TOP. After POWER_UP command is complete, set AM_SEEK_BAND_TOP to 0x06AE (1710 kHz) using the SET_PROPERTY command.

Table 9. AM/SW/LW Receiver Property Summary (Continued)

| Prop | Name | Description | Default | Available In |
|--------|-------------------------------|---|---------|-----------------|
| 0x3204 | AM_RSQ_RSSI_LOW_THRESHOLD | Sets low threshold for RSSI interrupt. | 0x0000 | All |
| 0x3300 | AM_SOFT_MUTE_RATE | Sets the attack and decay rates when entering or leaving soft mute. The default is 278 dB/s. | 0x0040 | All |
| 0x3301 | AM_SOFT_MUTE_SLOPE | Sets the AM soft mute slope. Default value is a slope of 1. | 0x0002 | Si4730/31/34/35 |
| | | | 0x0001 | All others |
| 0x3302 | AM_SOFT_MUTE_MAX_ATTENUATION | Sets maximum attenuation during soft mute (dB). Set to 0 to disable soft mute. Default is 8 dB. | 0x0010 | Si4730/31/34/35 |
| | | | 0x0008 | All others |
| 0x3303 | AM_SOFT_MUTE_SNR_THRESHOLD | Sets SNR threshold to engage soft mute. Default is 8 dB. | 0x000A | Si4730/31/34/35 |
| | | | 0x0008 | All others |
| 0x3400 | AM_SEEK_BAND_BOTTOM | Sets the bottom of the AM band for seek. Default is 520. | 0x0208 | All |
| 0x3401 | AM_SEEK_BAND_TOP ² | Sets the top of the AM band for seek. Default is 1710. | 0x06AE | All |
| 0x3402 | AM_SEEK_FREQ_SPACING | Selects frequency spacing for AM seek. Default is 10 kHz spacing. | 0x000A | All |
| 0x3403 | AM_SEEK_SNR_THRESHOLD | Sets the SNR threshold for a valid AM Seek/Tune. If the value is zero then SNR threshold is not considered when doing a seek. Default value is 5 dB. | 0x0005 | All |
| 0x3404 | AM_SEEK_RSSI_THRESHOLD | Sets the RSSI threshold for a valid AM Seek/Tune. If the value is zero then RSSI threshold is not considered when doing a seek. Default value is 25 dBμV. | 0x0019 | All |
| 0x4000 | RX_VOLUME | Sets the output volume. | 0x003F | All |
| 0x4001 | RX_HARD_MUTE | Mutes the L and R audio outputs. | 0x0000 | All |

Notes:

1. The 1 kHz option, 1.8 kHz option, and 100 Hz high-pass Line Noise Rejection filter are supported on Si473x-D60 and later devices and Si4732 device (AM_SW_LW component 3.0 or later).
The 2.5 kHz option is supported on Si473x-D60 and later devices and Si4732 devices (AM_SW_LW component 5.0 or later).
2. Component 1.0 incorrectly reports 0x06B9 (1721 kHz) as default for AM_SEEK_BAND_TOP. After POWER_UP command is complete, set AM_SEEK_BAND_TOP to 0x06AE (1710 kHz) using the SET_PROPERTY command.

Table 10. Status Response for the AM/SW/LW Receiver

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

| Bit | Name | Function |
|-----|----------|---|
| 7 | CTS | Clear to Send. 0 = Wait before sending next command. 1 = Clear to send next command. |
| 6 | ERR | Error. 0 = No error 1 = Error |
| 5:4 | Reserved | Values may vary. |
| 3 | RSQINT | Received Signal Quality Interrupt. 0 = Received Signal Quality measurement has not been triggered. 1 = Received Signal Quality measurement has been triggered. |
| 2:1 | Reserved | Values may vary. |
| 0 | STCINT | Seek/Tune Complete Interrupt. 0 = Tune complete has not been triggered. 1 = Tune complete has been triggered. |

5.2.1. AM/SW/LW Receiver Commands

Command 0x01. POWER_UP

Initiates the boot process to move the device from powerdown to powerup mode. The boot can occur from internal device memory or a system controller downloaded patch. To confirm that the patch is compatible with the internal device library revision, the library revision should be confirmed by issuing the POWER_UP command with FUNC = 15 (query library ID). The device returns the response, including the library revision, and then moves into powerdown mode. The device can then be placed in powerup mode by issuing the POWER_UP command with FUNC = 1 (AM/SW/LW Receive) and the patch may be applied. See Section "7.2. Powerup from a Component Patch" on page 132 for more information.

The POWER_UP command configures the state of ROUT (pin 13, Si4732 pin 16) and LOUT (pin 14, Si4732 pin 1) for analog audio mode and GPO2/INT (pin 18, Si4732 pin 3) for interrupt operation. For the Si4731/32/35, the POWER_UP command also configures the state of GPO3/DCLK (pin 17, Si4732 pin 2), DFS (pin 16, Si4732 pin 1), and DOUT (pin 15, Si4732 pin 16) for digital audio mode. The command configures GPO2/INT interrupts (GPO2OEN) and CTS interrupts (CTSIEN). If both are enabled, GPO2/INT is driven high during normal operation and low for a minimum of 1 μ s during the interrupt. The CTSIEN bit is duplicated in the GPO_IEN property. The command is complete when the CTS bit (and optional interrupt) is set.

Note: To change function (e.g. AM/SW/LW RX to FM RX), issue POWER_DOWN command to stop current function; then, issue POWER_UP to start new function.

Note: Delay at least 500 ms between powerup command and first tune command to wait for the oscillator to stabilize if XOSCEN is set and crystal is used as the RCLK.

Available in: All

Command Arguments: Two

Response Bytes: None (FUNC = 1), Seven (FUNC = 15)

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-------------|---------|-------|--------|-----------|----|----|----|
| CMD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | CTSIEN | GPO2OEN | PATCH | XOSCEN | FUNC[3:0] | | | |
| ARG2 | OPMODE[7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|---------|--|
| 1 | 7 | CTSIEN | CTS Interrupt Enable. 0 = CTS interrupt disabled. 1 = CTS interrupt enabled. |
| 1 | 6 | GPO2OEN | GPO2 Output Enable. 0 = GPO2 output disabled (Hi-Z). 1 = GPO2 output enabled. |
| 1 | 5 | PATCH | Patch Enable. 0 = Boot normally 1 = Copy NVM to RAM, but do not boot. After CTS has been set, RAM may be patched. |

| ARG | Bit | Name | Function |
|-----|-----|-------------|--|
| 1 | 4 | XOSCEN | Crystal Oscillator Enable. 0 = Use external RCLK (crystal oscillator disabled). 1 = Use crystal oscillator (RCLK and GPO3/DCLK with external 32.768 kHz crystal and OPMODE = 00000101). See Si473x Data Sheet Application Schematic for external BOM details. |
| 1 | 3:0 | FUNC[3:0] | Function. 0 = Reserved. 1 = AM/SW/LW Receive. 2–14 = Reserved. 15 = Query Library ID. |
| 2 | 7:0 | OPMODE[7:0] | Application Setting 00000101 = Analog audio outputs (LOUT/ROUT). 00001011 = Digital audio output (DCLK, LOUT/DFS, ROUT/DIO)(Si4731/32/35/37 only with XOSCEN = 0) 10110000 = Digital audio outputs (DCLK, DFS, DIO) (Si4731/35/37 only with XOSCEN = 0). 10110101 = Analog and digital audio outputs (LOUT/ROUT and DCLK, DFS, DIO) (Si4731/35 only with XOSCEN = 0). |

Response (to FUNC = 1, AM Receive)

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

Response (to FUNC = 15, Query Library ID)

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|----------------|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |
| RESP1 | PN[7:0] | | | | | | | |
| RESP2 | FWMAJOR[7:0] | | | | | | | |
| RESP3 | FWMINOR[7:0] | | | | | | | |
| RESP4 | RESERVED[7:0] | | | | | | | |
| RESP5 | RESERVED[7:0] | | | | | | | |
| RESP6 | CHIPREV[7:0] | | | | | | | |
| RESP7 | LIBRARYID[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|----------------|---|
| 1 | 7:0 | PN[7:0] | Final 2 digits of part number (HEX). |
| 2 | 7:0 | FWMAJOR[7:0] | Firmware Major Revision (ASCII). |
| 3 | 7:0 | FWMINOR[7:0] | Firmware Minor Revision (ASCII). |
| 4 | 7:0 | RESERVED[7:0] | Reserved, various values. |
| 5 | 7:0 | RESERVED[7:0] | Reserved, various values. |
| 6 | 7:0 | CHIPREV[7:0] | Chip Revision (ASCII). |
| 7 | 7:0 | LIBRARYID[7:0] | Library Revision (HEX). |

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Command 0x10. GET_REV

Returns the part number, chip revision, firmware revision, patch revision and component revision numbers. The command is complete when the CTS bit (and optional interrupt) is set. This command may only be sent when in powerup mode.

Available in: All

Command arguments: None

Response bytes: Eight

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|--------------------------|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |
| RESP1 | PN[7:0] | | | | | | | |
| RESP2 | FWMAJOR[7:0] | | | | | | | |
| RESP3 | FWMINOR[7:0] | | | | | | | |
| RESP4 | PATCH _H [7:0] | | | | | | | |
| RESP5 | PATCH _L [7:0] | | | | | | | |
| RESP6 | CMPMAJOR[7:0] | | | | | | | |
| RESP7 | CMPMINOR[7:0] | | | | | | | |
| RESP8 | CHIPREV[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------|---|
| 1 | 7:0 | PN[7:0] | Final 2 digits of Part Number (HEX). |
| 2 | 7:0 | FWMAJOR[7:0] | Firmware Major Revision (ASCII). |
| 3 | 7:0 | FWMINOR[7:0] | Firmware Minor Revision (ASCII). |
| 4 | 7:0 | PATCH _H [7:0] | Patch ID High Byte (HEX). |
| 5 | 7:0 | PATCH _L [7:0] | Patch ID Low Byte (HEX). |
| 6 | 7:0 | CMPMAJOR[7:0] | Component Major Revision (ASCII). |
| 7 | 7:0 | CMPMINOR[7:0] | Component Minor Revision (ASCII). |
| 8 | 7:0 | CHIPREV[7:0] | Chip Revision (ASCII). |

Command 0x11. POWER_DOWN

Moves the device from powerup to powerdown mode. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. Note that only the POWER_UP command is accepted in powerdown mode. **If the system controller writes a command other than POWER_UP when in powerdown mode, the device does not respond. The device will only respond when a POWER_UP command is written. GPO pins are powered down and not active during this state. For optimal power down current, GPO2 must be either internally driven low through GPIO_CTL command or externally driven low.**

Note: In AMRX component 1.0, a reset is required when the system controller writes a command other than POWER_UP when in powerdown mode.

Note: The following describes the state of all the pins when in powerdown mode:
 GPIO1, GPIO2, GPIO3 = 0
 ROUT, LOUT, DOUT, DFS = HiZ

Available in: All

Command arguments: None

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

Command 0x12. SET_PROPERTY

Sets a property shown in Table 9, “AM/SW/LW Receiver Property Summary,” on page 69. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. See Figure 25, “CTS and SET_PROPERTY Command Complete tCOMP Timing Model,” on page 143 and Table 32, “Command Timing Parameters for the AM Receiver,” on page 145.

Available in: All

Command Arguments: Five

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|--------------------------|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG2 | PROP _H [7:0] | | | | | | | |
| ARG3 | PROP _L [7:0] | | | | | | | |
| ARG4 | PROPD _H [7:0] | | | | | | | |
| ARG5 | PROPD _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|--------------------------|--|
| 1 | 7:0 | Reserved | Always write to 0. |
| 2 | 7:0 | PROP _H [7:0] | Property High Byte. This byte in combination with PROP _L is used to specify the property to modify. See Section "5.2.2. AM/SW/LW Receiver Properties" on page 89. |
| 3 | 7:0 | PROP _L [7:0] | Property Low Byte. This byte in combination with PROP _H is used to specify the property to modify. See Section "5.2.2. AM/SW/LW Receiver Properties" on page 89. |
| 4 | 7:0 | PROPD _H [7:0] | Property Value High Byte. This byte in combination with PROPD _L is used to set the property value. See Section "5.2.2. AM/SW/LW Receiver Properties" on page 89. |
| 5 | 7:0 | PROPD _L [7:0] | Property Value Low Byte. This byte in combination with PROPD _H is used to set the property value. See Section "5.2.2. AM/SW/LW Receiver Properties" on page 89. |

Command 0x13. GET_PROPERTY

Gets a property shown in Table 9, “AM/SW/LW Receiver Property Summary,” on page 69. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Available in: All

Command arguments: Three

Response bytes: Three

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-------------------------|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG2 | PROP _H [7:0] | | | | | | | |
| ARG3 | PROP _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|-------------------------|---|
| 1 | 7:0 | Reserved | Always write to 0. |
| 2 | 7:0 | PROP _H [7:0] | Property High Byte. This byte in combination with PROP _L is used to specify the property to get. |
| 3 | 7:0 | PROP _L [7:0] | Property Low Byte. This byte in combination with PROP _H is used to specify the property to get. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|--------------------------|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |
| RESP1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| RESP2 | PROPD _H [7:0] | | | | | | | |
| RESP3 | PROPD _L [7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------|---|
| 1 | 7:0 | Reserved | Always returns 0. |
| 2 | 7:0 | PROPD _H [7:0] | Property Value High Byte. This byte in combination with PROPD _L represents the requested property value. |
| 3 | 7:0 | PROPD _L [7:0] | Property Value High Byte. This byte in combination with PROPD _H represents the requested property value. |

Command 0x14. GET_INT_STATUS

Updates bits 6:0 of the status byte. This command should be called after any command that sets the STCINT or RSQINT bits. When polling this command should be periodically called to monitor the STATUS byte, and when using interrupts, this command should be called after the interrupt is set to update the STATUS byte. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be set when in powerup mode.

Available in: All

Command arguments: None

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

Command 0x40. AM_TUNE_FREQ

Tunes the AM/SW/LW receive to a frequency between 149 and 23 MHz in 1 kHz steps. In AM only mode, the valid frequency is between 520 and 1710 kHz in 1 kHz steps. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The ERR bit (and optional interrupt) is set if an invalid argument is sent. Note that only a single interrupt occurs if both the CTS and ERR bits are set. The optional STC interrupt is set when the command completes. The STCINT bit is set only after the GET_INT_STATUS command is called. This command may only be sent when in powerup mode. The command clears the STC bit if it is already set. See Figure 24, “CTS and STC Timing Model,” on page 142 and Table 32, “Command Timing Parameters for the AM Receiver,” on page 145.

AM: LO frequency is 45 kHz above RF for RF frequencies ≤ 1000 kHz and 45 kHz below RF for RF frequencies > 1000 kHz. For example, LO frequency is 945 kHz when tuning to 900 kHz.

Note: FAST bit is supported in Si473x-D60 and later devices and Si4732 device (AMRX component 3.0 or later).
ANTCAP bits are supported in AMRX component 2.0 or later (all devices).

Available in: All

Command arguments: Five

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-------------------------|----|----|----|----|----|----|------|
| CMD | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST |
| ARG2 | FREQ _H [7:0] | | | | | | | |
| ARG3 | FREQ _L [7:0] | | | | | | | |

| | |
|-------------|----------------------------|
| ARG4 | ANTCAP _H [15:8] |
| ARG5 | ANTCAP _L [7:0] |

| ARG | Bit | Name | Function |
|-----|------|-------------------------------|---|
| 1 | 7:1 | Reserved | Always write to 0. |
| 1 | 0 | FAST | FAST Tuning. If set, executes fast and invalidated tune. The tune status will not be accurate. |
| 2 | 7:0 | FREQ _H [7:0] | Tune Frequency High Byte. This byte in combination with FREQ _L selects the tune frequency in kHz. In AM/SW/LW mode, the valid range is from 149 to 23000 (149 kHz–23 MHz). In AM only mode the valid range is from 520 to 1710 (520–1710 kHz). |
| 3 | 7:0 | FREQ _L [7:0] | Tune Frequency Low Byte. This byte in combination with FREQ _H selects the tune frequency in kHz. In AM/SW/LW mode, the valid range is from 149 to 23000 (149 kHz–23 MHz). In AM only mode the valid range is from 520 to 1710 (520–1710 kHz). |
| 4 | 15:8 | ANTCAP _H [15:8] | Antenna Tuning Capacitor High Byte. This byte in combination with ANTCAP _L selects the tuning capacitor value. If both bytes are set to zero, the tuning capacitor value is selected automatically. If the value is set to anything other than 0, the tuning capacitance is manually set as 95 fF x ANTCAP + 7 pF. ANTCAP manual range is 1–6143. Automatic capacitor tuning is recommended. Note: In SW mode, ANTCAP _H [15:8] needs to be set to 0 and ANTCAP _L [7:0] needs to be set to 1. |
| 5 | 7:0 | ANTCAP _L [7:0] | Antenna Tuning Capacitor Low Byte. This byte in combination with ANTCAP _H selects the tuning capacitor value. If both bytes are set to zero, the tuning capacitor value is selected automatically. If the value is set to anything other than 0, the tuning capacitance is manually set as 95 fF x ANTCAP + 7 pF. ANTCAP manual range is 1–6143. Automatic capacitor tuning is recommended. Note: In SW mode, ANTCAP _H [15:8] needs to be set to 0 and ANTCAP _L [7:0] needs to be set to 1. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

Command 0x41. AM_SEEK_START

Initiates a seek for a channel that meets the RSSI and SNR criteria for AM. Clears any pending STCINT or RSQINT interrupt status. RSQINT is only cleared by the RSQ status command when the INTACK bit is set. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The ERR bit (and optional interrupt) is set if an invalid argument is sent. Note that only a single interrupt occurs if both the CTS and ERR bits are set. The optional STC interrupt is set when the command completes. The STCINT bit is set only after the GET_INT_STATUS command is called. This command may only be sent when in powerup mode. The command clears the STCINT bit if it is already set. See Figure 24, “CTS and STC Timing Model,” on page 142 and Table 32, “Command Timing Parameters for the AM Receiver,” on page 145.

Note: ANTCAP bits are supported in AMRX component 2.1 or later.

Available in: All

Command arguments: Five

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----------------------------|----|----|----|--------|------|----|----|
| CMD | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | SEEKUP | WRAP | 0 | 0 |
| ARG2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG4 | ANTCAP _H [15:8] | | | | | | | |
| ARG5 | ANTCAP _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|------|----------------------------|--|
| 1 | 7:4 | Reserved | Always write to 0. |
| 1 | 3 | SEEKUP | Seek Up/Down. Determines the direction of the search, either UP = 1, or DOWN = 0. |
| 1 | 2 | WRAP | Wrap/Halt. Determines whether the seek should Wrap = 1, or Halt = 0 when it hits the band limit. |
| 1 | 1:0 | Reserved | Always write to 0. |
| 2 | 7:0 | Reserved | Always write to 0. |
| 3 | 7:0 | Reserved | Always write to 0. |
| 4 | 15:8 | ANTCAP _H [15:8] | Antenna Tuning Capacitor High Byte. This byte in combination with ANTCAP _L selects the tuning capacitor value. If both bytes are set to zero, the tuning capacitor value is selected automatically. If the value is set to anything other than 0, the tuning capacitance is manually set as $95 \text{ fF} \times \text{ANTCAP} + 7 \text{ pF}$. ANTCAP manual range is 1–6143. Automatic capacitor tuning is recommended. Note: In SW mode, ANTCAP _H [15:8] needs to be set to 0 and ANTCAP _L [7:0] needs to be set to 1. |
| 5 | 7:0 | ANTCAP _L [7:0] | Antenna Tuning Capacitor Low Byte. This byte in combination with ANTCAP _H selects the tuning capacitor value. If both bytes are set to zero, the tuning capacitor value is selected automatically. If the value is set to anything other than 0, the tuning capacitance is manually set as $95 \text{ fF} \times \text{ANTCAP} + 7 \text{ pF}$. ANTCAP manual range is 1–6143. Automatic capacitor tuning is recommended. Note: In SW mode, ANTCAP _H [15:8] needs to be set to 0 and ANTCAP _L [7:0] needs to be set to 1. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

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Command 0x42. AM_TUNE_STATUS

Returns the status of AM_TUNE_FREQ or AM_SEEK_START commands. The command returns the current frequency, RSSI, SNR, and the antenna tuning capacitance value (0–6143). The command clears the STCINT interrupt bit when INTACK bit of ARG1 is set. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Note: AFCRL bit does not work properly on AMRX component 2.1 or earlier.

Available in: All

Command arguments: One

Response bytes: Seven

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|----|----|----|----|----|----|--------|--------|
| CMD | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | CANCEL | INTACK |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 7:2 | Reserved | Always write to 0. |
| 1 | 1 | CANCEL | Cancel seek. If set, aborts a seek currently in progress. |
| 1 | 0 | INTACK | Seek/Tune Interrupt Clear. If set, clears the seek/tune complete interrupt status indicator. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|--------------------------------|-----|----|----|--------|----|-------|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |
| RESP1 | BLTF | X | X | X | X | X | AFCRL | VALID |
| RESP2 | READFREQ _H [7:0] | | | | | | | |
| RESP3 | READFREQ _L [7:0] | | | | | | | |
| RESP4 | RSSI[7:0] | | | | | | | |
| RESP5 | SNR[7:0] | | | | | | | |
| RESP6 | READANTCAP _H [15:8] | | | | | | | |
| RESP7 | READANTCAP _L [7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------------|---|
| 1 | 7 | BLTF | Band Limit. Reports if a seek hit the band limit (WRAP = 0 in AM_START_SEEK) or wrapped to the original frequency (WRAP = 1). |
| 1 | 6:2 | Reserved | Always returns 0. |
| 1 | 1 | AFCRL | AFC Rail Indicator. Set if the AFC rails. |
| 1 | 0 | VALID | Valid Channel. Set if the channel is currently valid and would have been found during a seek. |
| 2 | 7:0 | READFREQ _H [7:0] | Read Frequency High Byte. This byte in combination with READFREQ _L returns frequency being tuned (kHz). |
| 3 | 7:0 | READFREQ _L [7:0] | Read Frequency Low Byte. This byte in combination with READFREQ _H returns frequency being tuned (kHz). |
| 4 | 7:0 | RSSI[7:0] | Received Signal Strength Indicator. This byte contains the receive signal strength when tune is completed (dBμV). |
| 5 | 7:0 | SNR[7:0] | SNR. This byte contains the SNR metric when tune is completed (dB). |
| 6 | 7:0 | READANTCAP _H [15:8] | Read Antenna Tuning Capacitor High Byte. This byte in combination with READANTCAP _L returns the current antenna tuning capacitor value. The tuning capacitance is 95 fF x READANTCAP + 7 pF. |
| 7 | 7:0 | READANTCAP _L [7:0] | Read Antenna Tuning Capacitor Low Byte. This byte in combination with READANTCAP _H returns the current antenna tuning capacitor value. The tuning capacitance is 95 fF x READANTCAP + 7 pF. |

Command 0x43. AM_RSQ_STATUS

Returns status information about the received signal quality. The command returns RSSI and SNR. It also indicates valid channel (VALID), soft mute engagement (SMUTE), and AFC rail status (AFCRL). This command can be used to check if the received signal is above the RSSI high threshold as reported by RSSIHINT, or below the RSSI low threshold as reported by RSSILINT. It can also be used to check if the signal is above the SNR high threshold as reported by SNRHINT, or below the SNR low threshold as reported by SNRLINT. The command clears the RSQINT, SNRHINT, SNRLINT, RSSIHINT, and RSSILINT interrupt bits when INTACK bit of ARG1 is set. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Note: AFCRL bit does not work properly on AMRX component 2.1 or earlier.

Available in: All

Command arguments: One

Response bytes: Five

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|----|----|----|--------|
| CMD | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | INTACK |

| ARG | Bit | Name | Function |
|-----|-----|--------|---|
| 1 | 0 | INTACK | Interrupt Acknowledge. 0 = Interrupt status preserved. 1 = Clears RSQINT, SNRHINT, SNRLINT, RSSIHINT, RSSILINT |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----------|-----|----|----|---------|---------|-----------|-----------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |
| RESP1 | X | X | X | X | SNRHINT | SNRLINT | RSSI-HINT | RSSIILINT |
| RESP2 | X | X | X | X | SMUTE | X | AFCRL | VALID |
| RESP3 | X | X | X | X | X | X | X | X |
| RESP4 | RSSI[7:0] | | | | | | | |
| RESP5 | SNR[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|-----------|---|
| 1 | 3 | SNRHINT | SNR Detect High. 0 = Received SNR has not exceeded above SNR high threshold. 1 = Received SNR has exceeded above SNR high threshold. |
| 1 | 2 | SNRLINT | SNR Detect Low. 0 = Received SNR has not exceeded below SNR low threshold. 1 = Received SNR has exceeded below SNR low threshold. |
| 1 | 1 | RSSIHINT | RSSI Detect High. 0 = RSSI has not exceeded above RSSI high threshold. 1 = RSSI has exceeded above RSSI high threshold. |
| 1 | 0 | RSSILINT | RSSI Detect Low. 0 = RSSI has not exceeded below RSSI low threshold. 1 = RSSI has exceeded below RSSI low threshold. |
| 2 | 3 | SMUTE | Soft Mute Indicator. Indicates soft mute is engaged. |
| 2 | 1 | AFCRL | AFC Rail Indicator. Set if the AFC rails. |
| 2 | 0 | VALID | Valid Channel. Set if the channel is currently valid and would have been found during a seek. |
| 4 | 7:0 | RSSI[7:0] | Received Signal Strength Indicator. Contains the current receive signal strength (dBμV). |
| 5 | 7:0 | SNR[7:0] | SNR. Contains the current SNR metric (dB). |

Command 0x47. AM_AGC_STATUS

Returns the AM AGC setting of the device. The command returns whether the AGC is enabled or disabled and it returns the gain index. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in power up mode.

Available in: All

Command arguments: None

Response bytes: Two

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|----|----|----|----|----|----|----|----|
| CMD | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|---------------|-----|----|----|--------|----|----|----------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |
| RESP1 | X | X | X | X | X | X | X | AMAGCDIS |
| RESP2 | AMAGCNDX[7:0] | | | | | | | |

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| RESP | Bit | Name | Function |
|------|-----|----------|---|
| 1 | 0 | AMAGCDIS | AM AGC Disable This bit indicates if the AGC is enabled or disabled. 0 = AGC enabled. 1 = AGC disabled. |
| 2 | 7:0 | AMAGCNDX | AM AGC Index This byte reports the current AGC gain index. 0 = Minimum attenuation (max gain) 1 – 36+ATTN_BACKUP = Intermediate attenuation 37+ATTN_BACKUP = Maximum attenuation (min gain) Note: The max index is subject to change. See Property 0x3705 AM_FRONTEND_AGC_CONTROL for details on ATTN_BACKUP. |

Command 0x48. AM_AGC_OVERRIDE

Overrides the AM AGC setting by disabling the AGC and forcing the gain index that ranges between 0 (minimum attenuation) and 37+ATTN_BACKUP (maximum attenuation). The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in power up mode.

Available in: All

Command arguments: Two

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|---------------|----|----|----|----|----|----|----------|
| CMD | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | AMAGCDIS |
| ARG2 | AMAGCNDX[7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 0 | AMAGCDIS | AM AGC Disable This bit selects whether the AGC is enabled or disabled. 0 = AGC enabled. 1 = AGC disabled. |
| 2 | 7:0 | AMAGCNDX | AM AGC Index If AMAGCDIS = 1, this byte forces the AGC gain index. 0 = Minimum attenuation (max gain) 1 – 36+ATTN_BACKUP = Intermediate attenuation 37+ATTN_BACKUP = Maximum attenuation (min gain) *Note: The max index is subject to change. See Property 0x3705 AM_FRONTEND_AGC_CONTROL for details on ATTN_BACKUP. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|--------|----|----|--------|
| STATUS | CTS | ERR | X | X | RSQINT | X | X | STCINT |

Command 0x80. GPIO_CTL

Enables output for GPO1, 2, and 3. GPO1, 2, and 3 can be configured for output (Hi-Z or active drive) by setting the GPO1OEN, GPO2OEN, and GPO3OEN bit. The state (high or low) of GPO1, 2, and 3 is set with the GPIO_SET command. To avoid excessive current consumption due to oscillation, GPO pins should not be left in a high impedance state. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. The default is all GPO pins set for high impedance.

Notes:

1. GPIO_CTL is supported in AM_SW_LW component 2.0 or later.
2. The use of GPO2 as an interrupt pin and/or the use of GPO3 as DCLK digital clock input will override this GPIO_CTL function for GPO2 and/or GPO3 respectively.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|---------|---------|---------|----|
| CMD | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | GPO3OEN | GPO2OEN | GPO1OEN | 0 |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 7:4 | Reserved | Always write 0. |
| 1 | 3 | GPO3OEN | GPO3 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 2 | GPO2OEN | GPO2 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 1 | GPO1OEN | GPO1 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 0 | Reserved | Always write 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|--------|--------|--------|
| STATUS | CTS | ERR | X | X | X | RDSINT | ASQINT | STCINT |

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Command 0x81. GPIO_SET

Sets the output level (high or low) for GPO1, 2, and 3. GPO1, 2, and 3 can be configured for output by setting the GPO1OEN, GPO2OEN, and GPO3OEN bit in the GPIO_CTL command. To avoid excessive current consumption due to oscillation, GPO pins should not be left in a high impedance state. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is all GPO pins set for high impedance.

Note: GPIO_SET is supported in AM_SW_LW component 2.0 or later.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|-----------|-----------|-----------|----|
| CMD | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | GPO3LEVEL | GPO2LEVEL | GPO1LEVEL | 0 |

| ARG | Bit | Name | Function |
|-----|-----|-----------|--|
| 1 | 7:4 | Reserved | Always write 0. |
| 1 | 3 | GPO3LEVEL | GPO3 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 2 | GPO2LEVEL | GPO2 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 1 | GPO1LEVEL | GPO1 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 0 | Reserved | Always write 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|--------|--------|--------|
| STATUS | CTS | ERR | X | X | X | RDSINT | ASQINT | STCINT |

5.2.2. AM/SW/LW Receiver Properties

Property 0x0001. GPO_IEN

Configures the sources for the GPO2/ $\overline{\text{INT}}$ interrupt pin. Valid sources are the lower 8 bits of the STATUS byte, including CTS, ERR, RSQINT, and STCINT bits. The corresponding bit is set before the interrupt occurs. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The CTS interrupt enable (CTSIEN) can be set with this property and the POWER_UP command. The state of the CTSIEN bit set during the POWER_UP command can be read by reading this property and modified by writing this property. This property may only be set or read when in powerup mode.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|--------|-----|----|--------|--------|--------|----|----|--------|----|----|--------|
| Name | 0 | 0 | 0 | 0 | RSQREP | 0 | 0 | STCREP | CTSIEN | ERRIEN | 0 | 0 | RSQIEN | 0 | 0 | STCIEN |

| Bit | Name | Function |
|-------|----------|---|
| 15:12 | Reserved | Always write to 0. |
| 11 | RSQREP | RSQ Interrupt Repeat. 0 = No interrupt generated when RSQINT is already set (default) 1 = Interrupt generated even if RSQINT is already set |
| 10:9 | Reserved | Always write to 0. |
| 8 | STCREP | STC Interrupt Repeat. 0 = No interrupt generated when STCINT is already set (default) 1 = Interrupt generated even if STCINT is already set |
| 7 | CTSIEN | CTS Interrupt Enable. After PowerUp, this bit reflects the CTSIEN bit in ARG1 of PowerUp Command. 0 = No interrupt generated when CTS is set 1 = Interrupt generated when CTS is set |
| 6 | ERRIEN | ERR Interrupt Enable. 0 = No interrupt generated when ERR is set (default) 1 = Interrupt generated when ERR is set |
| 5:4 | Reserved | Always write to 0. |
| 3 | RSQIEN | RSQ Interrupt Enable. 0 = No interrupt generated when RSQINT is set (default) 1 = Interrupt generated when RSQINT is set |
| 2:1 | Reserved | Always write to 0. |
| 0 | STCIEN | Seek/Tune Complete Interrupt Enable. 0 = No interrupt generated when STCINT is set (default) 1 = Interrupt generated when STCINT is set |

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Property 0x0102. DIGITAL_OUTPUT_FORMAT

Configures the digital audio output format. Configuration options include DCLK edge, data format, force mono, and sample precision.

Note: DIGITAL_OUTPUT_FORMAT is supported in AM_SW_LW component 2.0 or later.

Available in: Si4705/06, Si4731/32/35, Si4730/34-D60 and later

Default: 0x0000

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|----|----|----|----|----|----|---|---|-------|------------|---|---|---|------------|---|---|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OFALL | OMODE[3:0] | | | 0 | OSIZE[1:0] | | |

| Bit | Name | Function |
|------|------------|--|
| 15:8 | Reserved | Always write to 0. |
| 7 | OFALL | Digital Output DCLK Edge. 0 = use DCLK rising edge 1 = use DCLK falling edge |
| 6:3 | OMODE[3:0] | Digital Output Mode. 0000 = I ² S 0110 = Left-justified 1000 = MSB at second DCLK after DFS pulse 1100 = MSB at first DCLK after DFS pulse |
| 2 | Reserved | Always write to 0. |
| 1:0 | OSIZE[1:0] | Digital Output Audio Sample Precision. 0 = 16-bits 1 = 20-bits 2 = 24-bits 3 = 8-bits |

Property 0x0104. DIGITAL_OUTPUT_SAMPLE_RATE

Enables digital audio output and configures digital audio output sample rate in samples per second (sps). When DOSR[15:0] is 0, digital audio output is disabled. To enable digital audio output, program DOSR[15:0] with the sample rate in samples per second. The over-sampling rate must be set in order to satisfy a minimum DCLK of 1 MHz. **The system controller must establish DCLK and DFS prior to enabling the digital audio output else the device will not respond and will require reset. The sample rate must be set to 0 before DCLK/DFS is removed. AM_TUNE_FREQ command must be sent after the POWER_UP command to start the internal clocking before setting this property.**

Note: DIGITAL_OUTPUT_SAMPLE_RATE is supported in AM_SW_LW component 2.0 or later.

Available in: Si4705/06, Si4731/32/35, Si4730/34-D60 and later

Default: 0x0000 (digital audio output disabled)

Units: sps

Range: 32–48 ksps, 0 to disable digital audio output

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Name | DOSR[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|------------|--|
| 15:0 | DOSR[15:0] | Digital Output Sample Rate. 32–48 ksps. 0 to disable digital audio output. |

Property 0x0201. REFCLK_FREQ

Sets the frequency of the REFCLK from the output of the prescaler. The REFCLK range is 31130 to 34406 Hz (32768 5% Hz) in 1 Hz steps, or 0 (to disable AFC). For example, an RCLK of 13MHz would require a prescaler value of 400 to divide it to 32500 Hz REFCLK. The reference clock frequency property would then need to be set to 32500 Hz. RCLK frequencies between 31130 Hz and 40 MHz are supported, however, there are gaps in frequency coverage for prescaler values ranging from 1 to 10, or frequencies up to 311300 Hz. The following table summarizes these RCLK gaps.

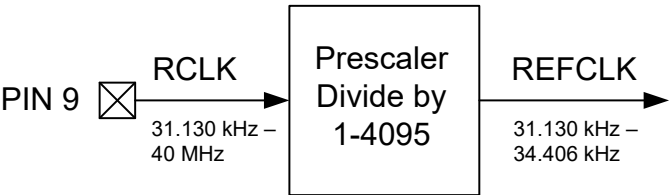


Figure 10. REFCLK Prescaler

Table 11. RCLK Gaps

| Prescaler | RCLK Low (Hz) | RCLK High (Hz) |
|-----------|---------------|----------------|
| 1 | 31130 | 34406 |
| 2 | 62260 | 68812 |
| 3 | 93390 | 103218 |
| 4 | 124520 | 137624 |
| 5 | 155650 | 172030 |
| 6 | 186780 | 206436 |
| 7 | 217910 | 240842 |
| 8 | 249040 | 275248 |
| 9 | 280170 | 309654 |
| 10 | 311300 | 344060 |

The RCLK must be valid 10 ns before and 10 ns after completing the AM_TUNE_FREQ command. In addition, the RCLK must be valid at all times when the carrier is enabled for proper AGC operation. The RCLK may be removed or reconfigured at other times. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. The default is 32768 Hz.

Available in: All
Default: 0x8000 (32768)
Units: 1 Hz
Step: 1Hz
Range: 31130-34406

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | REFCLKF[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|---------------|---|
| 15:0 | REFCLKF[15:0] | Frequency of Reference Clock in Hz. The allowed REFCLK frequency range is between 31130 and 34406 Hz (32768 5%), or 0 (to disable AFC). |

Property 0x0202. REFCLK_PRESCALE

Sets the number used by the prescaler to divide the external RCLK down to the internal REFCLK. The range may be between 1 and 4095 in 1 unit steps. For example, an RCLK of 13 MHz would require a prescaler value of 400 to divide it to 32500 Hz. The reference clock frequency property would then need to be set to 32500 Hz. The RCLK must be valid 10 ns before sending and 20 ns after completing the AM_TUNE_FREQ and AM_SEEK_START commands. In addition, the RCLK must be valid at all times for proper AFC operation. The RCLK may be removed or reconfigured at other times. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 1.

Available in: All

Default: 0x0001

Step: 1

Range: 1–4095

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|----------|-------------|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | RCLK SEL | RCLKP[11:0] | | | | | | | | | | | |

| Bit | Name | Function |
|-------|-------------|--|
| 15:13 | Reserved | Always write to 0. |
| 12 | RCLKSEL | RCLKSEL. 0 = RCLK pin is clock source. 1 = DCLK pin is clock source. |
| 11:0 | RCLKP[11:0] | Prescaler for Reference Clock. Integer number used to divide the RCLK frequency down to REFCLK frequency. The allowed REFCLK frequency range is between 31130 and 34406* Hz (32768 \pm 5%), or 0 (to disable AFC). |

***Note:** For shortwave frequencies, choose a prescaler value such that you can limit the REFCLK frequency range to 31130–32768* Hz.

Property 0x3100. AM_DEEMPHASIS

Sets the AM Receive de-emphasis to 50 μ s. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is disabled.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|--------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DEEMPH |

| Bit | Name | Function |
|------|----------|--|
| 15:1 | Reserved | Always write to 0. |
| 0 | DEEMPH | AM De-Emphasis. 1 = 50 μ s. 0 = Disabled. |

Property 0x3102. AM_CHANNEL_FILTER

Selects the bandwidth of the AM channel filter. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 2 kHz bandwidth channel filter.

Note: The 1 kHz option, 1.8 kHz option, and 100 Hz high-pass Line Noise Rejection filter are supported on Si473x-D60 and later devices and Si4732 device (AM_SW_LW component 3.0 or later). The 2.5 kHz option is supported on Si473x-D60 and later devices and Si4732 devices (AM_SW_LW component 5.0 or later).

Available in: All

Default: 0x0003

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|---------|----|----|----|----|---------------|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | AMPLFLT | 0 | 0 | 0 | 0 | AMCHFLT[03:0] | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:9 | Reserved | Always write to 0. |
| 8 | AMPLFLT | Enables the AM Power Line Noise Rejection Filter |
| 7:4 | Reserved | Always write to 0. |
| 3:0 | AMCHFILT | AM Channel Filter. Selects the bandwidth of the AM channel filter. The following choices are available: 0 = 6 kHz Bandwidth 1 = 4 kHz Bandwidth 2 = 3 kHz Bandwidth 3 = 2 kHz Bandwidth 4 = 1 kHz Bandwidth 5 = 1.8 kHz Bandwidth 6 = 2.5 kHz Bandwidth, gradual roll off 7–15 = Reserved (Do not use) |

Property 0x3103. AM_AUTOMATIC_VOLUME_CONTROL_MAX_GAIN

Sets the maximum gain for automatic volume control. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 16 dB.

The maximum AVC gain affects audio output level, especially under weak signal conditions. It amplifies the signal as well as noise. When a signal is very weak (needs a lot of gain) then the maximum gain will be applied, and may make the noise too harsh for the listener, even the soft mute functions. The user can reduce the noise further by adjusting the maximum AVC gain. The property allows the user to optimize the trade-off between maintaining output level and suppressing noise.

Note: The maximum AVC gain is 90.3 dB. This would be equivalent to AM_AUTOMATIC_VOLUME_CONTROL_MAX_GAIN property value 0x7800, which is the maximum value.

Available in: Si473x-D60 and later, Si4732

Default: 0x1543 (Si473x-D60 and later, Si4732)

Step: 1

Range: 0X1000 ~ 0x7800

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|--------------------|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | AVC_MAXGAIN [14:0] | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-------------|---|
| 15 | Reserved | Always write to 0. |
| 14:0 | AVC_MAXGAIN | Automatic Volume Control Max Gain. Maximum gain for automatic volume control. The max gain value is given by $AVC_MAXGAIN = g * 340.2$ where g is the desired maximum AVC gain in dB. Minimum of 12 dB is recommend when SOFTMUTE is enabled. |

Property 0x3104. AM_MODE_AFC_SW_PULL_IN_RANGE

Sets the SW AFC pull-in or tracking range. The value PULL_IN_RANGE is relative to the tuned frequency and is specified as $1/(PPM \times 10^{-6})$. For example to program a pull-in range of 115 ppm, $PULL_IN_RANGE = 1/(115 \times 10^{-6}) = 8695$. The command is complete when the CTS bit (and optional interrupt) is set.

Available in: Si4734/35-D60 and later, Si4732

Default: 0x21F7 (115 ppm)

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | SWPIR[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-------------|--|
| 15:0 | SWPIR[15:0] | SW Pull-In Range The SW pull-in range expressed relative to the tuned frequency. |

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Property 0x3105. AM_MODE_AFC_SW_LOCK_IN_RANGE

Sets the SW AFC lock-in or capture range. The value LOCK_IN_RANGE is relative to the tuned frequency and is specified as $1/(PPM \times 10^{-6})$. For example to program a lock-in range of 85 ppm, $LOCK_IN_RANGE = 1/(85 \times 10^{-6}) = 11765$. The command is complete when the CTS bit (and optional interrupt) is set.

Available in: Si4734/35-D60 and later, Si4732

Default: 0x2DF5 (85 ppm)

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | SWPIR[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-------------|--|
| 15:0 | SWPIR[15:0] | SW Pull-In Range The SW lock-in range expressed relative to the tuned frequency. |

Property 0x3200. AM_RSQ_INT_SOURCE

Configures interrupt related to Received Signal Quality metrics. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|--------|--------|--------|---------|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNRHIE | SNRLIE | RSSIHI | RSSILIE |

| Bit | Name | Function |
|------|----------|---|
| 15:4 | Reserved | Always write 0. |
| 3 | SNRHIE | Interrupt Source Enable: SNR High. Enable SNR high as the source of interrupt which the threshold is set by AM_RSQ_SNR_HI_THRESHOLD. |
| 2 | SNRLIE | Interrupt Source Enable: SNR Low. Enable SNR low as the as the source of interrupt which the threshold is set by AM_RSQ_SNR_LO_THRESHOLD. |
| 1 | RSSIHI | Interrupt Source Enable: RSSI High. Enable RSSI low as the source of interrupt which the threshold is set by AM_RSQ_RSSI_HI_THRESHOLD. |
| 0 | RSSILIE | Interrupt Source Enable: RSSI Low. Enable RSSI low as the source of interrupt which the threshold is set by AM_RSQ_RSSI_LO_THRESHOLD. |

Property 0x3201. AM_RSQ_SNR_HI_THRESHOLD

Sets high threshold which triggers the RSQ interrupt if the SNR is above this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 127 dB.

Available in: All
 Default: 0x007F
 Units: dB
 Step: 1
 Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNRH[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | SNRH | AM RSQ SNR High Threshold. Threshold which triggers the RSQ interrupt if the SNR goes above this threshold. Specified in units of dB in 1 dB steps (0–127). Default is 0 dB. |

Property 0x3202. AM_RSQ_SNR_LO_THRESHOLD

Sets low threshold which triggers the RSQ interrupt if the SNR is below this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0 dB.

Available in: All
 Default: 0x0000
 Units: dB
 Step: 1
 Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|-----------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SNRL[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | SNRL | AM RSQ SNR Low Threshold. Threshold which triggers the RSQ interrupt if the SNR goes below this threshold. Specified in units of dB in 1 dB steps (0–127). Default is 0 dB. |

Property 0x3203. AM_RSQ_RSSI_HI_THRESHOLD

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Sets high threshold which triggers the RSQ interrupt if the RSSI is above this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 127 dB.

Available in: All

Default: 0x007F

Units: dBμV

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RSSIH[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | RSSIH | AM RSQ RSSI High Threshold. Threshold which triggers the RSQ interrupt if the RSSI goes above this threshold. Specified in units of dBμV in 1 dB steps (0–127). Default is 0 dBμV. |

Property 0x3204. AM_RSQ_RSSI_LO_THRESHOLD

Sets low threshold which triggers the RSQ interrupt if the RSSI is below this threshold. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 0 dB.

Available in: All

Default: 0x0000

Units: dBμV

Step: 1

Range: 0–127

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|------------|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RSSIL[6:0] | | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:7 | Reserved | Always write to 0. |
| 6:0 | RSSIL | AM RSQ RSSI Low Threshold. Threshold which triggers the RSQ interrupt if the RSSI goes below this threshold. Specified in units of dBμV in 1 dB steps (0–127). Default is 0 dBμV. |

Property 0x3300. AM_SOFT_MUTE_RATE

Sets the attack and decay rates when entering or leaving soft mute. The value specified is multiplied by 4.35 dB/s to come up with the actual attack rate. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default rate is 278 dB/s.

Available in: All

Default: 0x0040

Actual Rate: SMRATE x 4.35

Units: dB/s

Step: 1

Range: 1–255

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|--------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | SMRATE[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|--------|---|
| 15:0 | SMRATE | AM Soft Mute Rate. Determines how quickly the AM goes into soft mute when soft mute is enabled. The actual rate is calculated by taking the value written to the field and multiplying it with 4.35 dB/s. The default rate is 278 dB/s (SMRATE[15:0] = 0x0040). |

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Property 0x3400. AM_SEEK_BAND_BOTTOM

Sets the lower boundary for the AM band in kHz. This value is used to determine when the lower end of the AM band is reached when performing a seek. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 520 kHz (0x0208).

Available in: All

Default: 0x0208

Units: kHz

Step: 1 kHz

Valid Range: 149–23000 kHz

Recommended Range:

- AM in US: 520–1710 kHz
- AM in Asia: 522–1710 kHz
- SW: 2300–23000 kHz
- LW: 153–279 kHz

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | AMSKFREQL[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-----------|--|
| 15:0 | AMSKFREQL | AM Seek Band Bottom. Specify the lower boundary of the AM band when performing a seek. The seek either stops at this limit or wraps based on the parameters of AM_SEEK_START command that was issued to initiate a seek. The default value for the lower boundary of the AM band is 520 kHz. |

Property 0x3401. AM_SEEK_BAND_TOP

Sets the upper boundary for the AM band in kHz. This value is used to determine when the higher end of the AM band is reached when performing a seek. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 1710 kHz (0x06AE).

Available in: All

Default: 0x06AE

Note: Firmware 1.0 incorrectly reports 0x06B9 (1721 kHz) as default for AM_SEEK_BAND_TOP. After POWER_UP command is complete, set AM_SEEK_BAND_TOP to 0x06AE (1710 kHz) using the SET_PROPERTY command.

Units: kHz

Step: 1 kHz

Valid Range: 149–23000 kHz

Recommended Range:

- AM in US: 520–1710 kHz
- AM in Asia: 522–1710 kHz
- SW: 2300–23000 kHz
- LW: 153–279 kHz

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | AMSKFREQH[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|-----------|---|
| 15:0 | AMSKFREQH | AM Seek Band Top. Specify the higher boundary of the AM band when performing a seek. The seek either stops at this limit or wraps based on the parameters of AM_SEEK_START command that was issued to initiate a seek. The default value for the upper boundary of the AM band is 1710 kHz. |

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Property 0x3402. AM_SEEK_FREQ_SPACING

Sets the frequency spacing for the AM Band when performing a seek. The frequency spacing determines how far the next tune is going to be from the currently tuned frequency. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default frequency spacing is 10 kHz.

Available in: All

Default: 0x000A

Units: kHz

Valid Values: 1 (1 kHz), 5 (5 kHz), 9 (9 kHz), and 10 (10 kHz).

Recommended Value:

- AM in US: 10 (10 kHz)
- AM in Asia: 9 (9 kHz)
- SW: 5 (5 kHz)
- LW: 9 (9 kHz)

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----------------|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | AMSKSPACE[3:0] | | | |

| Bit | Name | Function |
|------|-----------|---|
| 15:4 | Reserved | Always write to 0. |
| 3:0 | AMSKSPACE | AM Seek Frequency Spacing. Sets the frequency spacing when performing a seek in the AM band. The default frequency spacing is 10 kHz. |

Property 0x3403. AM_SEEK_TUNE_SNR_THRESHOLD

Sets the SNR threshold for a valid AM Seek/Tune. If the value is zero, then SNR is not used as a valid criteria when doing a seek for AM. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default threshold is 5 dB.

Available in: All

Default: 0x0005

Units: dB

Step: 1

Range: 0–63

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|--------------|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | AMSKSNR[5:0] | | | | | |

| Bit | Name | Function |
|------|----------|--|
| 15:6 | Reserved | Always write to 0. |
| 5:0 | AMSKSNR | AM Seek/Tune SNR Threshold. SNR Threshold which determines if a valid channel has been found during Seek/Tune. Specified in units of dB in 1 dB steps (0–63). Default threshold is 5 dB. |

Property 0x3404. AM_SEEK_TUNE_RSSI_THRESHOLD

Sets the RSSI threshold for a valid AM Seek/Tune. If the value is zero then RSSI is not used as a valid criteria when doing a seek for AM. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 25 dBμV.

Available in: All

Default: 0x0019

Units: dBμV

Step: 1

Range: 0–63

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|----|----|----|----|---------------|----|----|----|----|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | AMSKRSSI[5:0] | | | | | |

| Bit | Name | Function |
|------|----------|---|
| 15:6 | Reserved | Always write to 0. |
| 5:0 | AMSKRSSI | AM Seek/Tune Received Signal Strength Threshold. RSSI Threshold which determines if a valid channel has been found during Seek/Tune. Specified in units of dBμV in 1 dBμV steps (0–63). Default threshold is 25 dBμV. |

5.3. Commands and Properties for the Stereo Audio ADC Mode (Si4704/05/30/31)

The following two tables are the summary of the commands and properties for the Stereo Audio ADC component applicable to Si4704/05/30/31-D62.

Table 12. Stereo Audio ADC Mode Command Summary

| Cmd | Name | Description | Devices |
|--|----------------|--|---------|
| 0x01 | POWER_UP | Power-up device and mode selection. Modes include operational function and audio interface configuration | All |
| 0x10 | GET_REV | Returns the revision information on the device. | All |
| 0x11 | POWER_DOWN | Power-down device. | All |
| 0x12 | SET_PROPERTY | Sets the value of a property. | All |
| 0x13 | GET_PROPERTY | Retrieves a property's value. | All |
| 0x14 | GET_INT_STATUS | Read interrupt status bits. | All |
| 0x15 | PATCH_ARGS* | Reserved command used for patch file down-loads. | All |
| 0x16 | PATCH_DATA* | Reserved command used for patch file down-loads. | All |
| 0x61 | AUX_ASRC_START | Starts sampling rate conversion. | All |
| 0x65 | AUX_ASQ_STATUS | Reports audio signal quality metrics. | All |
| 0x80 | GPIO_CNTL | Configures GPO1, 2, and 3 as output or Hi-Z | All |
| 0x81 | GPIO_SET | Sets GPO1, 2, and 3 output level (low or high). | All |
| *Note: Commands PATCH_ARGS and PATCH_DATA are only used to patch firmware. For information on applying a patch file, see "7.2. Powerup from a Component Patch" on page 132. | | | |

Table 13. Stereo Audio ADC Mode Property Summary

| Prop | Name | Description | Default | Available In |
|--------|----------------------------|--|---------|--------------|
| 0x0001 | GPO_IEN | Enables interrupt sources. | 0x0000 | All |
| 0x0102 | DIGITAL_OUTPUT_FORMAT | Configure digital audio outputs. | 0x0000 | All |
| 0x0104 | DIGITAL_OUTPUT_SAMPLE_RATE | Configure digital audio output sample rate. | 0x0000 | All |
| 0x0201 | REFCLK_FREQ | Sets the frequency of the reference clock in Hz. The range is 31130 to 34406 Hz. | 0x8000 | All |
| 0x0202 | REFCLK_PRESCALE | Sets prescaler value for the reference clock. | 0x0001 | All |
| 0x6600 | AUX_ASQ_INTERRUPT_SOURCE | Configure ASQ Interrupt source. | 0x0000 | All |

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|----|----|----|----|--------|----|
| Name | CTS | ERR | X | X | X | X | ASQINT | X |

| Bit | Name | Function |
|-----|----------|--|
| 7 | CTS | Clear to Send. 0 = Wait before sending next command. 1 = Clear to send next command. |
| 6 | ERR | Error. 0 = No error 1 = Error |
| 5:2 | Reserved | Values may vary. |
| 1 | ASQINT | Audio Signal Quality Interrupt. 0 = Audio signal quality interrupt has not been triggered. 1 = Audio signal quality interrupt has been triggered. |
| 0 | Reserved | Values may vary. |

5.3.1. Stereo Audio ADC Mode Commands

Command 0x01. POWER_UP

Initiates the boot process to move the device from powerdown to powerup mode. The boot can occur from internal device memory or a system controller downloaded patch. To confirm that the patch is compatible with the internal device library revision, the library revision should be confirmed by issuing the POWER_UP command with FUNC = 15 (query library ID). The device returns the response, including the library revision, and then moves into powerdown mode. The device can then be placed in powerup mode by issuing the POWER_UP command with FUNC = 4 (AUX Input) and the patch may be applied (See Section "7.2. Powerup from a Component Patch" on page 132).

The POWER_UP command configures the state of LIN (pin 15) and RIN (pin 16) for analog audio inputs and GPO2/INT (pin 18) for interrupt operation. POWER_UP command also configures the state of GPO3/DCLK (pin 17), DFS (pin 14), and DOUT (pin 13) for digital audio mode. The command configures GPO2/INT interrupts (GPO2OEN) and CTS interrupts (CTSIEN). If both are enabled, GPO2/INT is driven high during normal operation and low for a minimum of 1 μ s during the interrupt. The CTSIEN bit is duplicated in the GPO_IEN property. The command is complete when the CTS bit (and optional interrupt) is set.

Note: To change function (e.g. FM RX to AUX IN or AUX IN to AM RX), issue POWER_DOWN command to stop current function; then, issue POWER_UP to start new function.

Note: Delay at least 500 ms between powerup command and first tune command to wait for the oscillator to stabilize if XOSCEN is set and crystal is used as the RCLK.

Available in: All

Command Arguments: Two

Response Bytes: None (FUNC = 0), Seven (FUNC = 15)

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-------------|---------|-------|--------|-----------|----|----|----|
| CMD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | CTSIEN | GPO2OEN | PATCH | XOSCEN | FUNC[3:0] | | | |
| ARG2 | OPMODE[7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|---------|---|
| 1 | 7 | CTSIEN | CTS Interrupt Enable. 0 = CTS interrupt disabled. 1 = CTS interrupt enabled. |
| 1 | 6 | GPO2OEN | GPO2 Output Enable. 0 = GPO2 output disabled. 1 = GPO2 output enabled. |
| 1 | 5 | PATCH | Patch Enable. 0 = Boot normally. 1 = Copy NVM to RAM, but do not boot. After CTS has been set, RAM may be patched. |

| ARG | Bit | Name | Function |
|-----|-----|-------------|---|
| 1 | 4 | XOSCEN | Crystal Oscillator Enable. 0 = Use external RCLK (crystal oscillator disabled). 1 = Use crystal oscillator (RCLK and GPO3/DCLK with external 32.768 kHz crystal and OPMODE=00000101). See Si47xx Data Sheet Application Schematic for external BOM details. |
| 1 | 3:0 | FUNC[3:0] | Function. 0–3 = Reserved. 4 = AUX IN. 5–14 = Reserved. |
| 2 | 7:0 | OPMODE[7:0] | Application Setting. 01011011 = Digital audio outputs (DCLK, DFS, DIO) |

Response (FUNC = 4, AUX IN)

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |

Response (FUNC = 15, Query Library ID)

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|----------------|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |
| RESP1 | PN[7:0] | | | | | | | |
| RESP2 | FWMAJOR[7:0] | | | | | | | |
| RESP3 | FWMINOR[7:0] | | | | | | | |
| RESP4 | RESERVED[7:0] | | | | | | | |
| RESP5 | RESERVED[7:0] | | | | | | | |
| RESP6 | CHIPREV[7:0] | | | | | | | |
| RESP7 | LIBRARYID[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|----------------|---|
| 1 | 7:0 | PN[7:0] | Final 2 digits of part number (HEX). |
| 2 | 7:0 | FWMAJOR[7:0] | Firmware Major Revision (ASCII). |
| 3 | 7:0 | FWMINOR[7:0] | Firmware Minor Revision (ASCII). |
| 4 | 7:0 | RESERVED[7:0] | Reserved, various values. |
| 5 | 7:0 | RESERVED[7:0] | Reserved, various values. |
| 6 | 7:0 | CHIPREV[7:0] | Chip Revision (ASCII). |
| 7 | 7:0 | LIBRARYID[7:0] | Library Revision (HEX). |

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Command 0x10. GET_REV

Returns the part number, chip revision, firmware revision, patch revision and component revision numbers. The command is complete when the CTS bit (and optional interrupt) is set. This command may only be sent when in powerup mode.

Available in: All

Command arguments: None

Response bytes: Fifteen (Si4705 only), Eight (Si4704/3x)

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|--------------------------|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |
| RESP1 | PN[7:0] | | | | | | | |
| RESP2 | FWMAJOR[7:0] | | | | | | | |
| RESP3 | FWMINOR[7:0] | | | | | | | |
| RESP4 | PATCH _H [7:0] | | | | | | | |
| RESP5 | PATCH _L [7:0] | | | | | | | |
| RESP6 | CMPMAJOR[7:0] | | | | | | | |
| RESP7 | CMPMINOR[7:0] | | | | | | | |
| RESP8 | CHIPREV[7:0] | | | | | | | |
| RESP10 | Reserved | | | | | | | |
| RESP11 | Reserved | | | | | | | |
| RESP12 | Reserved | | | | | | | |
| RESP13 | Reserved | | | | | | | |
| RESP14 | Reserved | | | | | | | |
| RESP15 | CID[7:0] (Si4705 only) | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------|--------------------------------------|
| 1 | 7:0 | PN[7:0] | Final 2 digits of Part Number (HEX). |
| 2 | 7:0 | FWMAJOR[7:0] | Firmware Major Revision (ASCII). |
| 3 | 7:0 | FWMINOR[7:0] | Firmware Minor Revision (ASCII). |
| 4 | 7:0 | PATCH _H [7:0] | Patch ID High Byte (HEX). |
| 5 | 7:0 | PATCH _L [7:0] | Patch ID Low Byte (HEX). |

| | | | |
|----|-----|---------------|--|
| 6 | 7:0 | CMPMAJOR[7:0] | Component Major Revision (ASCII). |
| 7 | 7:0 | CMPMINOR[7:0] | Component Minor Revision (ASCII). |
| 8 | 7:0 | CHIPREV[7:0] | Chip Revision (ASCII). |
| 15 | 7:0 | CID[7:0] | CID (Si4705 only). |

Command 0x11. POWER_DOWN

Moves the device from powerup to powerdown mode. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. Note that only the POWER_UP command is accepted in powerdown mode. **If the system controller writes a command other than POWER_UP when in powerdown mode, the device does not respond. The device will only respond when a POWER_UP command is written. GPO pins are powered down and not active during this state. For optimal power down current, GPO2 must be either internally driven low through GPIO_CTL command or externally driven low.**

Note: The following describes the state of all the pins when in powerdown mode:

GPIO1, GPIO2, and GPIO3 = 0

DOUT, DFS, RIN, LIN = HiZ

Available in: All

Command arguments: None

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------|-----|-----|----|----|----|----|----|----|
| STATUS | CTS | ERR | X | X | X | X | X | X |

Command 0x12. SET_PROPERTY

Sets a property shown in Table 13, “Stereo Audio ADC Mode Property Summary,” on page 104. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. See Figure 25, “CTS and SET_PROPERTY Command Complete tCOMP Timing Model,” on page 143 and Table 33, “Command Timing Parameters for the Stereo Audio ADC Mode,” on page 145.

Available in: All

Command Arguments: Five

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|--------------------------|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG2 | PROP _H [7:0] | | | | | | | |
| ARG3 | PROP _L [7:0] | | | | | | | |
| ARG4 | PROPD _H [7:0] | | | | | | | |
| ARG5 | PROPD _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|--------------------------|--|
| 1 | 7:0 | Reserved | Always write to 0. |
| 2 | 7:0 | PROP _H [7:0] | Property High Byte. This byte in combination with PROP _L is used to specify the property to modify. |
| 3 | 7:0 | PROP _L [7:0] | Property Low Byte. This byte in combination with PROP _H is used to specify the property to modify. |
| 4 | 7:0 | PROPD _H [7:0] | Property Value High Byte. This byte in combination with PROPD _L is used to set the property value. |
| 5 | 7:0 | PROPD _L [7:0] | Property Value Low Byte. This byte in combination with PROPD _H is used to set the property value. |

Command 0x13. GET_PROPERTY

Gets a property as shown in Table 13, “Stereo Audio ADC Mode Property Summary,” on page 104. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Available in: All

Command arguments: Three

Response bytes: Three

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|-------------------------|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG2 | PROP _H [7:0] | | | | | | | |
| ARG3 | PROP _L [7:0] | | | | | | | |

| ARG | Bit | Name | Function |
|-----|-----|-------------------------|---|
| 1 | 7:0 | Reserved | Always write to 0. |
| 2 | 7:0 | PROP _H [7:0] | Property High Byte. This byte in combination with PROP _L is used to specify the property to get. |
| 3 | 7:0 | PROP _L [7:0] | Property Low Byte. This byte in combination with PROP _H is used to specify the property to get. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|--------------------------|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |
| RESP1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| RESP2 | PROPD _H [7:0] | | | | | | | |
| RESP3 | PROPD _L [7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|--------------------------|---|
| 1 | 7:0 | Reserved | Always returns 0. |
| 2 | 7:0 | PROPD _H [7:0] | Property Value High Byte. This byte in combination with PROPD _L represents the requested property value. |
| 3 | 7:0 | PROPD _L [7:0] | Property Value High Byte. This byte in combination with PROPD _H represents the requested property value. |

Command 0x14. GET_INT_STATUS

Updates bits 6:0 of the status byte. This command should be called after any command that sets the ASQINT bit. When polling this command should be periodically called to monitor the STATUS byte, and when using interrupts, this command should be called after the interrupt is set to update the STATUS byte. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be set when in powerup mode.

Available in: All

Command arguments: None

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|----|----|----|----|----|----|----|----|
| CMD | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |

Command 0x61. AUX_ASRC_START

Starts sample rate conversion in signal processing module. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The ERR bit (and optional interrupt) is set if an invalid argument is sent. Note that only a single interrupt occurs if both the CTS and ERR bits are set. This command may only be sent when in powerup mode.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|----|----|----|----|----|----|----|----|
| CMD | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |

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Command 0x65. AUX_ASQ_STATUS

Returns status information about audio signal quality. The command returns the input signal LEVEL. This command can be used to detect if a signal overload condition is present indicated by OVERLOADINT. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode.

Available in: All

Command arguments: One

Response bytes: Three

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|----|----|----|--------|
| CMD | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | INTACK |

| ARG | Bit | Name | Function |
|-----|-----|--------|---|
| 1 | 0 | INTACK | Interrupt Acknowledge. 0 = Interrupt status preserved. 1 = Clears ASQINT |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|------------|-----|----|----|----|----|--------|-------------|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |
| RESP1 | X | X | X | X | X | X | X | OVERLOADINT |
| RESP2 | X | X | X | X | X | X | X | OVERLOAD |
| RESP3 | LEVEL[7:0] | | | | | | | |

| RESP | Bit | Name | Function |
|------|-----|-------------|---|
| 1 | 0 | OVERLOADINT | Audio Signal Overload Interrupt. 0 = Audio Input Signal overload has not been detected. 1 = Audio Input Signal overload has been detected. |
| 2 | 0 | OVERLOAD | Audio Signal Overload. 0 = Audio Input Signal overload is not present. 1 = Audio Input Signal overload is present. |
| 3 | 7:0 | LEVEL[7:0] | Audio Input Signal Level. Line input audio level indicator in FS. Range: -128 to 127 |

Command 0x80. GPIO_CTL

Enables output for GPO1, 2, and 3. GPO1, 2, and 3 can be configured for output (Hi-Z or active drive) by setting the GPO1OEN, GPO2OEN, and GPO3OEN bit. The state (high or low) of GPO1, 2, and 3 is set with the GPIO_SET command. To avoid excessive current consumption due to oscillation, GPO pins should not be left in a high impedance state. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This command may only be sent when in powerup mode. The default is all GPO pins set for high impedance.

Note: The use of GPO2 as an interrupt pin and/or the use of GPO3 as DCLK digital clock input will override this GPIO_CTL function for GPO2 and/or GPO3 respectively.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|---------|---------|---------|----|
| CMD | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ARG1 | 0 | 0 | 0 | 0 | GPO3OEN | GPO2OEN | GPO1OEN | 0 |

| ARG | Bit | Name | Function |
|-----|-----|----------|--|
| 1 | 7:4 | Reserved | Always write 0. |
| 1 | 3 | GPO3OEN | GPO3 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 2 | GPO2OEN | GPO2 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 1 | GPO1OEN | GPO1 Output Enable. 0 = Output Disabled (Hi-Z) (default). 1 = Output Enabled. |
| 1 | 0 | Reserved | Always write 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |

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Command 0x81. GPIO_SET

Sets the output level (high or low) for GPO1, 2, and 3. GPO1, 2, and 3 can be configured for output by setting the GPO1OEN, GPO2OEN, and GPO3OEN bit in the GPIO_CTL command. To avoid excessive current consumption due to oscillation, GPO pins should not be left in a high impedance state. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is all GPO pins set for high impedance.

Available in: All

Command arguments: One

Response bytes: None

Command

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------|----|----|----|----|-----------|-----------|-----------|----|
| CMD | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| ARG1 | 0 | 0 | 0 | 0 | GPO3LEVEL | GPO2LEVEL | GPO1LEVEL | 0 |

| ARG | Bit | Name | Function |
|-----|-----|-----------|--|
| 1 | 7:4 | Reserved | Always write 0. |
| 1 | 3 | GPO3LEVEL | GPO3 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 2 | GPO2LEVEL | GPO2 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 1 | GPO1LEVEL | GPO1 Output Level. 0 = Output low (default). 1 = Output high. |
| 1 | 0 | Reserved | Always write 0. |

Response

| Bit | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|-----|-----|----|----|----|----|--------|----|
| STATUS | CTS | ERR | X | X | X | X | ASQINT | X |

5.3.2. Stereo Audio ADC Mode Properties

Property 0x0001. GPO_IEN

Configures the sources for the GPO2/ $\overline{\text{INT}}$ interrupt pin. Valid sources are the lower 8 bits of the STATUS byte, including CTS, ERR, and ASQINT bits. The corresponding bit is set before the interrupt occurs. The CTS bit (and optional interrupt) is set when it is safe to send the next command. The CTS interrupt enable (CTSIEN) can be set with this property and the POWER_UP command. The state of the CTSIEN bit set during the POWER_UP command can be read by reading this property and modified by writing this property. This property may only be set or read when in powerup mode.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|-----|-----|-----|--------|----|--------|--------|----|----|----|----|--------|----|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | ASQIEN | 0 | CTSIEN | ERRIEN | 0 | 0 | 0 | 0 | ASQIEN | 0 |

| Bit | Name | Function |
|-------|----------|---|
| 15:10 | Reserved | Always write to 0. |
| 9 | ASQREP | ASQ Interrupt Repeat. 0 = No interrupt generated when ASQINT is already set (default). 1 = Interrupt generated even if ASQINT is already set. |
| 8 | Reserved | Always write to 0. |
| 7 | CTSIEN | CTS Interrupt Enable. After PowerUp, this bit reflects the CTSIEN bit in ARG1 of PowerUp Command. 0 = No interrupt generated when CTS is set. 1 = Interrupt generated when CTS is set. |
| 6 | ERRIEN | ERR Interrupt Enable. 0 = No interrupt generated when ERR is set (default). 1 = Interrupt generated when ERR is set. |
| 5:2 | Reserved | Always write to 0. |
| 1 | ASQIEN | ASQ Interrupt Enable. 0 = No interrupt generated when ASQINT is set (default). 1 = Interrupt generated when ASQINT is set. |
| 0 | Reserved | Always write to 0. |

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Property 0x0102. DIGITAL_OUTPUT_FORMAT

Configures the digital audio output format. Configuration options include DCLK edge, data format, force mono, and sample precision.

Available in: All

Default: 0x0000

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|----|----|----|----|----|----|---|---|-------|------------|---|---|---|-------|------------|---|
| Name | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OFALL | OMODE[3:0] | | | | OMONO | OSIZE[1:0] | |

| Bit | Name | Function |
|------|------------|--|
| 15:8 | Reserved | Always write to 0. |
| 7 | OFALL | Digital Output DCLK Edge. 0 = use DCLK rising edge 1 = use DCLK falling edge |
| 6:3 | OMODE[3:0] | Digital Output Mode. 0000 = I ² S 0110 = Left-justified 1000 = MSB at second DCLK after DFS pulse 1100 = MSB at first DCLK after DFS pulse |
| 2 | OMONO | Digital Output Mono Mode. 0 = Use mono/stereo blend (per blend thresholds) 1 = Force mono |
| 1:0 | OSIZE[1:0] | Digital Output Audio Sample Precision. 0 = 16-bits 1 = 20-bits 2 = 24-bits 3 = 8-bits |

Property 0x0104. DIGITAL_OUTPUT_SAMPLE_RATE

Enables digital audio output and configures digital audio output sample rate in samples per second (sps). When DOSR[15:0] is 0, digital audio output is disabled. The over-sampling rate must be set in order to satisfy a minimum DCLK of 1 MHz. To enable digital audio output, program DOSR[15:0] with the sample rate in samples per second. **The system controller must establish DCLK and DFS prior to enabling the digital audio output else the device will not respond and will require reset. The sample rate must be set to 0 before the DCLK/DFS is removed.**

Available in: All

Default: 0x0000 (digital audio output disabled)

Units: sps

Range: 32–48 ksps, 0 to disable digital audio output

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Name | DOSR[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|------------|---|
| 15:0 | DOSR[15:0] | Digital Output Sample Rate. 32, 44.1, and 48 ksps. 0 to disable digital audio output. |

Property 0x0201. REFCLK_FREQ

Sets the frequency of the REFCLK from the output of the prescaler. The REFCLK range is 31130 to 34406 Hz (32768 \pm 5% Hz) in 1 Hz steps, or 0 (to disable AFC). For example, an RCLK of 13 MHz would require a prescaler value of 400 to divide it to 32500 Hz REFCLK. The reference clock frequency property would then need to be set to 32500 Hz. RCLK frequencies between 31130 Hz and 40 MHz are supported, however, there are gaps in frequency coverage for prescaler values ranging from 1 to 10, or frequencies up to 311300 Hz. The following table summarizes these RCLK gaps.

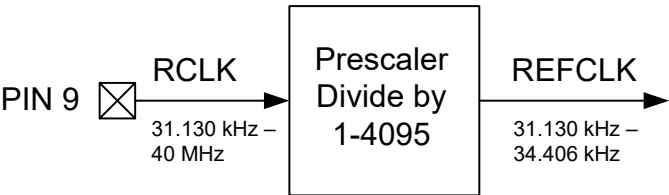


Figure 11. REFCLK Prescaler

Table 14. RCLK Gaps

| Prescaler | RCLK Low (Hz) | RCLK High (Hz) |
|-----------|---------------|----------------|
| 1 | 31130 | 34406 |
| 2 | 62260 | 68812 |
| 3 | 93390 | 103218 |
| 4 | 124520 | 137624 |
| 5 | 155650 | 172030 |
| 6 | 186780 | 206436 |
| 7 | 217910 | 240842 |
| 8 | 249040 | 275248 |
| 9 | 280170 | 309654 |
| 10 | 311300 | 344060 |

The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 32768 Hz.

The RCLK must be valid 10 ns before sending and 20 ns after completing the AUX_ASRC_START command. In addition, the RCLK must be valid at all times for proper AFC operation. The RCLK may be removed or reconfigured at other times.

Available in: All
Default: 0x8000 (32768)
Units: 1 Hz
Step: 1 Hz
Range: 31130–34406

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|----|
| Name | REFCLKF[15:0] | | | | | | | | | | | | | | | |

| Bit | Name | Function |
|------|---------------|---|
| 15:0 | REFCLKF[15:0] | Frequency of Reference Clock in Hz. The allowed REFCLK frequency range is between 31130 and 34406 Hz (32768 \pm 5%), or 0 (to disable AFC). |

Property 0x0202. REFCLK_PRESCALE

Sets the number used by the prescaler to divide the external RCLK down to the internal REFCLK. The range may be between 1 and 4095 in 1 unit steps. For example, an RCLK of 13 MHz would require a prescaler value of 400 to divide it to 32500 Hz. The reference clock frequency property would then need to be set to 32500 Hz. The RCLK must be valid 10 ns before sending and 20 ns after completing the AUX_ASRC_START command. In addition, the RCLK must be valid at all times for proper AFC operation. The RCLK may be removed or reconfigured at other times. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in powerup mode. The default is 1.

Available in: All

Default: 0x0001

Step: 1

Range: 1–4095

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-----|-----|-----|----------|---------------|-----|----|----|----|----|----|----|----|----|----|----|
| Name | 0 | 0 | 0 | RCLK-SEL | REFCLKP[11:0] | | | | | | | | | | | |

| Bit | Name | Function |
|-------|---------------|--|
| 15:13 | Reserved | Always write to 0. |
| 12 | RCLKSEL | 0 = RCLK pin is clock source. 1 = DCLK pin is clock source. |
| 11:0 | REFCLKP[11:0] | Prescaler for Reference Clock. Integer number used to divide clock frequency down to REFCLK frequency. The allowed REFCLK frequency range is between 31130 and 34406 Hz (32768 5%), or 0 (to disable AFC). |

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Property 0x6600. AUX_ASQ_INTERRUPT_SOURCE

Configures interrupt related to Audio Signal Quality metrics. The CTS bit (and optional interrupt) is set when it is safe to send the next command. This property may only be set or read when in power up mode. The default is 0.

Available in: All

Default: 0x0000

| Bit | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|--------|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|-----------------|
| Name | 0X0000 | | | | | | | | | | | | | | | OVER LOADINT |

| Bit | Name | Function |
|------|-------------|---|
| 15:2 | Reserved | Always write to 0. |
| 1:0 | OVERLOADINT | Interrupt Source Enable: Overload 0 = Disable audio signal overload detection interrupt 1 = Enable audio signal overload detection interrupt |

6. Control Interface

The bus mode is selected by sampling the state of the GPO1 and GPO2/INT pins on the rising edge of $\overline{\text{RST}}$. The GPO1 pin includes a 1 M Ω internal pull-up resistor that is connected while $\overline{\text{RST}}$ is low, and the GPO2/INT pin includes an internal 1 M Ω pull-down resistor that is connected while the $\overline{\text{RST}}$ pin is low. Therefore, it is only necessary for the system controller to actively drive pins if a mode other than the default 2-wire mode is required, as shown in Table 15. After bus mode selection is complete, the device is placed in powerdown mode. The minimum setup time for GPO1 and GPO2 before $\overline{\text{RST}} = 1$ is 30 ns when actively driven by the system controller and 100 μs if the internal 1 M Ω resistor is allowed to set the default GPO1 (high) and GPO2 (low).

Table 15. Bus Mode Selection

| Bus Mode | GPO2/INT | GPO1 |
|----------|----------------|----------------|
| 3-wire | 0 | 0 (must drive) |
| SPI | 1 (must drive) | 1 |
| 2-wire | 0 | 1 |

In powerdown mode, all circuitry is disabled except for the device control interface. The device comes out of powerdown mode when the POWER_UP command is written to the command register. Once in powerup mode, the device accepts additional commands, such as tuning, and the setting of properties, such as power level. The device will not accept commands while in powerdown mode, with the exception of the powerup command. **If the system controller writes a command other than POWER_UP when in powerdown mode, the device does not respond, and a reset is required.**

Setting the $\overline{\text{RST}}$ pin low places the device in reset mode. In reset mode, all circuitry is disabled including the device control interface; registers are set to their default settings, and the control bus is disabled.

6.1. 2-Wire Control Interface Mode

Figures 12 and 13 show the 2-wire Control Interface Read and Write Timing Parameters and Diagrams, respectively.

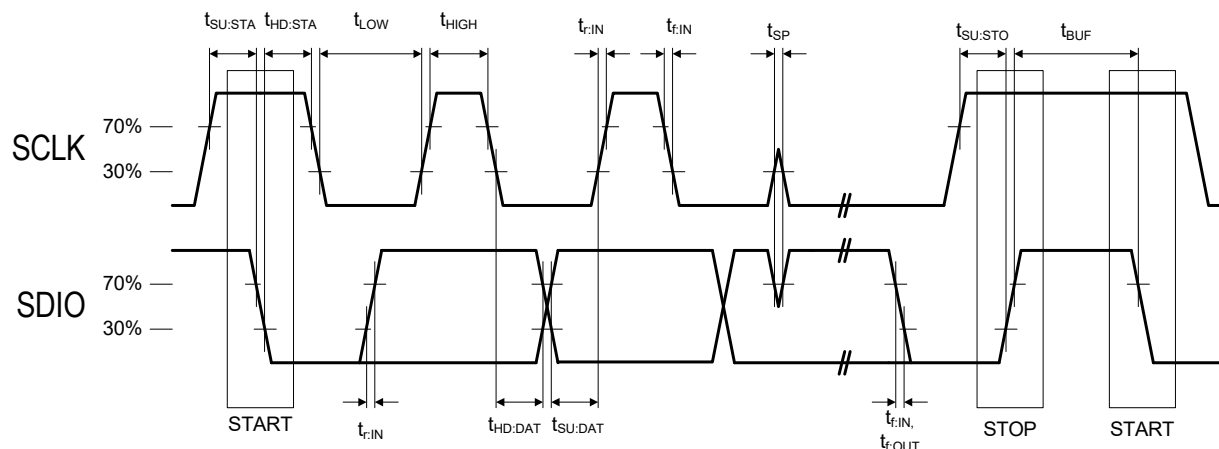


Figure 12. 2-wire Control Interface Read and Write Timing Parameters

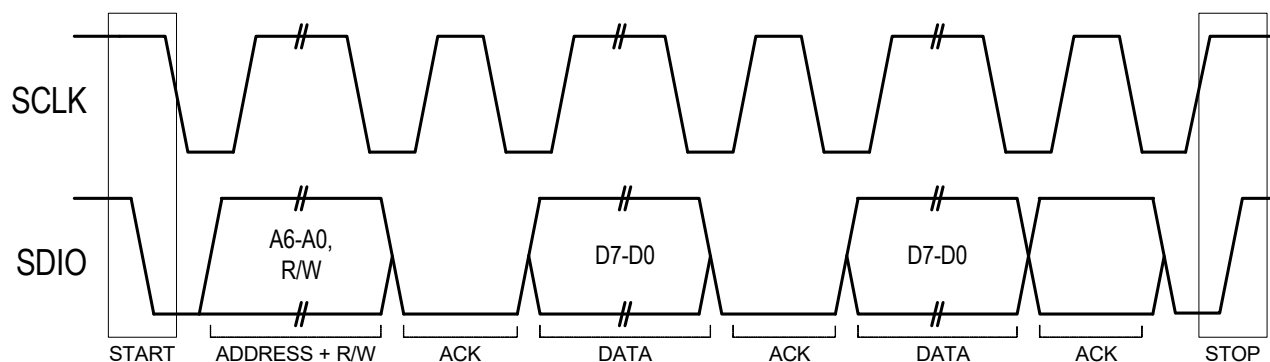


Figure 13. 2-wire Control Interface Read and Write Timing Diagram

2-wire bus mode uses only the SCLK and SDIO pins for signaling. A transaction begins with the START condition, which occurs when SDIO falls while SCLK is high. Next, the system controller drives an 8-bit control word serially on SDIO, which is captured by the device on rising edges of SCLK. The control word consists of a seven-bit device address followed by a read/write bit (read = 1, write = 0). The device acknowledges the control word by driving SDIO low on the next falling edge of SCLK.

Although the device responds to only a single device address, this address can be changed with the $\overline{\text{SEN}}$ pin (note that the $\overline{\text{SEN}}$ pin is not used for signaling in 2-wire mode). When $\overline{\text{SEN}} = 0$, the seven-bit device address is 0010001b. When $\overline{\text{SEN}} = 1$, the address is 1100011b.

For write operations, the system controller next sends a data byte on SDIO, which is captured by the device on rising edges of SCLK. The device acknowledges each data byte by driving SDIO low for one cycle on the next falling edge of SCLK. The system controller may write up to 8 data bytes in a single 2-wire transaction. The first byte is a command, and the next seven bytes are arguments. **Writing more than 8 bytes results in unpredictable device behavior.**

For read operations, after the device has acknowledged the control byte, it will drive an eight-bit data byte on SDIO, changing the state of SDIO on the falling edges of SCLK. The system controller acknowledges each data byte by driving SDIO low for one cycle on the next falling edge of SCLK. If a data byte is not acknowledged by the system controller, the transaction will end. The system controller may read up to 16 data bytes in a single 2-wire transaction. These bytes contain the status byte and response data from the device.

A 2-wire transaction ends with the STOP condition, which occurs when SDIO rises while SCLK is high.

Table 16 demonstrates the command and response procedure implemented in the system controller to use the 2-wire bus mode. In this example the FM_TUNE_FREQ command is demonstrated.

Table 16. Command and Response Procedure (2-Wire Bus Mode)

| Action | Data | Description |
|--------|-------|--------------------------------------|
| CMD | 0x20 | FM_TUNE_FREQ |
| ARG1 | 0x00 | |
| ARG2 | 0x27 | Set frequency to 101.1 MHz |
| ARG3 | 0x7E | |
| ARG4 | 0x00 | Set antenna tuning capacitor to auto |
| STATUS | →0x80 | Reply status. Clear-to-send high. |

To send the FM_TUNE_FREQ command and arguments, the system controller sends the START condition, followed by the 8-bit control word, which consists of a seven-bit device address (0010001b SEN = 0 or 1100011b SEN = 1) and the write bit (0b) indicated by ADDR+W = 00100010b = 0x22. In this example, SEN = 0 resulting in the control word ADDR+W = 00100010b = 0x22. If instead SEN = 1, the resulting control word would be ADDR+W = 11000110b = 0xC6. The device acknowledges the control word by setting SDIO = 0, indicated by ACK = 0. The system controller then sends the CMD byte, 0x20, and again the device acknowledges by setting ACK = 0. The system controller and device repeat this process for the ARG1, ARG2, and ARG3 bytes. Commands may take up to seven argument bytes, and this flexibility should be designed into the 2-wire bus mode implementation. Alternatively, all seven argument bytes may be sent for all commands, but unusual arguments must be 0x00. **Unpredictable device behavior will result if more than seven arguments are sent.**

| START | ADDR+W | ACK | CMD | ACK | ARG1 | ACK | ARG2 | ACK | ARG3 | ACK | ARG4 | ACK | STOP |
|-------|--------|-----|------|-----|------|-----|------|-----|------|-----|------|-----|------|
| START | 0x22 | 0 | 0x20 | 0 | 0x00 | 0 | 0x27 | 0 | 0x7E | 0 | 0x00 | 0 | STOP |

To read the status and response from the device, the system controller sends the START condition, followed by the eight-bit control word, which consists of the seven bit device address and the read bit (1b). In this example, SEN = 0 and the write control word is ADDR+R = 00100011b = 0x23. If SEN = 1, the write control word would be ADDR+R = 11000111b = 0xC7. The device acknowledges the control word by setting ACK = 0. Next the system controller reads the STATUS byte. In this example, the STATUS byte is 0x00, indicating that the CTS bit, bit 8, has not been set. The response bytes are not ready for reading and that the device is not ready to accept another command. The system controller sets SDIO = 1, indicated by NACK = 1, to signal to the device the 2-wire transfer will end. The system controller should set the STOP condition. This process is repeated until the STATUS byte indicates that CTS bit is set, 0x80 in this example.

| START | ADDR+R | ACK | STATUS | NACK | STOP |
|-------|--------|-----|--------|------|------|
| START | 0x23 | 0 | 0x00 | 1 | STOP |

When the STATUS byte returns CTS bit set, 0x80 in this example, the system controller may read the response bytes from the device. The controller sets ACK = 0 to indicate to the device that additional bytes will be read. The RESP1 byte is read by the system controller, followed by the system controller setting ACK = 0. This is repeated for RESP2. RESP3 is read by the system controller followed by the system controller setting NACK = 1, indicating that RESP3 is the last byte to be read. The system controller then sets the STOP condition. Responses may be up to 15 bytes in length (RESP1–RESP15) depending on the command. It is acceptable to read all 15 response bytes. However, unused response bytes return random data and must be ignored. Note that the FM_TUNE_FREQ command returns only the STATUS byte and response bytes are shown only for completeness.

| START | ADDR+R | ACK | STATUS | ACK | RESP1 | ACK | RESP2 | ACK | RESP3 | NACK | STOP |
|-------|--------|-----|--------|-----|-------|-----|-------|-----|-------|------|------|
| START | 0x23 | 0 | 0x80 | 0 | 0x00 | 0 | 0x00 | 0 | 0x00 | 1 | STOP |

6.2. 3-Wire Control Interface Mode

Figures 14 and 15 show the 3-wire Control Interface Read and Write Timing Parameters and Diagrams, respectively.

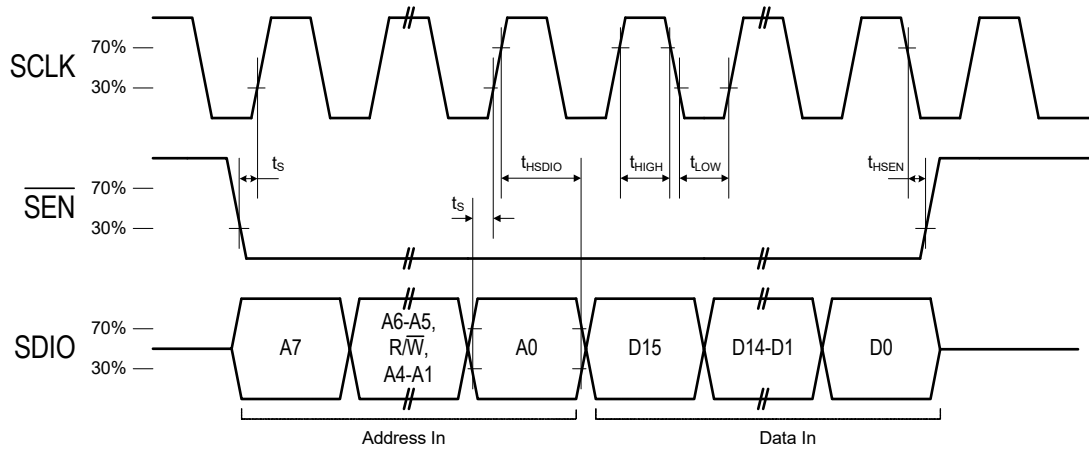


Figure 14. 3-Wire Control Interface Write Timing Parameters

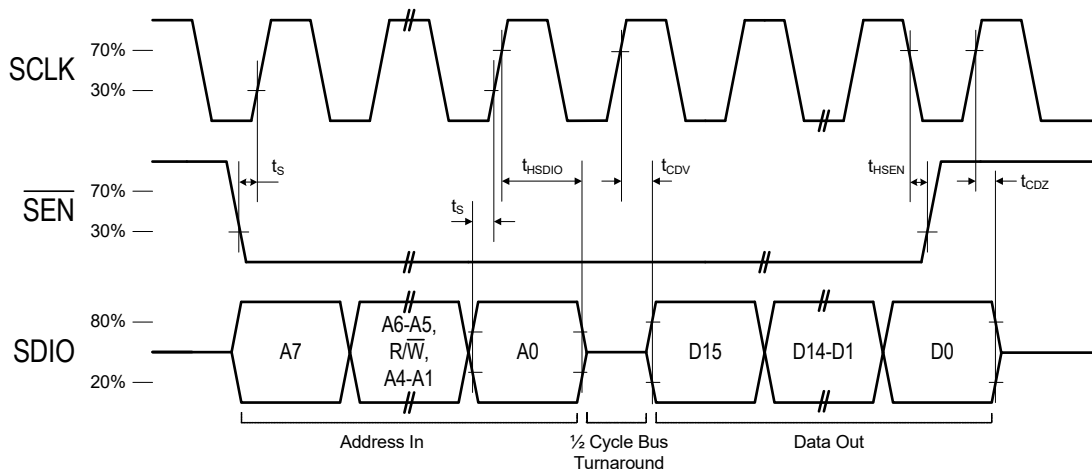


Figure 15. 3-Wire Control Interface Read Timing Parameters

3-wire bus mode uses the SCLK, SDIO and $\overline{\text{SEN}}$ pins. A transaction begins when the system controller drives $\overline{\text{SEN}}$ low. Next, the system controller drives a 9-bit control word on SDIO, which is captured by the device on rising edges of SCLK. The control word is comprised of a three bit chip address (A7:A5 = 101b), a read/write bit (write = 0, read = 1), the chip address (A4 = 0), and a four bit register address (A3:A0).

For write operations, the control word is followed by a 16-bit data word, which is captured by the device on rising edges of SCLK.

For read operations, the control word is followed by a delay of one-half SCLK cycle for bus turn-around. Next, the device drives the 16-bit read data word serially on SDIO, changing the state of SDIO on each rising edge of SCLK.

A transaction ends when the system controller sets $\overline{\text{SEN}} = 1$, then pulses SCLK high and low one final time. SCLK may either stop or continue to toggle while $\overline{\text{SEN}}$ is high. In 3-wire mode, commands are sent by first writing each argument to register(s) 0xA1–0xAF, then writing the command word to register 0xA0. A response is retrieved by reading registers 0xA8–0xAF.

Table 17. Register Map for 3-Wire Mode

| 3w Addr | Name | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------|----------------------|----------|-----|-----|-----|------------|------------|------------|------------|----------|----|----|----|----|----|----|----|
| A0h | COMMAND1 | CMD | | | | | | | | ARG1 | | | | | | | |
| A1h | COMMAND2 | ARG2 | | | | | | | | ARG3 | | | | | | | |
| A2h | COMMAND3 | ARG4 | | | | | | | | ARG5 | | | | | | | |
| A3h | COMMAND4 | ARG6 | | | | | | | | ARG7 | | | | | | | |
| A4h | Reserved1 | Reserved | | | | | | | | Reserved | | | | | | | |
| A5h | Reserved2 | Reserved | | | | | | | | Reserved | | | | | | | |
| A6h | Reserved3 | Reserved | | | | | | | | Reserved | | | | | | | |
| A7h | Reserved4 | Reserved | | | | | | | | Reserved | | | | | | | |
| A8h | STATUS/ RESPONSE1 | CTS | ERR | | | RSDIN T | RDSIN T | ASQIN T | STCIN T | RESP1 | | | | | | | |
| A9h | RESPONSE2 | RESP2 | | | | | | | | RESP3 | | | | | | | |
| AAh | RESPONSE3 | RESP4 | | | | | | | | RESP5 | | | | | | | |
| ABh | RESPONSE4 | RESP6 | | | | | | | | RESP7 | | | | | | | |
| ACH | RESPONSE5 | RESP8 | | | | | | | | RESP9 | | | | | | | |
| ADh | RESPONSE6 | RESP10 | | | | | | | | RESP11 | | | | | | | |
| Aeh | RESPONSE7 | RESP12 | | | | | | | | RESP13 | | | | | | | |
| Afh | RESPONSE8 | RESP14 | | | | | | | | RESP15 | | | | | | | |

In 3-wire mode, the control registers are accessed as 16-bit entities (2 byte). In Table 17, the full 8-bit 3-wire address is shown, including the chip's fixed base address (A7:A4 = 1010b). The first two bytes in a command stream uses register COMMAND1. The CMD byte occupies register COMMAND1[15:8], while ARG1 occupies register COMMAND1[7:0]. Commands with an odd number of bytes must have the lower 8 bits of the register containing the final argument byte filled with 0x00. Registers which are not specified by the command must either not be written, or must be filled with 0x0000 (user's discretion). Writing register COMMAND1 causes the command to execute. As a consequence, all registers containing applicable argument bytes must be written (in any order) prior to writing register COMMAND1. For example, when sending the SET_PROPERTY command, write registers COMMAND2..COMMAND3 first, then register COMMAND1. Note that ARG1 is part of register COMMAND1 and must be written at the same time as CMD. The contents of registers STATUS/RESPONSE1..RESPONSE8 are not valid until the CTS bit (STATUS/RESPONSE1[15]) is set. RESPONSE1[13:8] is updated after sending the GET_INT_STATUS command. Response bytes which are not specified in the response byte stream are not guaranteed to be 0x00 and should be ignored. For example, GET_PROPERTY has 4 bytes of response data in registers RESPONSE1..RESPONSE2. The contents of registers RESPONSE3..RESPONSE8 are meaningless and not guaranteed to be 0x0000. Likewise, for commands which have an odd number of response bytes, or a single status byte, the least significant byte (bits 7:0) of the final register is meaningless, and not guaranteed to be 0x00.

Table 18 demonstrates the command and response procedure implemented in the system controller to use the 3-wire bus mode. In this example the FM_TUNE_FREQ command is demonstrated.

Table 18. Command and Response Procedure (3-Wire Bus Mode)

| Action | Data | Description |
|--------|-------|---------------------------------------|
| CMD | 0x20 | FM_TUNE_FREQ. |
| ARG1 | 0x00 | |
| ARG2 | 0x27 | Set Frequency to 101.1 MHz |
| ARG3 | 0x7E | |
| ARG4 | 0x00 | Set antenna tuning capacitor to auto. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

To send the FM_TUNE_FREQ command and arguments, the system controller sets $\overline{SEN} = 0$. Next, the controller drives the 9-bit control word on SDIO, consisting of the device address (A7:A5 = 101b), the write bit (0b), the device address (A4 = 0), and the register address for the COMMAND2 register (A3:A0 = 0001b). The control word is followed by a 16-bit data word, consisting of ARG2 followed by ARG3. The system controller then sets $\overline{SEN} = 1$ and pulses the SCLK high and then low one final time. For commands requiring additional arguments, in the COMMAND3 (ARG4, ARG5) and COMMAND4 (ARG6, ARG7) registers, the system controller would send these next.

| \overline{SEN} | CTL | ARG2 | ARG3 | \overline{SEN} | SCLK |
|------------------|------------|------|------|------------------|-------|
| 1 → 0 | 101000001b | 0x27 | 0x7E | 0 → 1 | Pulse |

Next the system controller initiates the command by setting $\overline{SEN} = 0$ and driving the 9-bit control word on SDIO, consisting of the device address (A7:A5 = 101b), the write bit (0b), the device address (A4 = 0), and the register address for the COMMAND1 register (A3:A0 = 0000b). The control word is followed by a 16-bit data word, consisting of the CMD byte followed by ARG1 byte. The system controller then sets $\overline{SEN} = 1$ and pulses the SCLK high and then low one final time.

| \overline{SEN} | CTL | CMD | ARG1 | \overline{SEN} | SCLK |
|------------------|------------|------|------|------------------|-------|
| 1 → 0 | 101000000b | 0x20 | 0x00 | 0 → 1 | Pulse |

To read the status and response from the device, the system controller sets $\overline{SEN} = 0$. Next, the controller drives the 9-bit control word 101101000b on SDIO, consisting of the device address (A7:A5 = 101b), the read bit (1b), the device address (A4 = 0), and the register address for the STATUS/RESPONSE1 register (A3:A0 = 1000b). The control word is followed by a 16-bit data word, consisting of STATUS followed by RESPONSE1. The system controller then sets $\overline{SEN} = 1$ and pulses the SCLK high and then low one final time. In this example, the STATUS byte is 0x00, indicating that the CTS bit, bit 8, has not been set and that the response bytes are not ready for reading and that the device is not ready to accept another command. RESP1 will be random until the CTS bit is set. This process should be repeated until the STATUS byte indicates that CTS bit is set, 0x80 in this example.

| \overline{SEN} | CTL | STATUS | RESP1 | \overline{SEN} | SCLK |
|------------------|------------|--------|-------|------------------|-------|
| 1 → 0 | 101101000b | 0x00 | 0x00 | 0 → 1 | Pulse |

When the STATUS byte indicates that the CTS bit has been set, 0x80 in this example, the system controller may read the RESPONSE bytes from the device in any order.

| \overline{SEN} | CTL | STATUS | RESP1 | \overline{SEN} | SCLK |
|------------------|------------|--------|-------|------------------|-------|
| 1 → 0 | 101101000b | 0x80 | 0x00 | 0 → 1 | Pulse |

6.3. SPI Control Interface Mode

Figures 16 and 17 show the SPI Control Interface Read and Write Timing Parameters and Diagrams, respectively.

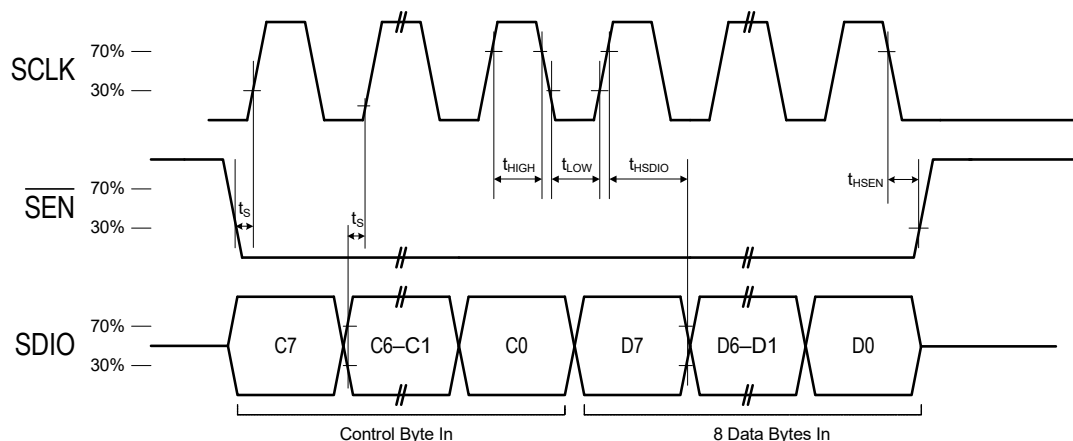


Figure 16. SPI Control Interface Write Timing Parameters

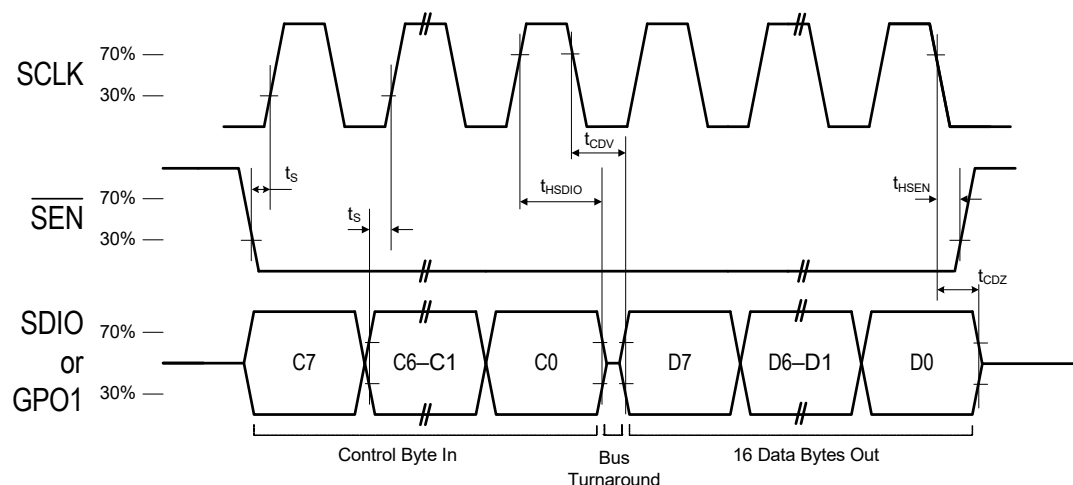


Figure 17. SPI Control Interface Read Timing Parameters

SPI bus mode uses the SCLK, SDIO and $\overline{\text{SEN}}$ pins for read/write operations. The system controller can choose to receive read data from the device on either SDIO or GPO1. A transaction begins when the system controller drives $\overline{\text{SEN}} = 0$. The system controller then pulses SCLK eight times, while driving an 8-bit control byte serially on SDIO. The device captures the data on rising edges of SCLK. The control byte must have one of five values:

- 0x48 = write a command (controller drives 8 additional bytes on SDIO)
- 0x80 = read a response (device drives one additional byte on SDIO)
- 0xC0 = read a response (device drives 16 additional bytes on SDIO)
- 0xA0 = read a response (device drives one additional byte on GPO1)
- 0xE0 = read a response (device drives 16 additional bytes on GPO1)

For write operations, the system controller must drive exactly 8 data bytes (a command and arguments) on SDIO after the control byte. The data is captured by the device on the rising edge of SCLK.

For read operations, the controller must read exactly one byte (STATUS) after the control byte or exactly 16 data bytes (STATUS and RESP1–RESP15) after the control byte. The device changes the state of SDIO (or GPO1, if specified) on the falling edge of SCLK. Data must be captured by the system controller on the rising edge of SCLK. Keep $\overline{\text{SEN}}$ low until all bytes have transferred. A transaction may be aborted at any time by setting $\overline{\text{SEN}}$ high and

toggling SCLK high and then low. Commands will be ignored by the device if the transaction is aborted.

Table 19 demonstrates the command and response procedure that would need to be implemented in the system controller to use the SPI bus mode. In this example the FM_TUNE_FREQ command is demonstrated.

Table 19. Command and Response Procedure—SPI Bus Mode

| Action | Data | Description |
|--------|-------|---------------------------------------|
| CMD | 0x20 | FM_TUNE_FREQ |
| ARG1 | 0x00 | |
| ARG2 | 0x27 | Set frequency to 101.1 MHz |
| ARG3 | 0x7E | |
| ARG4 | 0x00 | Set antenna tuning capacitor to auto. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

To send the FM_TUNE_FREQ command and arguments, the system controller sets $\overline{SEN} = 0$, sends the control byte 0x48, followed by the CMD byte and seven argument bytes, ARG1-ARG7, followed by setting $\overline{SEN} = 1$. Note that all seven argument bytes must be sent by the controller or the command will fail. Unused arguments must be written as 0x00.

| \overline{SEN} | CTL | CMD | ARG1 | ARG2 | ARG3 | ARG4 | ARG5 | ARG6 | ARG7 | \overline{SEN} |
|------------------|------|------|------|------|------|------|------|------|------|------------------|
| 1 → 0 | 0x48 | 0x20 | 0x00 | 0x27 | 0x7E | 0x00 | 0x00 | 0x00 | 0x00 | 0 → 1 |

To read the status and response from the device, the system controller sets $\overline{SEN} = 0$ and sends the control byte 0x80 to read the response on SDIO (or the control byte 0xA0 to read the response on GPO1). Next the system controller reads the STATUS byte. In this example, the STATUS byte is 0x00, indicating that the CTS bit, bit 8, has not been set and that the response bytes are not ready for reading. The device is not ready to accept another command. The system controller sets $\overline{SEN} = 1$ to end the transfer. This process should be repeated until the STATUS byte indicates that CTS bit is set, 0x80 in this example.

| \overline{SEN} | CTL | STATUS | \overline{SEN} |
|------------------|------|--------|------------------|
| 1 → 0 | 0x80 | 0x00 | 0 → 1 |

When the STATUS byte indicates that the CTS bit has been set, 0x80 in this example, the system controller may read the response bytes from the device. To read the status and response from the device, the system controller sets $\overline{SEN} = 0$ and sends the control byte 0xC0 to read the response on SDIO (or the control byte 0xE0 to read the response on GPO1). Note that all 16 response bytes must be read from the device. Unused response bytes are random and should be ignored. Note that the FM_TUNE_FREQ command returns only the STATUS byte and RESP1–RESP15 bytes are shown only for completeness.

| \overline{SEN} | CTL | STATUS | RESP1 | RESP2 | RESP3 | RESP4 | RESP5 | RESP6 | RESP7 | RESP8 | RESP9 | RESP10 | RESP11 | RESP12 | RESP13 | RESP14 | RESP15 | \overline{SEN} |
|------------------|------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|--------|--------|--------|--------|--------|--------|------------------|
| 1 → 0 | 0xC0 | 0x80 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0 → 1 |

7. Powerup

There are two procedures for booting the device to move it from powerdown mode to the powerup mode. The first and most common is a boot from internal device memory. The second is a boot from a firmware patch that is written from the system controller to the device.

To power up the device:

1. Supply VDD and VIO while keeping the $\overline{\text{RST}} = 0$.
The minimum VDD and VIO rise time is 25 μs , and VDD and VIO must be stable 250 μs before setting $\overline{\text{RST}} = 1$. Power supplies may be sequenced in any order.
 $\overline{\text{RST}}$ is in the VIO supply domain and therefore $\overline{\text{RST}} = 0$ must be maintained before VIO is supplied.
2. Set GPO1 and GPO2 for the desired bus mode.
The minimum setup time for GPO1 and GPO2 before $\overline{\text{RST}} = 1$ is 30 ns when actively driven by the system controller and 100 μs if the internal 1 M Ω resistor is allowed to set the default GPO1 (high) and GPO2 (low).
3. Set $\overline{\text{RST}} = 1$.
4. Write POWER_UP to the command register.
The POWER_UP command instructs the device to boot from internal memory, see Section “7.1. Powerup from Device Memory”, or from a firmware patch sent from the system controller, see Section “7.2. Powerup from a Component Patch”. After CTS = 1, the device is ready to commence normal operation and accept additional commands. The POWER_UP command configures the state of DIN (Pin 13, Si4732 Pin 16), DFS (Pin 14, Si4732 pin 1), and RIN (Pin 16 on Si4704/05/3x-D62) and LIN (Pin 15 on Si4704/05/3x-D62) for analog or digital audio modes and GPO2/INT for interrupt operation. Prior to this command, these pins are set to high impedance. The GPIO_CTL and GPIO_SET commands configure the state of GPO2/INT and GPO3. Prior to this command these pins are set to high impedance.
5. Provide RCLK.
Note that the RCLK buffer is in the VIO supply domain and may therefore be supplied at any time after VIO is supplied. The RCLK must be valid 10 ns before any command that enables the receiver, such as the FM_TUNE_FREQ command, and for 10 ns after any command that disables the carrier, such as the TX_TUNE_POWER command with a value of 0x00. The RCLK is required for proper AGC operation when the carrier is enabled. The RCLK may be removed or reconfigured when the carrier is disabled.

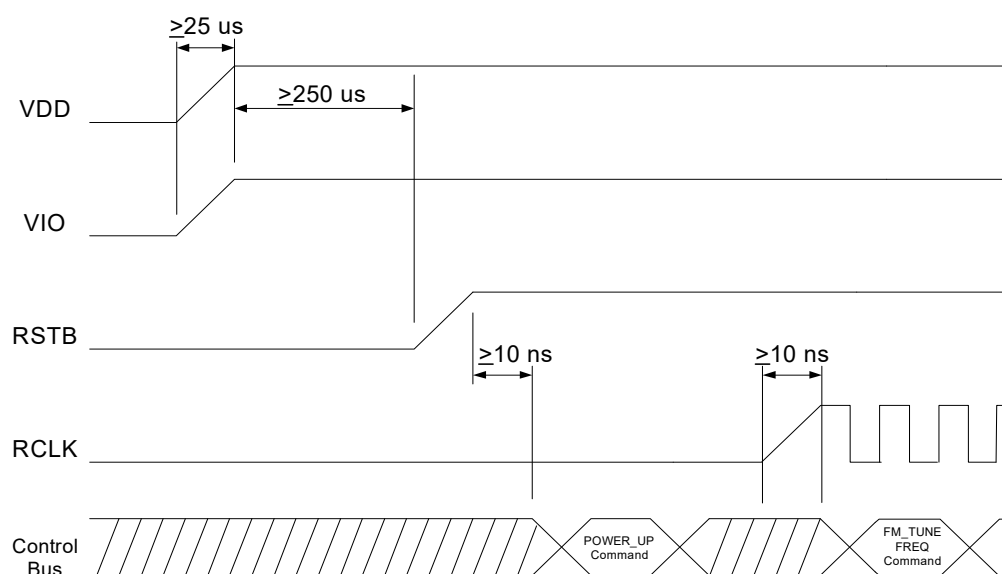


Figure 18. Device Power Up Timing

7.1. Powerup from Device Memory

Table 20. Using the POWER_UP command for the FM Receiver

| Action | Data | Description |
|--------|-------|-----------------------------------|
| CMD | 0x01 | POWER_UP |
| ARG1 | 0x00 | Set to FM Receive. |
| ARG2 | 0x05 | Set to Analog Out. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

1. Send the POWER_UP command by writing the CMD field with value 0x01.
2. Send ARG1, 0x00 (no patch, CTS and GPO2 interrupts disabled, FM receive selected). Optionally various interrupts such as the CTS interrupt can be enabled by varying this argument, see Section “5. Commands and Properties”.
3. Send ARG2, 0x05 (analog output is selected)
4. Poll the CTS bit until it has been set high, or until a CTS interrupt is received (if CTS interrupt is enabled).

Table 21. Using the POWER_UP Command for the AM/SW/LW Receiver

| Action | Data | Description |
|--------|-------|-----------------------------------|
| CMD | 0x01 | POWER_UP |
| ARG1 | 0x01 | Set to AM/SW/LW Receive. |
| ARG2 | 0x05 | Set to Analog Out. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

1. Send the POWER_UP command by writing the CMD field with value 0x01.
2. Send ARG1, 0x01 (no patch, CTS and GPO2 interrupts disabled, AM/SW/LW receive selected). Optionally various interrupts such as the CTS interrupt can be enabled by varying this argument, see Section “5. Commands and Properties”.
3. Send ARG2, 0x05 (analog output selected)
4. Poll the CTS bit until it has been set high, or until a CTS interrupt is received (if CTS interrupt is enabled).

7.2. Powerup from a Component Patch

The device has the ability to receive component patches from the system controller to modify sections or all of the device memory.

7.2.1. Patching Capabilities

In order to support interim updates to the device component, patches can be applied to the component by the system controller via a download mechanism. Patches can be provided by Skyworks Solutions to customers to address field issues, errata, or adjust device behavior. Patches are unique to a particular device firmware version and cannot be generated by customers.

Patches can be used to replace a portion of the component (to address errata for example) or to download an entirely new component image (to allow a customer to test a new component release on their device prior to receiving programmed parts).

Patches are tagged with a unique identification to allow them to be tracked and are encrypted requiring the customer to use a tag when downloading to allow the Si47xx to decrypt the patch.

Prior to downloading a partial patch, the user must confirm that the device contains the correct firmware and library to support the patch.

7.2.1.1. Examples

For a programmatic indication, the POWER_UP command can be used to confirm the device library and firmware version. For a visual indication, the marking on the device can be used to confirm the firmware version. Tables 22 through 24 summarize the library and firmware mapping and compatibility.

Table 22. Si4704/05 Firmware, Library, and Component Compatibility

| Part # | Firmware | Library | FMRX Component | AUXIN Component |
|---------------|----------|---------|----------------|-----------------|
| Si4704/05-D50 | 5.0 | R11 | 7.0 | N/A |
| Si4704/05-D60 | 6.0 | R11 | 7.0 | N/A |
| Si4704/05-D62 | 6.2 | R11 | 7.0 | 1.0 |

Table 23. Si4706 Firmware, Library, and Component Compatibility

| Part # | Firmware | Library | FMRX Component |
|------------|----------|---------|----------------|
| Si4706-D50 | 5.0 | R11 | 7.0 |

Table 24. Si4730/31 Firmware, Library, and Component Compatibility

| Part # | Firmware | Library | FMRX Component | AM_SW_LW RX Component | AUXIN Component |
|---------------|----------|---------|----------------|-----------------------|-----------------|
| Si4730/31-D60 | 6.0 | R11 | 7.0 | 6.0 | N/A |
| Si4730/31-D62 | 6.2 | R11 | 7.0 | 6.0 | 1.0 |

Table 25. Si4749 Firmware, Library, and Component Compatibility

| Part # | Firmware | Library | FMRX Component |
|------------|----------|---------|----------------|
| Si4749-C10 | 1.0 | R10 | 4.0 |

Table 26. Si4734/35 Firmware, Library, and Component Compatibility

| Part # | Firmware | Library | FMRX Component | AM_SW_LWRX Component |
|---------------|----------|---------|----------------|----------------------|
| Si4734/35-D60 | 6.0 | R11 | 7.0 | 6.0 |

Table 27. Si4732 Firmware, Library, and Component Compatibility

| Part # | Firmware | Library | FMRX Component | AM_SW_LWRX Component |
|------------|----------|---------|----------------|----------------------|
| Si4732-A10 | 1.0 | R11 | 7.0 | 6.0 |

7.2.2. Patching Procedure

Patching is accomplished by sending a series of commands to the device. These commands are sent in the same manner as any other device commands and can be sent over any of the command busses (2-wire, 3-wire, SPI).

The first command that is sent to the device is the POWER_UP command to confirm that the patch is compatible with the internal device library revision. The device moves into the powerup mode, returns the reply, and moves into the powerdown mode. The POWER_UP command is sent to the device again to configure the mode of the device and additionally is used to start the patching process. When applying the patch, the PATCH bit in ARG1 of the POWER_UP command must be set to 1 to begin the patching process.

Once the POWER_UP command is sent and the device is placed in patch mode, the patch file can be sent to the device. The patch file typically has a .csg extension. It is formatted into 8 columns, consisting of a leading command (0x15 or 0x16), and 7 arguments. The controlling system must send each line of 8 bytes, wait for a CTS, then send the next set of 8, etc., until the entire patch has been sent. An example showing the first few lines and final line of a patch file is shown below.

The patch download mechanism is verified with a checksum embedded in the patch download. If the checksum fails, the part issues an error code, ERR (bit 6 of the one byte reply that is available after each 8-byte transfer), and halts. The part must be reset to recover from this error condition.

The following is an example of a patch file.

```
# Copyright 2006 Skyworks Solutions, Inc.
# Patch generated 21:09 August 09 2006
# fmtx version 0.0 alpha
0x15,0x00,0x0B,0x1D,0xBB,0x14,0xC4,0xA1
0x16,0x98,0x81,0xD9,0x71,0xED,0x0E,0xAC
.
.
[up to 1979 additional lines]
.
.
0x15,0x00,0x00,0x00,0x00,0x00,0x49,0xFD
```

A full memory patch requires 15856 bytes of system controller memory, however, most patches require significantly less memory. In 2-wire mode, a full memory patch download requires approximately 500 ms at a 400 kHz clock rate. The following is an example of the commands required to boot the device from powerdown mode using the patch file in the previous example. The device has completed the boot process when the CTS bit is set high after the last byte in the file is transferred and is ready to accept additional commands and proceed with normal operation.

Table 28 provides an example of using the POWER_UP command with patching enabled. The table is broken into three columns. The first column lists the action taking place: command (CMD), argument (ARG), status (STATUS) or response (RESP). The second column lists the data byte or bytes in hexadecimal that are being sent or received. An arrow preceding the data indicates data being sent from the device to the system controller. The third column describes the action.

Table 28. Example POWER_UP Command with Patching Enabled

| Action | Data | Description |
|--|-------|--|
| CMD | 0x01 | POWER_UP |
| ARG1 | 0xCF | Set to Read Library ID, Enable Interrupts. |
| ARG2 | 0x05 | Set to Analog Out. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x06 | Part Number, HEX (0x06 = Si4706) |
| RESP2 | →0x32 | Firmware Major Rev, ASCII (0x32 = 2) |
| RESP3 | →0x30 | Firmware Minor Rev, ASCII (0x30 = 0) |
| RESP4 | →0x00 | Reserved |
| RESP5 | →0x00 | Reserved |
| RESP6 | →0x41 | Chip Rev, ASCII (0x41 = revA) |
| RESP7 | →0x04 | Library ID, HEX (0x04 = library 4) |
| CMD | 0x01 | POWER_UP |
| ARG1 | 0xE2 | Set to FM Transmit, set patch enable, enable interrupts. |
| ARG2 | 0x50 | Set to Analog Line Input. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x15 | Reserved for Patch. |
| ARG1 | 0x00 | |
| ARG2 | 0x0B | |
| ARG3 | 0x1D | |
| ARG4 | 0xBB | |
| ARG5 | 0x14 | |
| ARG6 | 0xC4 | |
| ARG7 | 0xA1 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x16 | Reserved for Patch. |
| ARG1 | 0x98 | |
| ARG2 | 0x81 | |
| ARG3 | 0xD9 | |
| ARG4 | 0x71 | |
| ARG5 | 0xED | |
| ARG6 | 0x0E | |
| ARG7 | 0xAC | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| <p style="text-align: center;">[up to 1979 additional lines]</p> | | |

Table 28. Example POWER_UP Command with Patching Enabled (Continued)

| | | |
|--------|-------|-----------------------------------|
| CMD | 0x15 | Reserved for Patch. |
| ARG1 | 0x00 | |
| ARG2 | 0x00 | |
| ARG3 | 0x00 | |
| ARG4 | 0x00 | |
| ARG5 | 0x00 | |
| ARG6 | 0x49 | |
| ARG7 | 0xFD | Reply Status. Clear-to-send high. |
| STATUS | →0x80 | |

8. Powerdown

The procedure for moving the device from powerup to powerdown modes requires writing the POWER_DOWN command.

Table 29. Using the POWER_DOWN command

| Action | Data | Description |
|--------|-------|-----------------------------------|
| CMD | 0x11 | POWER_DOWN |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

To Power Down the device and remove VDD and VIO (optional):

- 1. Set RCLK = 0 (optional).
Note that the RCLK buffer is in the VIO supply domain and may therefore be supplied at any time that VIO is supplied. The RCLK must be valid 10 ns before and 10 ns after sending commands. In addition, the RCLK must be valid at all times for proper AFC operation. The RCLK may be removed or reconfigured at other times.
- 2. Write POWER_DOWN to the command register.
Note that all register contents will be lost.
- 3. Set $\overline{\text{RST}} = 0$.
Note that $\overline{\text{RST}}$ must be held high for 10 ns after the completion of the POWER_DOWN command.
- 4. Remove VDD (optional).
- 5. Remove VIO (optional).
Note that VIO must not be removed without removing VDD. **Unexpected device operation may result.**

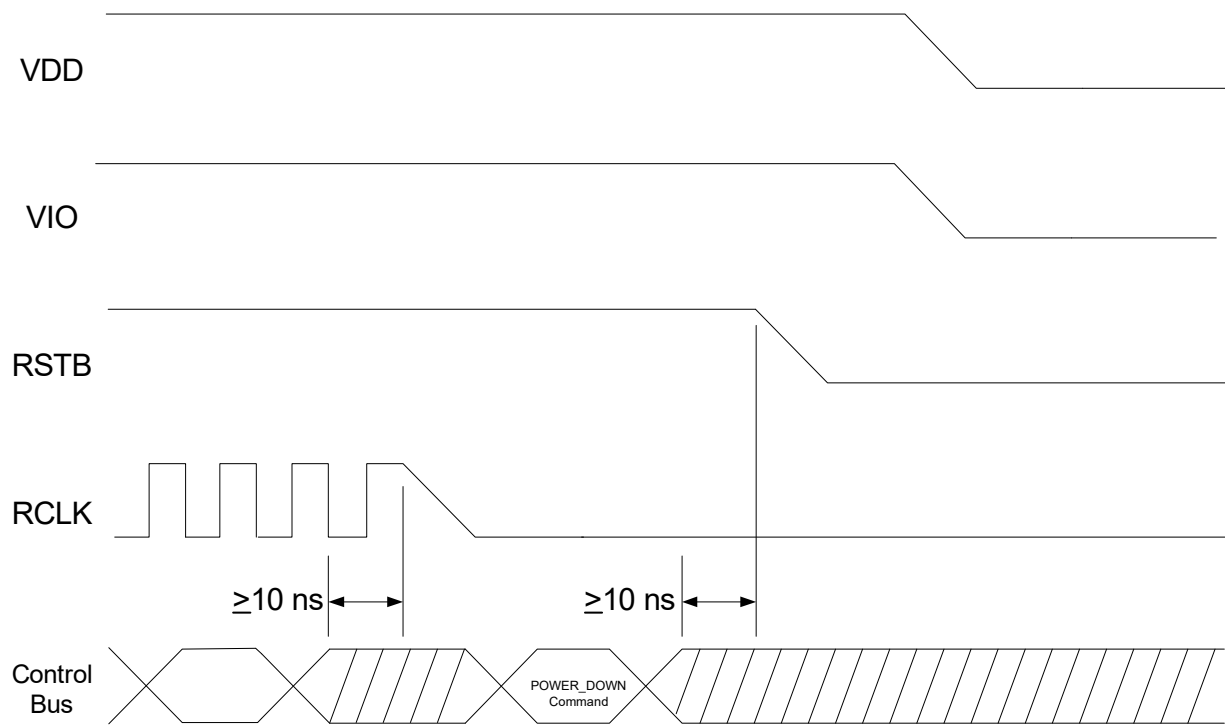


Figure 19. Device Power Down Timing

9. Digital Audio Interface

The digital audio interface operates in slave mode and supports 3 different audio data formats:

- I²S
- Left-Justified
- DSP Mode

In I²S mode, the MSB is captured on the second rising edge of DCLK following each DFS transition. The remaining bits of the word are sent in order down to the LSB. The Left Channel is transferred first when the DFS is low, and the Right Channel is transferred when the DFS is high.

In Left-Justified mode, the MSB is captured on the first rising edge of DCLK following each DFS transition. The remaining bits of the word are sent in order down to the LSB. The Left Channel is transferred first when the DFS is high, and the Right Channel is transferred when the DFS is low.

In DSP mode, the DFS becomes a pulse with a width of 1 DCLK period. The Left Channel is transferred first, followed right away by the Right Channel. There are two options in transferring the digital audio data in DSP mode: the MSB of the left channel can be transferred on the first rising edge of DCLK following the DFS pulse or on the second rising edge.

In all audio formats, depending on the word size, DCLK frequency and sample rates, there may be unused DCLK cycles after the LSB of each word before the next DFS transition and MSB of the next word.

The number of audio bits can be configured for 8, 16, 20, or 24 bits.

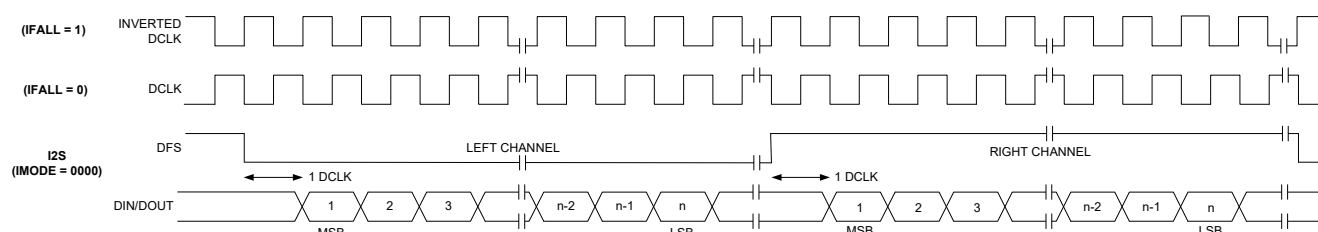


Figure 20. I²S Digital Audio Format

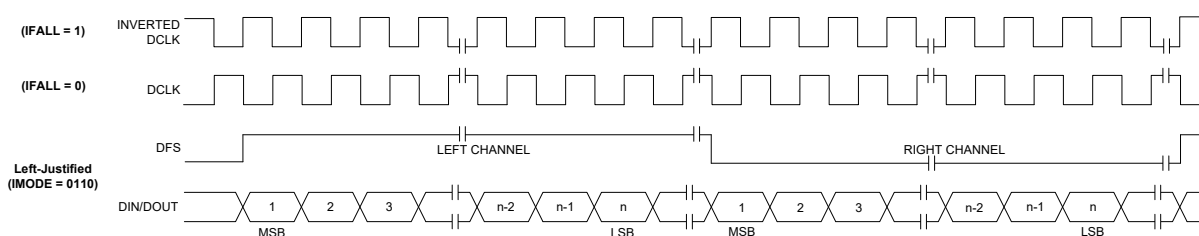


Figure 21. Left-Justified Digital Audio Format

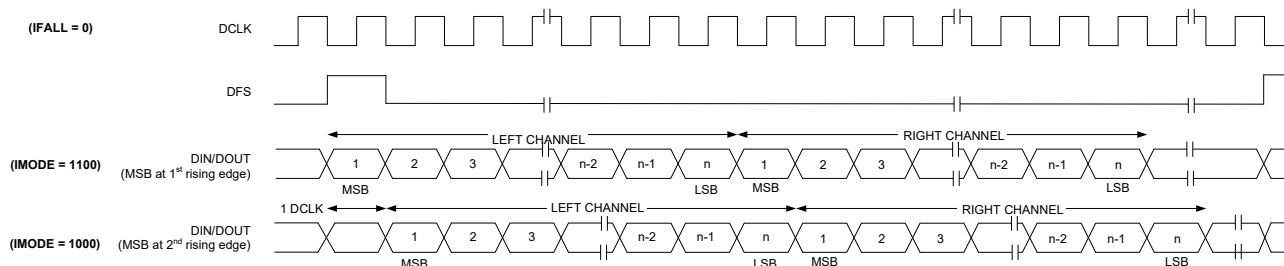


Figure 22. DSP Digital Audio Format

There is one additional property for AM/FM/SW/LW Receiver associated with using digital audio output.

For AM/FM/SW/LW Receiver:

1. Property 0x0102: DIGITAL_OUTPUT_FORMAT
2. Property 0x0104: DIGITAL_OUTPUT_SAMPLE_RATE

The procedure for using a digital audio is as follow:

1. When the device is powered up, the default value for DIGITAL_OUTPUT_SAMPLE_RATE is 0 (disable digital audio out).
2. User then must supply DCLK and DFS prior to setting the DIGITAL_OUTPUT_SAMPLE_RATE property.
3. This procedure can be applied anytime after the chip is powered up.
4. User may also change or disable DCLK/DFS during operation. Prior to changing or disabling DCLK/DFS, user has to set the DIGITAL_OUTPUT_SAMPLE_RATE property to 0. After changing or re-enabling DCLK/DFS, user then can set the sample rate property again.
5. The property DIGITAL_OUTPUT_FORMAT does not have a condition, thus it can be set anywhere after power up.

Notes:

1. Failure to provide DCLK and DFS prior to setting the sample rate property may cause the chip to go into an unknown state and user must reset the chip.
 2. The DIGITAL_OUTPUT_SAMPLE_RATE is the audio sampling rate (DFS rate) and is valid between 32kHz and 48kHz.
- The following table is a programming example of how to use digital audio.

Table 30. Digital Audio Programming Example

| Action | Data | Description |
|---|---|---|
| | | Action: POWER UP CHIP (look at respective programming example of power up in digital mode). |
| | | Action: User can send other commands or properties here. |
| | | Action: Supply DCLK and DFS. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x01 0x04 0xBB 0x80 →0x80 | SET_PROPERTY DIGITAL_OUTPUT_SAMPLE_RATE Sample rate = 0xBB80 = 48000Hz Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x01 0x02 0x00 0x00 →0x80 | SET_PROPERTY DIGITAL_OUTPUT_FORMAT Mode: I2S, stereo, 16bit, sample on rising edge of DCLK Reply Status. Clear-to-send high. |
| | | Action: User can send other commands or properties here. |
| | | Action: User needs to change or disable DCLK/DFS. |

Table 30. Digital Audio Programming Example

| | | |
|--------------|-------|--|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x01 | |
| ARG3 (PROP) | 0x04 | DIGITAL_OUTPUT_SAMPLE_RATE |
| ARG4 (PROPD) | 0x00 | Sample rate = 0 (disable digital audio) |
| ARG5 (PROPD) | 0x00 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| | | Action: User now is allowed to change or disabling DCLK/DFS. |
| | | Action: DCLK/DFS has been changed or re-enabled. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x01 | |
| ARG3 (PROP) | 0x04 | DIGITAL_OUTPUT_SAMPLE_RATE |
| ARG4 (PROPD) | 0xBB | Sample rate = 0xBB80 = 48000Hz |
| ARG5 (PROPD) | 0x80 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| | | Action: User can send other commands or properties here. |

10. Timing

There are two indicators: CTS (Clear to Send) and STC (Seek/Tune Complete) to indicate that a command has been accepted and execution completed by the part.

After sending every command, the CTS bit will be set indicating that the command has been accepted by the part and it is ready to receive the next command. The CTS bit, on most commands, also indicates that the command has completed execution. These commands are:

1. POWER_UP, POWER_DOWN, GET_REV, GET_PROPERTY, GPIO_CTL, GPIO_SET
2. On FM Receive component: FM_TUNE_STATUS, FM_RSQ_STATUS, FM_RDS_STATUS
3. On AM/SW/LW Receive component: AM_TUNE_STATUS, AM_RSQ_STATUS

The CTS timing model is shown in Figure 23.

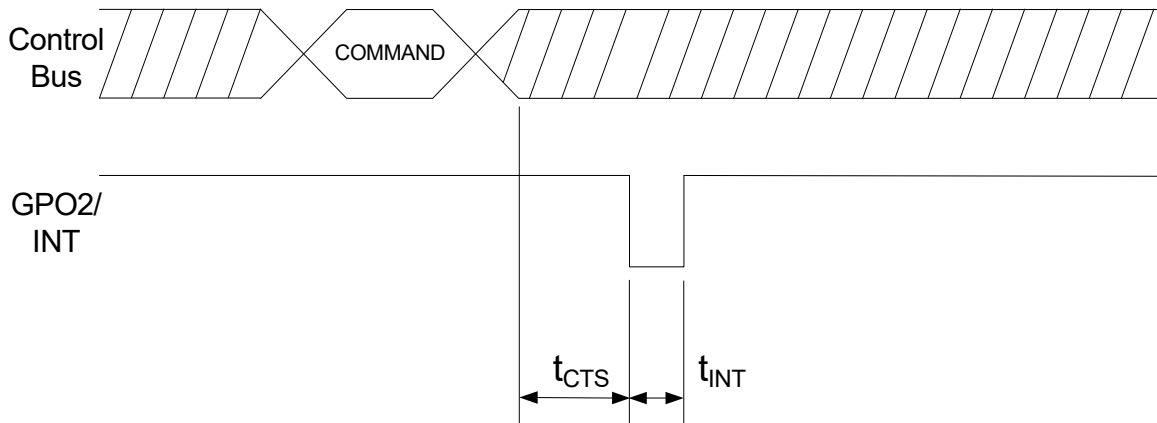


Figure 23. CTS Timing Model

In addition to CTS bit, there are a few commands (e.g., FM_TUNE_FREQ) that use the STC bit to indicate that the command has completed execution. It is highly recommended that user waits for the STC bit before sending the next command. When interrupt is not used, user can poll the status of this STC bit by sending the GET_INT_STATUS command until the STC bit has been set before sending the next command.

Commands that use STC bit to indicate execution has been completed:

1. On FM Receive component: FM_TUNE_FREQ, FM_SEEK_START
2. On AM/SW/LW Receive component: AM_TUNE_FREQ, AM_SEEK_START

The CTS and STC timing model is shown in Figure 24.

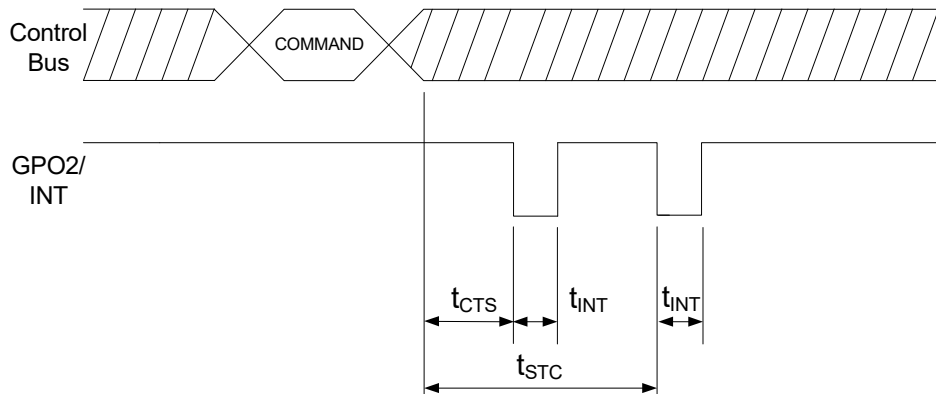


Figure 24. CTS and STC Timing Model

The SET_PROPERTY command does not have an indicator telling when the command has completed execution, rather the timing is guaranteed and it is called t_{COMP} . The CTS and SET_PROPERTY command completion timing model t_{COMP} is shown in Figure 25.

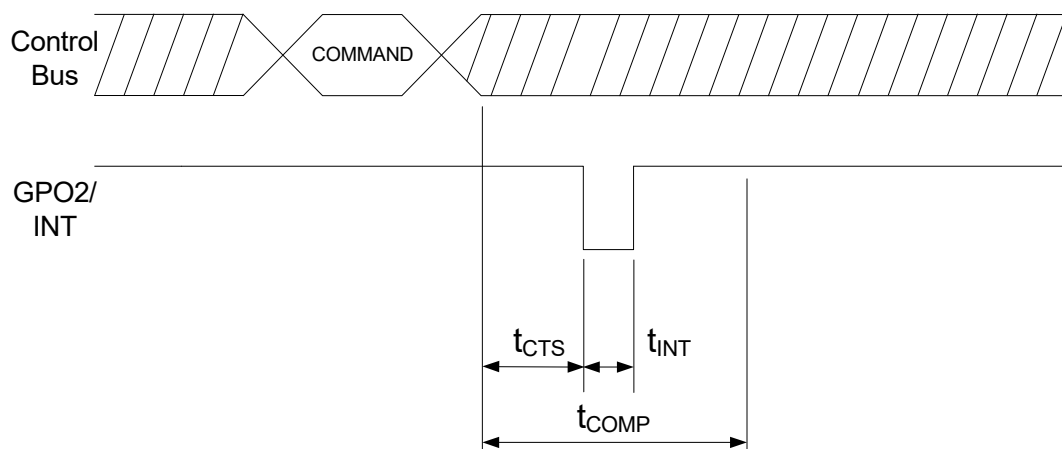


Figure 25. CTS and SET_PROPERTY Command Complete t_{COMP} Timing Model

Table 31. Command Timing Parameters for the FM Receiver

| Command | t _{CTS} | t _{STC} | t _{COMP} | t _{INT} |
|-----------------|------------------|--------------------|-------------------|------------------|
| POWER_UP | 110 ms | — | — | 1 μs |
| POWER_DOWN | 300 μs | — | — | |
| GET_REV | | — | — | |
| GET_PROPERTY | | — | — | |
| GET_INT_STATUS | | — | — | |
| PATCH_ARGS | | — | — | |
| PATCH_DATA | | — | — | |
| FM_RSQ_STATUS | | — | — | |
| FM_RDS_STATUS | | — | — | |
| FM_TUNE_STATUS | | — | — | |
| FM_TUNE_FREQ | | 60 ms ¹ | — | |
| FM_SEEK_START | | 60 ms ² | — | |
| SET_PROPERTY | | — | 10 ms | |
| FM_AGC_STATUS | | — | — | |
| FM_AGC_OVERRIDE | | — | — | |
| GPIO_CTL | | — | — | |
| GPIO_SET | | — | — | |

Notes:

1. t_{STC} for FM_TUNE_FREQ / FM_SEEK_START commands is 80 ms on FMRX component 2.0 and earlier.
2. t_{STC} is seek time per channel. Total seek time depends on bandwidth, channel spacing, and number of channels to next valid channel.

Worst case seek time complete for FM_SEEK_START is:

$$\left(\left(\frac{\text{FM_SEEK_BAND_TOP} - \text{FM_SEEK_BAND_BOTTOM}}{\text{FM_SEEK_FREQ_SPACING}} \right) + 1 \right) \times t_{\text{STC}}$$

for USA FM:

$$\left(\left(\frac{10790 - 8750}{20} \right) + 1 \right) \times 60 \text{ ms} = 6.2 \text{ s}$$

Table 32. Command Timing Parameters for the AM Receiver

| Command | t _{CTS} | t _{STC} | t _{COMP} | t _{INT} |
|----------------|------------------|------------------|-------------------|------------------|
| POWER_UP | 110 ms | — | — | 1 μs |
| POWER_DOWN | 300 μs | — | — | |
| GET_REV | | — | — | |
| GET_PROPERTY | | — | — | |
| GET_INT_STATUS | | — | — | |
| PATCH_ARGS | | — | — | |
| PATCH_DATA | | — | — | |
| AM_RSQ_STATUS | | — | — | |
| AM_TUNE_STATUS | | — | — | |
| AM_TUNE_FREQ | | 80 ms | — | |
| AM_SEEK_START | | 80 ms* | — | |
| SET_PROPERTY | | — | 10 ms | |
| GPIO_CTL | | — | — | |
| GPIO_SET | | — | — | |

***Note:** t_{STC} is seek time per channel. The worst-case seek time per channel is 200 ms. Total seek time depends on bandwidth, channel spacing, and number of channels to next valid channel.

Worst case seek time complete for AM_SEEK_START is:

$$\left(\left(\frac{\text{AM_SEEK_BAND_TOP} - \text{AM_SEEK_BAND_BOTTOM}}{\text{AM_SEEK_FREQ_SPACING}}\right) + 1\right) \times t_{\text{STC}}$$

for USA AM:

$$\left(\left(\frac{1710 - 520}{10}\right) + 1\right) \times 200 \text{ ms} = 24.0 \text{ s}$$

Table 33. Command Timing Parameters for the Stereo Audio ADC Mode

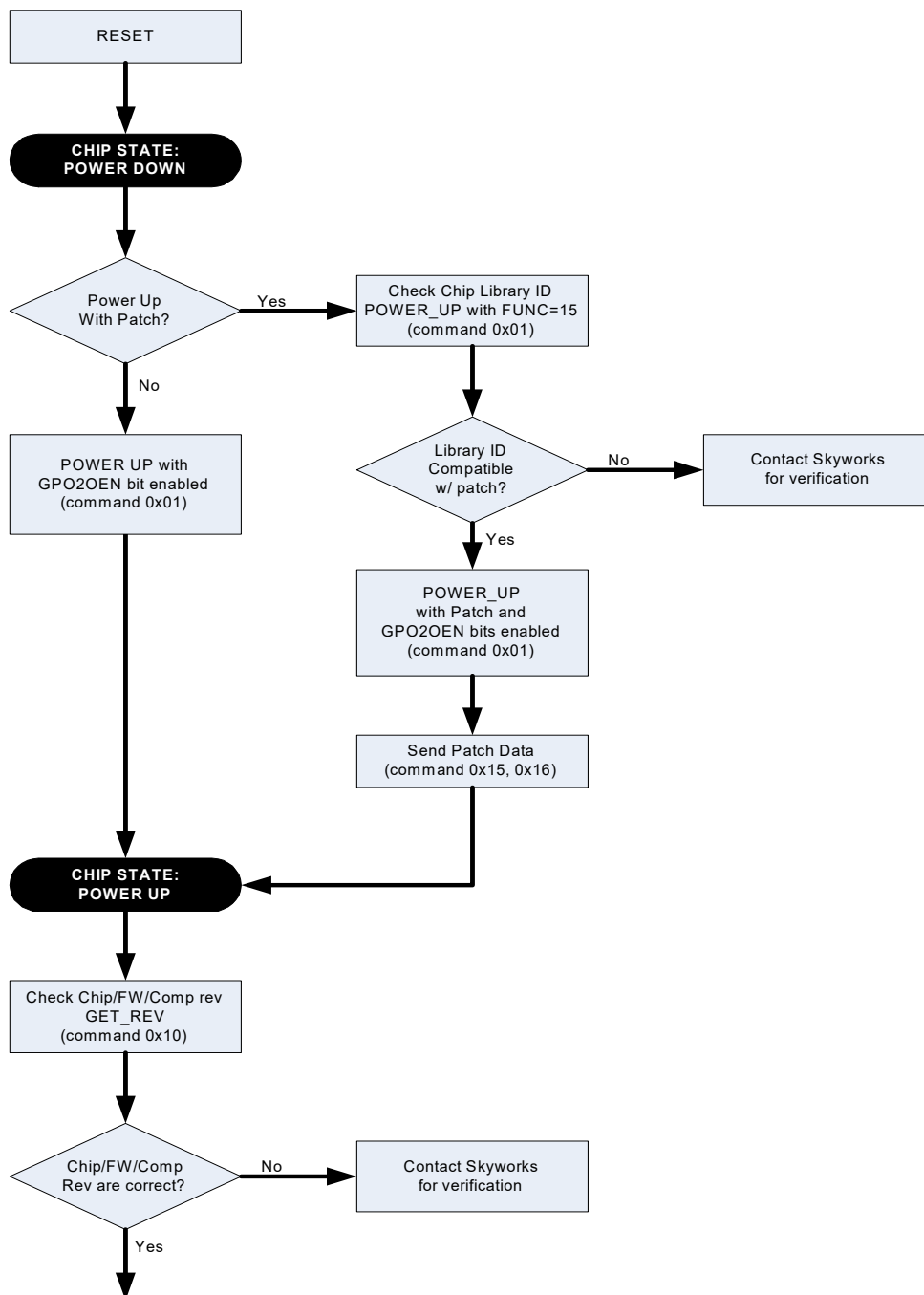
| Command | t _{CTS} | t _{COMP} | t _{INT} |
|----------------|------------------|-------------------|------------------|
| POWER_UP | 110 ms | — | 1 μs |
| POWER_DOWN | 300 μs | — | |
| GET_REV | | — | |
| GET_PROPERTY | | — | |
| GET_INT_STATUS | | — | |
| AUX_ASRC_START | | — | |
| AUX_ASQ_STATUS | | — | |
| GPIO_CTL | | — | |
| GPIO_SET | | — | |
| SET_PROPERTY | | 10 ms | |

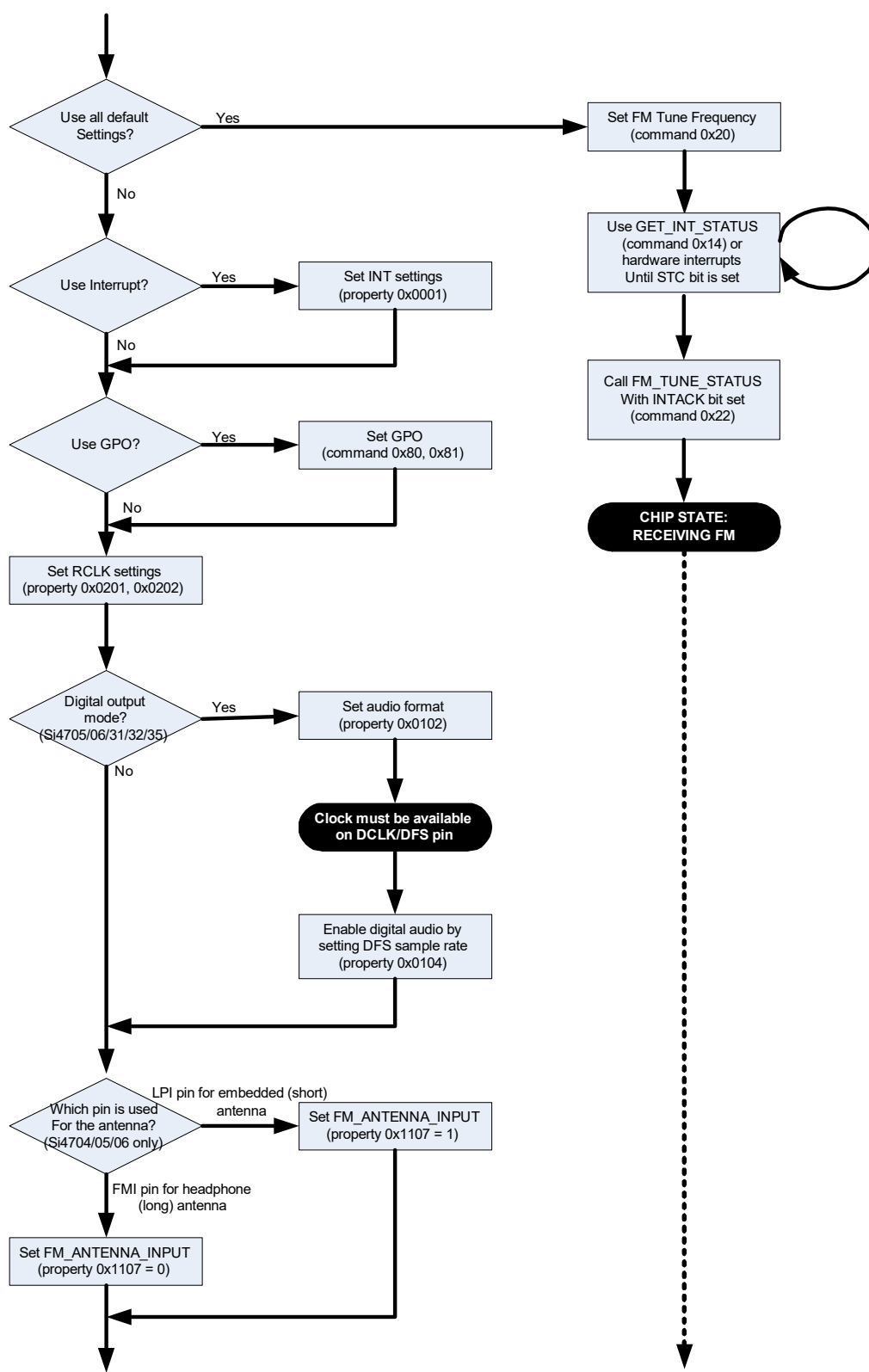
11. Programming Examples

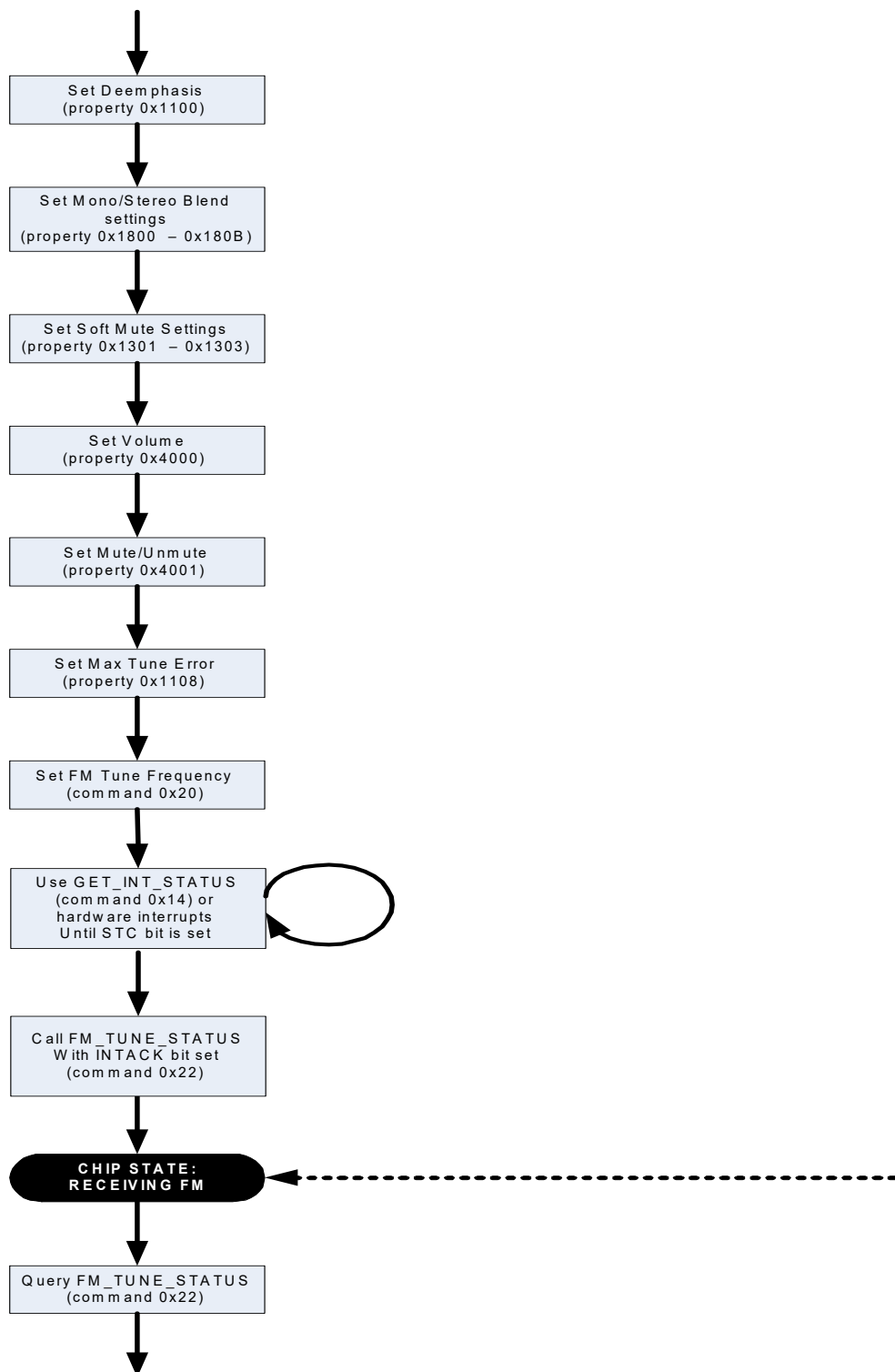
This section contains the programming example for each of the functions: FM Receive and AM/SW/LW Receive. Before each of the example, an overview of how to program the device is shown as a flowchart. Skyworks Solutions also provides the actual software (example code) and it can be downloaded from skyworksinc.com as AN332SW.

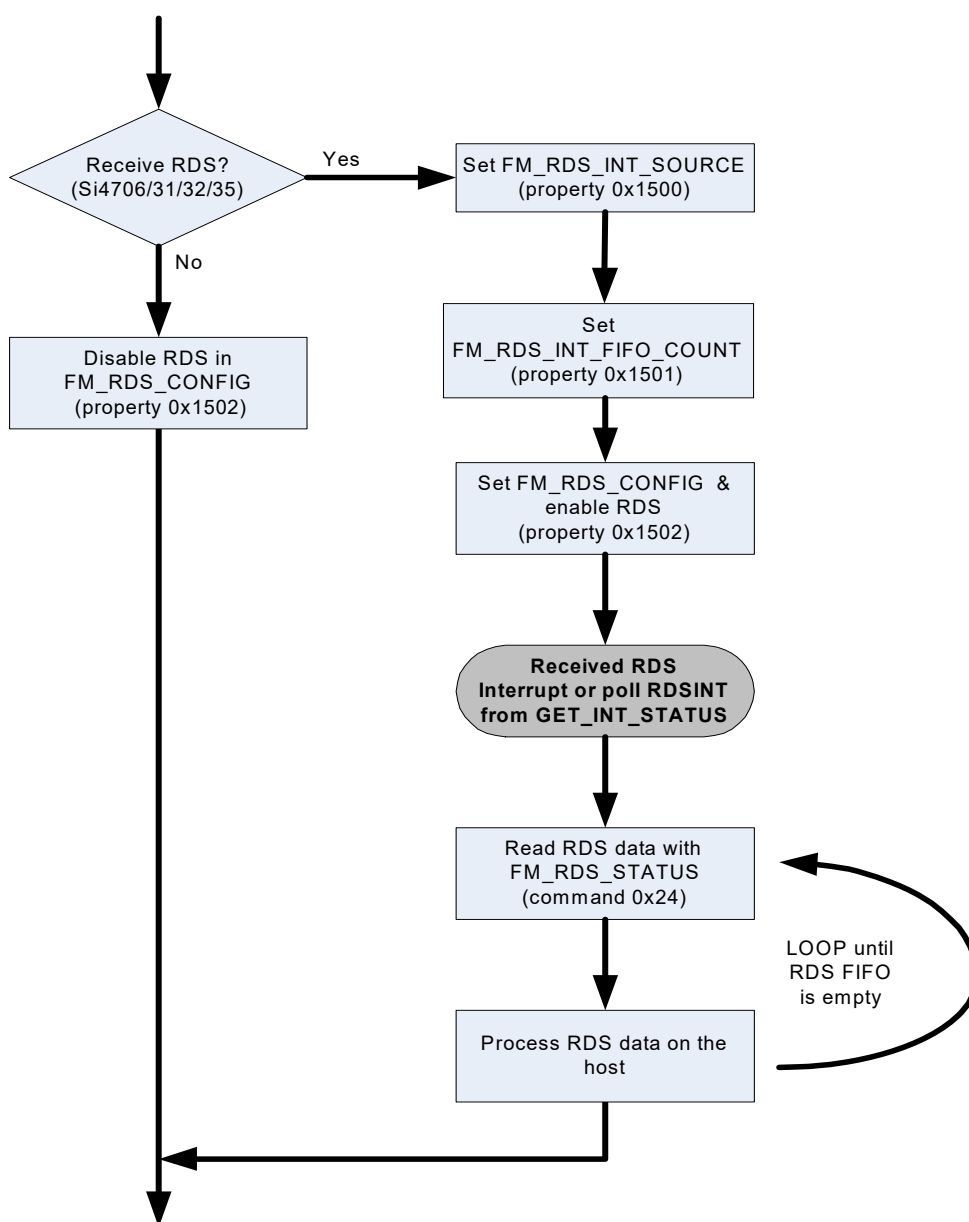
11.1. Programming Example for the FM/RDS Receiver

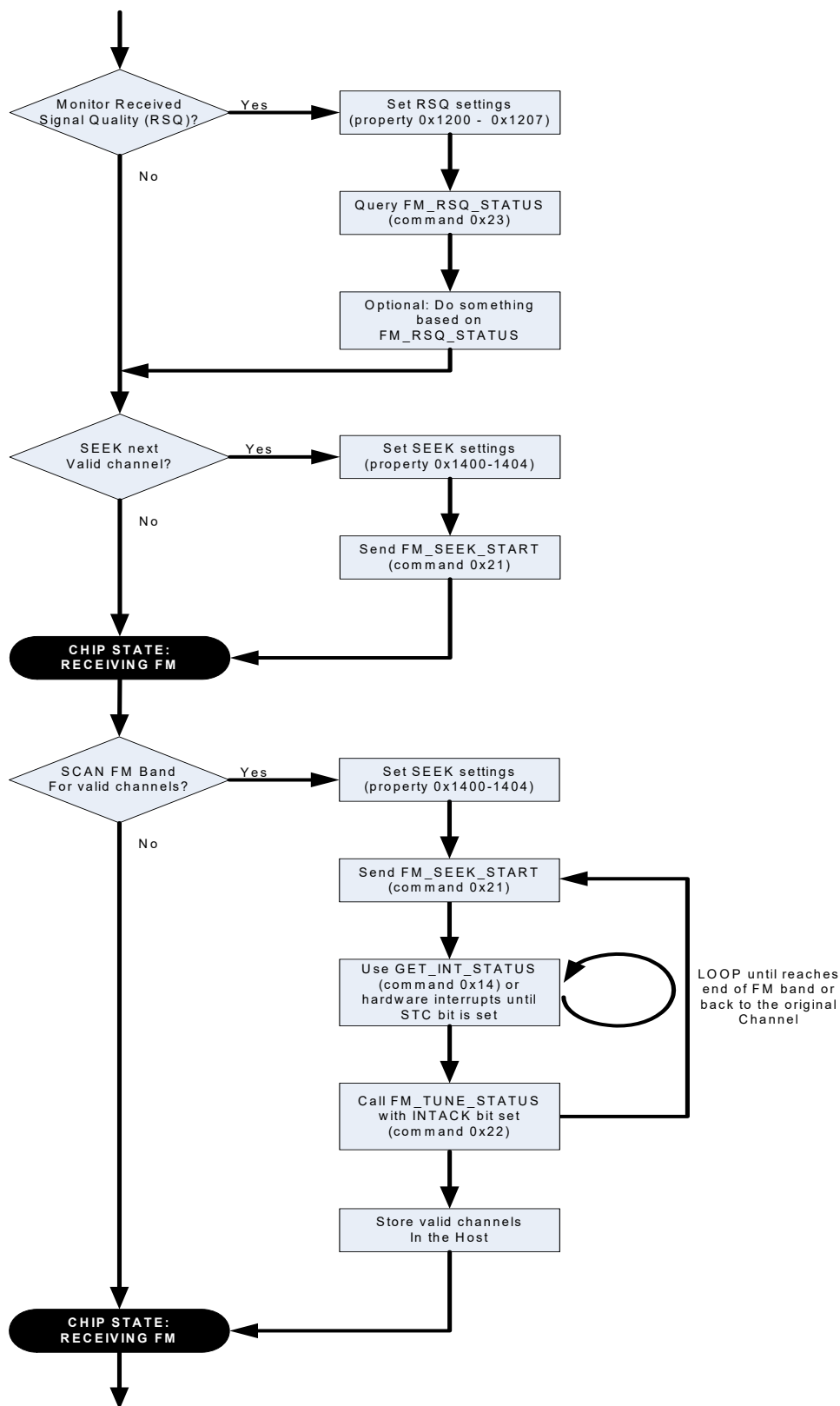
The following is a flowchart showing the overview of how to program the FM/RDS Receiver.











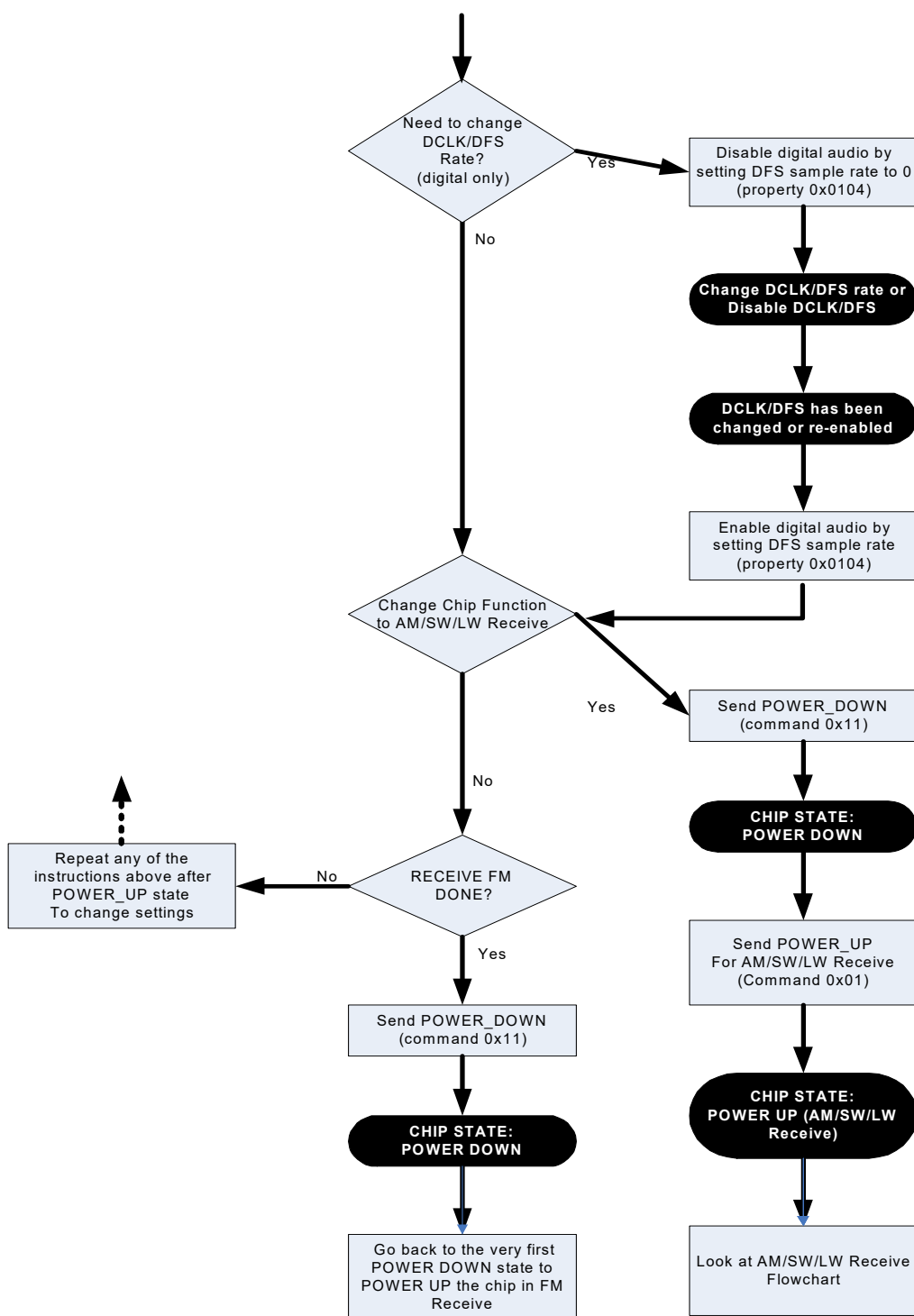


Table 34 provides an example for the FM/RDS Receiver. The table is broken into three columns. The first column lists the action taking place: command (CMD), argument (ARG), status (STATUS) or response (RESP). For SET_PROPERTY commands, the property (PROP) and property data (PROPD) are indicated. The second column lists the data byte or bytes in hexadecimal that are being sent or received. An arrow preceding the data indicates data being sent from the device to the system controller. The third column describes the action.

In some cases the default properties may be acceptable and no modification is necessary. Refer to Section “5. Commands and Properties” for a full description of each command and property.

Table 34. Programming Example for the FM/RDS Receiver

| Action | Data | Description |
|--------------------------------|-------|--|
| Powerup in Digital Mode | | |
| CMD | 0x01 | POWER_UP |
| ARG1 | 0xC0 | Set to FM Receive. Enable interrupts. |
| ARG2 | 0xB0 | Set to Digital Audio Output |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| | | Action: Ensure that DCLK and DFS are already supplied |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x01 | DIGITAL_OUTPUT_SAMPLE_RATE |
| ARG3 (PROP) | 0x04 | |
| ARG4 (PROPD) | 0xBB | Sample rate = 48000 Hz = 0xBB80 |
| ARG5 (PROPD) | 0x80 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x01 | DIGITAL_OUTPUT_FORMAT |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | Mode: I2S, stereo, 16bit, sample on rising edge of DCLK. |
| ARG5 (PROPD) | 0x00 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| | | Action: Go to Configuration (bypass “Powerup in analog mode” section). The rest of the programming is the same as analog. |
| Powerup in Analog Mode | | |
| CMD | 0x01 | POWER_UP |
| ARG1 | 0xC0 | Set to FM Receive. Enable interrupts. |
| ARG2 | 0x05 | Set to Analog Audio Output |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| Configuration | | |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------------|-------|--|
| CMD | 0x10 | GET_REV |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x1F | Part Number, HEX (0x1F = 31 dec. = Si4731) |
| RESP2 | →0x32 | Firmware Major Rev, ASCII (0x32 = 2) |
| RESP3 | →0x30 | Firmware Minor Rev, ASCII (0x30 = 0) |
| RESP4 | →0x85 | Patch ID MSB, example only |
| RESP5 | →0xC5 | Patch ID LSB, example only |
| RESP6 | →0x32 | Component Firmware Major Rev, ASCII (0x32 = 2) |
| RESP7 | →0x30 | Component Firmware Minor Rev, ASCII (0x30 = 0) |
| RESP8 | →0x42 | Chip Rev, ASCII (0x42 = revB) |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | GPO_IEN |
| ARG2 (PROP) | 0x00 | |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x00 | Set STCIEN, ERRIEN, CTSIEN, RSQIEN |
| ARG5 (PROPD) | 0xC9 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x02 | REFCLK_FREQ |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x7E | REFCLK = 32500 Hz |
| ARG5 (PROPD) | 0xF4 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x02 | REFCLK_PRESCALE |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x01 | Divide by 400 |
| ARG5 (PROPD) | 0x90 | (example RCLK = 13 MHz, REFCLK = 32500 Hz) |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x40 | RX_VOLUME |
| ARG3 (PROP) | 0x00 | |
| ARG4 (PROPD) | 0x00 | Output Volume = 63 |
| ARG5 (PROPD) | 0x3F | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x11 | FM_DEEMPHASIS |
| ARG3 (PROP) | 0x00 | |
| ARG4 (PROPD) | 0x00 | 50 μ s |
| ARG5 (PROPD) | 0x01 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|---|---|---|
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x40 0x01 0x00 0x00 →0x80 | SET_PROPERTY RX_HARD_MUTE Enable L and R audio outputs Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x18 0x00 0x00 0x31 →0x80 | SET_PROPERTY FM_BLEND_RSSI_STEREO_THRESHOLD Threshold = 49dB μ V = 0x0031 Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x18 0x01 0x00 0x1E →0x80 | SET_PROPERTY FM_BLEND_RSSI_MONO_THRESHOLD Threshold = 30 dB μ V = 0x001E Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x11 0x08 0x00 0x28 →0x80 | SET_PROPERTY FM_MAX_TUNE_ERROR Threshold = 40 kHz = 0x0028 Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x12 0x00 0x00 0x8F →0x80 | SET_PROPERTY FM_RSQ_INT_SOURCE Enable blend, SNR high, SNR low, RSSI high and RSSI low interrupts. Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x12 0x01 0x00 0x1E →0x80 | SET_PROPERTY FM_RSQ_SNR_HI_THRESHOLD Threshold = 30 dB = 0x001E Reply Status. Clear-to-send high. Clear-to-send high. |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------------|-------|-------------------------------------|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x12 | FM_RSQ_SNR_LO_THRESHOLD |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | Threshold = 6 dB = 0x0006 |
| ARG5 (PROPD) | 0x06 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x12 | FM_RSQ_RSSI_HI_THRESHOLD |
| ARG3 (PROP) | 0x03 | |
| ARG4 (PROPD) | 0x00 | Threshold = 50 dB μ V = 0x0032 |
| ARG5 (PROPD) | 0x32 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x12 | FM_RSQ_RSSI_LO_THRESHOLD |
| ARG3 (PROP) | 0x04 | |
| ARG4 (PROPD) | 0x00 | Threshold = 24 dB μ V = 0x0018 |
| ARG5 (PROPD) | 0x18 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x12 | FM_RSQ_BLEND_THRESHOLD |
| ARG3 (PROP) | 0x07 | |
| ARG4 (PROPD) | 0x00 | Pilot = 1, Threshold = 50% = 0x0032 |
| ARG5 (PROPD) | 0xB2 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x13 | FM_SOFT_MUTE_MAX_ATTENUATION |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | Attenuation = 10 dB = 0x000A |
| ARG5 (PROPD) | 0x0A | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x13 | FM_SOFT_MUTE_SNR_THRESHOLD |
| ARG3 (PROP) | 0x03 | |
| ARG4 (PROPD) | 0x00 | Threshold = 6 dB = 0x0006 |
| ARG5 (PROPD) | 0x06 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|---|---|---|
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x14 0x00 0x22 0x6A →0x80 | SET_PROPERTY FM_SEEK_BAND_BOTTOM Bottom Freq = 88.1 MHz = 0x226A Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x14 0x01 0x2A 0x26 →0x80 | SET_PROPERTY FM_SEEK_BAND_TOP Top Freq = 107.9 MHz = 0x2A26 Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x14 0x02 0x00 0x14 →0x80 | SET_PROPERTY FM_SEEK_FREQ_SPACING Freq Spacing = 200 kHz = 0x0014 Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x14 0x03 0x00 0x06 →0x80 | SET_PROPERTY FM_SEEK_TUNE_SNR_THRESHOLD Threshold = 6 dB = 0x0006 Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 (PROP) ARG3 (PROP) ARG4 (PROPD) ARG5 (PROPD) STATUS | 0x12 0x00 0x14 0x04 0x00 0x14 →0x80 | SET_PROPERTY FM_SEEK_TUNE_RSSI_THRESHOLD Threshold = 20 dBμV = 0x0014 Reply Status. Clear-to-send high. |
| CMD ARG1 ARG2 ARG3 ARG4 STATUS | 0x20 0x00 0x27 0xF6 0x00 →0x80 | FM_TUNE_FREQ Set frequency to 102.3 MHz = 0x27F6 Set antenna tuning capacitor to auto. Reply Status. Clear-to-send high. |
| CMD STATUS | 0x14 →0x81 | GET_INT_STATUS Reply Status. Clear-to-send high. STCINT = 1. |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|-----------------------------------|-------|--|
| CMD | 0x22 | FM_TUNE_STATUS |
| ARG1 | 0x01 | Clear STC interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x01 | Valid Frequency. |
| RESP2 | →0x27 | Frequency = 0x27F6 = 102.3 MHz |
| RESP3 | →0xF6 | |
| RESP4 | →0x2D | RSSI = 45 dBμV |
| RESP5 | →0x33 | SNR = 51 dB |
| RESP6 | →0x00 | |
| RESP7 | →0x00 | Antenna tuning capacitor = 0 (range = 0–191) |
| CMD | 0x23 | FM_RSQ_STATUS |
| ARG1 | 0x01 | Clear RSQINT |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x00 | No blend, SNR high, low, RSSI high or low interrupts. |
| RESP2 | →0x01 | Soft mute is not engaged, no AFC rail, valid frequency. |
| RESP3 | →0xD9 | Pilot presence, 89% blend |
| RESP4 | →0x2D | RSSI = 45 dBμV |
| RESP5 | →0x33 | SNR = 51 dB |
| RESP6 | →0x00 | |
| RESP7 | →0x00 | Freq offset = 0 kHz |
| CMD | 0x21 | FM_SEEK_START |
| ARG1 | 0x0C | Seek Up and Wrap. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x14 | GET_INT_STATUS |
| STATUS | →0x81 | Reply Status. Clear-to-send high. STCINT = 1. |
| CMD | 0x22 | FM_TUNE_STATUS |
| ARG1 | 0x01 | Clear STC interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x01 | Valid Frequency. |
| RESP2 | →0x28 | Frequency = 0x286E = 103.5 MHz |
| RESP3 | →0x6E | |
| RESP4 | →0x22 | RSSI = 34 dBμV |
| RESP5 | →0x2C | SNR = 44 dB |
| RESP6 | →0x00 | |
| RESP7 | →0x00 | Antenna tuning capacitor = 0 (range = 0–191) |
| RDS (Si4706/31/32/35 Only) | | |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2(PROP) | 0x15 | FM_RDS_INT_SOURCE |
| ARG3(PROP) | 0x00 | Enable RDSRECV interrupt (set RDSINT bit when RDS has filled the FIFO by the amount set on FM_RDS_INTERRUPT_FIFO_COUNT |
| ARG4(PROPD) | 0x00 | |
| ARG5(PROPD) | 0x01 | Reply Status. Clear-to-send high |
| STATUS | →0x80 | |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|-------------|-------|--|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2(PROP) | 0x15 | FM_RDS_INT_FIFO_COUNT |
| ARG3(PROP) | 0x01 | |
| ARG4(PROPD) | 0x00 | Set the minimum number of RDS groups stored in the RDS FIFO before RDSRECV is set |
| ARG5(PROPD) | 0x04 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2(PROP) | 0x15 | FM_RDS_CONFIG |
| ARG3(PROP) | 0x02 | |
| ARG4(PROPD) | 0xEF | Set Block Error A,B,C,D to 3,2,3,3 |
| ARG5(PROPD) | 0x01 | Enable RDS |
| STATUS | →0x80 | Reply Status. Clear-to-send high |
| CMD | 0x14 | GET_INT_STATUS |
| STATUS | →0x84 | Reply Status. Clear-to-send high. RDSINT = 1 |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x84 | Reply Status. Clear-to-send (CTS) high. RDS interrupt (RDSINT) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x17 | RDS FIFO Used: 0x17 = 23. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2000 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x00 | → PTY: 00000b (Undefined) |
| | | → Address code: 0000b = 0 (char 1,2,3,4) |
| RESP8 | →0x53 | Block C: 0x5349 →SI |
| RESP9 | →0x49 | |
| RESP10 | →0x4C | Block D: 0x4C49 →LI |
| RESP11 | →0x49 | |
| RESP12 | →0x00 | BLE: 0 (No Error) |
| | | Current RT: "SILI" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x16 | RDS FIFO Used: 0x16 = 22. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0C | → PTY: 00000b (Undefined) |
| | | → Address code: 00b = 0 (char 1,2) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x53 | Block D: 0x5349 →SI |
| RESP11 | →0x49 | |
| RESP12 | →0x00 | BLE: 0 (No Error) |
| | | Current PS: "SI" |
| | | Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x15 | RDS FIFO Used: 0x15 = 21. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2001 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x01 | → PTY: 00000b (Undefined) |
| | | → Address code: 0001b = 1 (char 5,6,7,8) |
| RESP8 | →0x43 | Block C: 0x434F →CO |
| RESP9 | →0x4F | |
| RESP10 | →0x4E | Block D: 0x4E20 →N |
| RESP11 | →0x20 | |
| RESP12 | →0x00 | BLE: 0 (No Error) |
| | | Current RT: "SILICON" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x15 | RDS FIFO Used: 0x15 = 21 (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x09 | → PTY: 00000b (Undefined) → Address code: 01b = 1 (char 3,4) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x4C | Block D: 0x4C41 →LA |
| RESP11 | →0x41 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: "SILA" Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x14 | RDS FIFO Used: 0x14 = 20. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2002 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x02 | → PTY: 00000b (Undefined) → Address code: 0002b = 2 (char 9,10,11,12) |
| RESP8 | →0x4C | Block C: 0x4C41 →LA |
| RESP9 | →0x41 | |
| RESP10 | →0x42 | Block D: 0x424F →BO |
| RESP11 | →0x4F | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: "SILICON LABO" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x14 | RDS FIFO Used: 0x14 = 20. (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0A | → PTY: 00000b (Undefined) → Address code: 10b = 2 (char 5,6) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x42 | Block D: 0x4253 →BS |
| RESP11 | →0x53 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: "SILABS" Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x13 | RDS FIFO Used: 0x13 = 19. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2003 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x03 | → PTY: 00000b (Undefined) → Address code: 0003b = 3 (char 13,14,15,16) |
| RESP8 | →0x52 | Block C: 0x5241 →RA |
| RESP9 | →0x41 | |
| RESP10 | →0x54 | Block D: 0x544F →TO |
| RESP11 | →0x4F | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: "SILICON LABORATO" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x13 | RDS FIFO Used: 0x13 = 19. (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0B | → PTY: 00000b (Undefined) → Address code: 11b = 3 (char 7,8) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x20 | Block D: 0x2020 →” “ |
| RESP11 | →0x20 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: “SILABS” Complete Scrolling PS: “SILABS RDS DEMO” |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x12 | RDS FIFO Used: 0x12 = 18. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2004 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x04 | → PTY: 00000b (Undefined) → Address code: 0004b = 4 (char 17,18,19,20) |
| RESP8 | →0x52 | Block C: 0x5249 →RI |
| RESP9 | →0x49 | |
| RESP10 | →0x45 | Block D: 0x4553 →ES |
| RESP11 | →0x53 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: “Skyworks Solutions” |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x12 | RDS FIFO Used: 0x12 = 18. (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0C | → PTY: 00000b (Undefined) → Address code: 00b = 0 (char 1,2) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x52 | Block D: 0x5244 →RD |
| RESP11 | →0x44 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: "RDLABS Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x11 | RDS FIFO Used: 0x11 = 17. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2005 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x05 | → PTY: 00000b (Undefined) → Address code: 0005b = 5 (char 21,22,23,24) |
| RESP8 | →0x20 | Block C: 0x2053 → S |
| RESP9 | →0x53 | |
| RESP10 | →0x49 | Block D: 0x4934 →I4 |
| RESP11 | →0x34 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: "Skyworks Solutions SI4" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x10 | RDS FIFO Used: 0x10 = 16. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x09 | → PTY: 00000b (Undefined) |
| | | → Address code: 01b = 1 (char 3,4) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x53 | Block D: 0x5320 →S |
| RESP11 | →0x20 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: "RDS BS" Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0F | RDS FIFO Used: 0x0F = 15. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2006 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x06 | → PTY: 00000b (Undefined) |
| | | → Address code: 0006b = 6 (char 25, 26, 27, 28) |
| RESP8 | →0x37 | Block C: 0x3731 →71 |
| RESP9 | →0x31 | |
| RESP10 | →0x58 | Block D: 0x5820 →x |
| RESP11 | →0x20 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: "Skyworks Solutions SI471x " |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0E | RDS FIFO Used: 0x0E = 14. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000A → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0A | → PTY: 00000b (Undefined) |
| | | → Address code: 10b = 2 (char 5, 6) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x44 | Block D: 0x4445 →DE |
| RESP11 | →0x45 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: "RDS DE" Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0E | RDS FIFO Used: 0x0E = 14. (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2007 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x07 | → PTY: 00000b (Undefined) |
| | | → Address code: 0007b = 7 (char 29,30,31,32) |
| RESP8 | →0x52 | Block C: 0x5244 →RD |
| RESP9 | →0x44 | |
| RESP10 | →0x53 | Block D: 0x5320 →S |
| RESP11 | →0x20 | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: "Skyworks Solutions SI471x RDS" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

| Action | Data | Description |
|---------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0D | RDS FIFO Used: 0x0D = 13. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0B | → PTY: 00000b (Undefined) |
| | | → Address code: 11b = 3 (char 7,8) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x4D | Block D: 0x4D4F →MO |
| RESP11 | →0x4F | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current PS: "RDS DEMO" Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| +STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0D | RDS FIFO Used: 0x0D = 13. (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2008 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x08 | → PTY: 00000b (Undefined) |
| | | → Address code: 0008b = 8 (char 33,34,35,36) |
| RESP8 | →0x44 | Block C: 0x4445 →DE |
| RESP9 | →0x45 | |
| RESP10 | →0x4D | Block D: 0x4D4F →MO |
| RESP11 | →0x4F | |
| RESP12 | →0x00 | BLE: 0 (No Error) Current RT: "Skyworks Solutions SI471x RDS DEMO" |

Table 34. Programming Example for the FM/RDS Receiver (Continued)

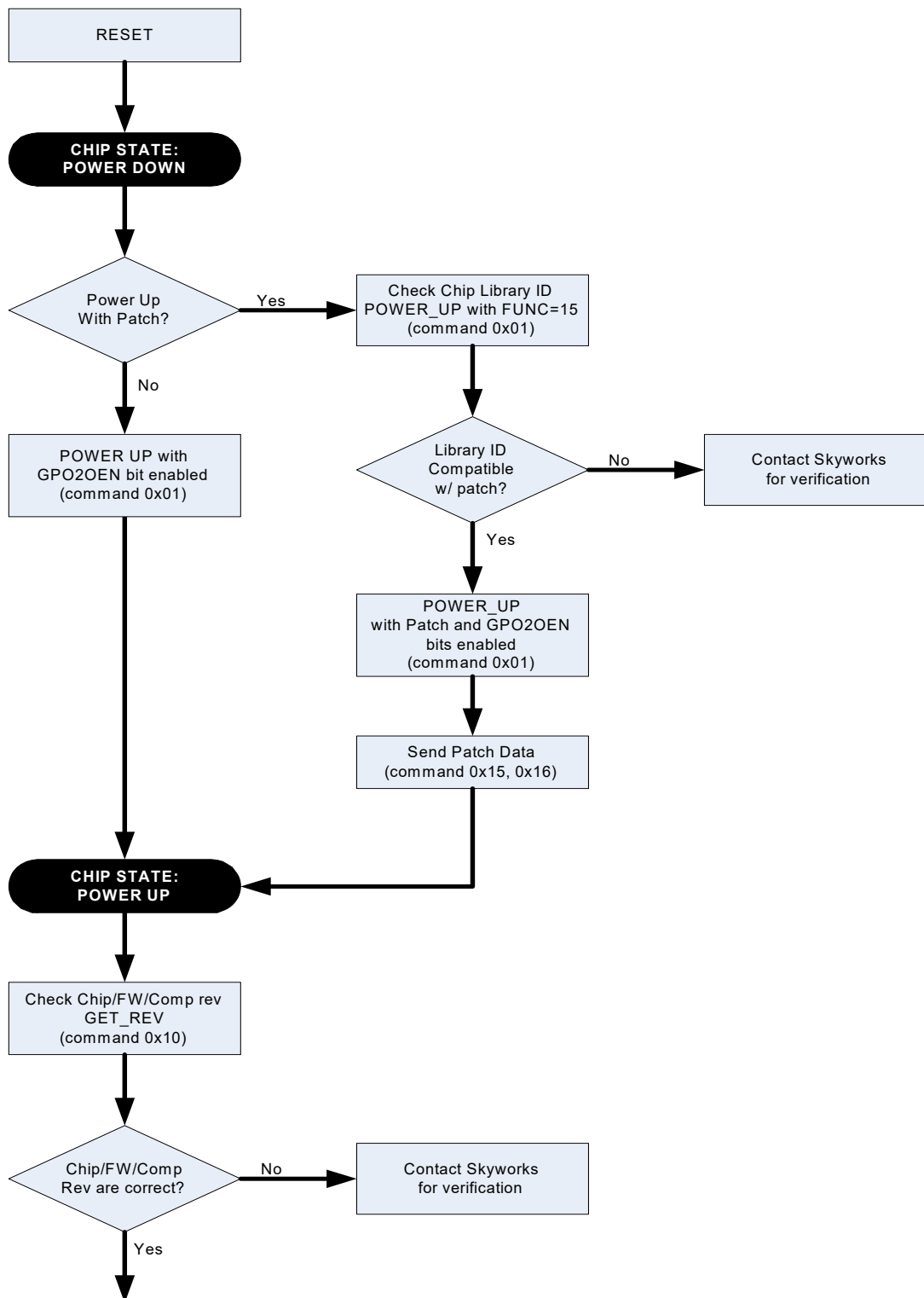
| Action | Data | Description |
|--------|-------|---|
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0C | RDS FIFO Used: 0x0C = 12. |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x00 | Block B: 0x000C → Group Type: 0A (Program Service PS) |
| RESP7 | →0x0C | → PTY: 00000b (Undefined) |
| | | → Address code: 00b = 0 (char 1,2) |
| RESP8 | →0xE1 | Block C (ignored) |
| RESP9 | →0x02 | |
| RESP10 | →0x53 | Block D: 0x5349 → SI |
| RESP11 | →0x49 | |
| RESP12 | →0x00 | BLE: 0 (No Error) |
| | | Current PS: "SIS_DEMO" Complete Scrolling PS: "SILABS RDS DEMO" |
| CMD | 0x24 | FM_RDS_STATUS |
| ARG1 | 0x01 | Clear RDS interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send (CTS) high. Seek/Tune Complete (STCINT) high. |
| RESP1 | →0x01 | Interrupt source: RDS received. |
| RESP2 | →0x01 | RDS Synchronized. No lost data. |
| RESP3 | →0x0D | RDS FIFO Used: 0x0C = 12. (FIFO receives another group while querying) |
| RESP4 | →0x40 | Block A: 0x40A7 → PI Code: 0x40A7 (KSLB). |
| RESP5 | →0xA7 | |
| RESP6 | →0x20 | Block B: 0x2009 → Group Type: 2A (Radio Text RT) |
| RESP7 | →0x09 | → PTY: 00000b (Undefined) |
| | | → Address code: 0009b = 9 (char 37,38,39,40) |
| RESP8 | →0x0D | Block C: 0x0D00 → 'RET' 'NUL' (end of RT) |
| RESP9 | →0x00 | |
| RESP10 | →0x00 | Block D: 0x0000 → 'NUL' 'NUL' |
| RESP11 | →0x00 | |
| RESP12 | →0x00 | BLE: 0 (No Error) |
| | | Current RT: "Skyworks Solutions SI471x RDS DEMO" |
| | | - continue sending FM_RDS_STATUS until FIFO empty - |
| CMD | 0x11 | POWER_DOWN |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

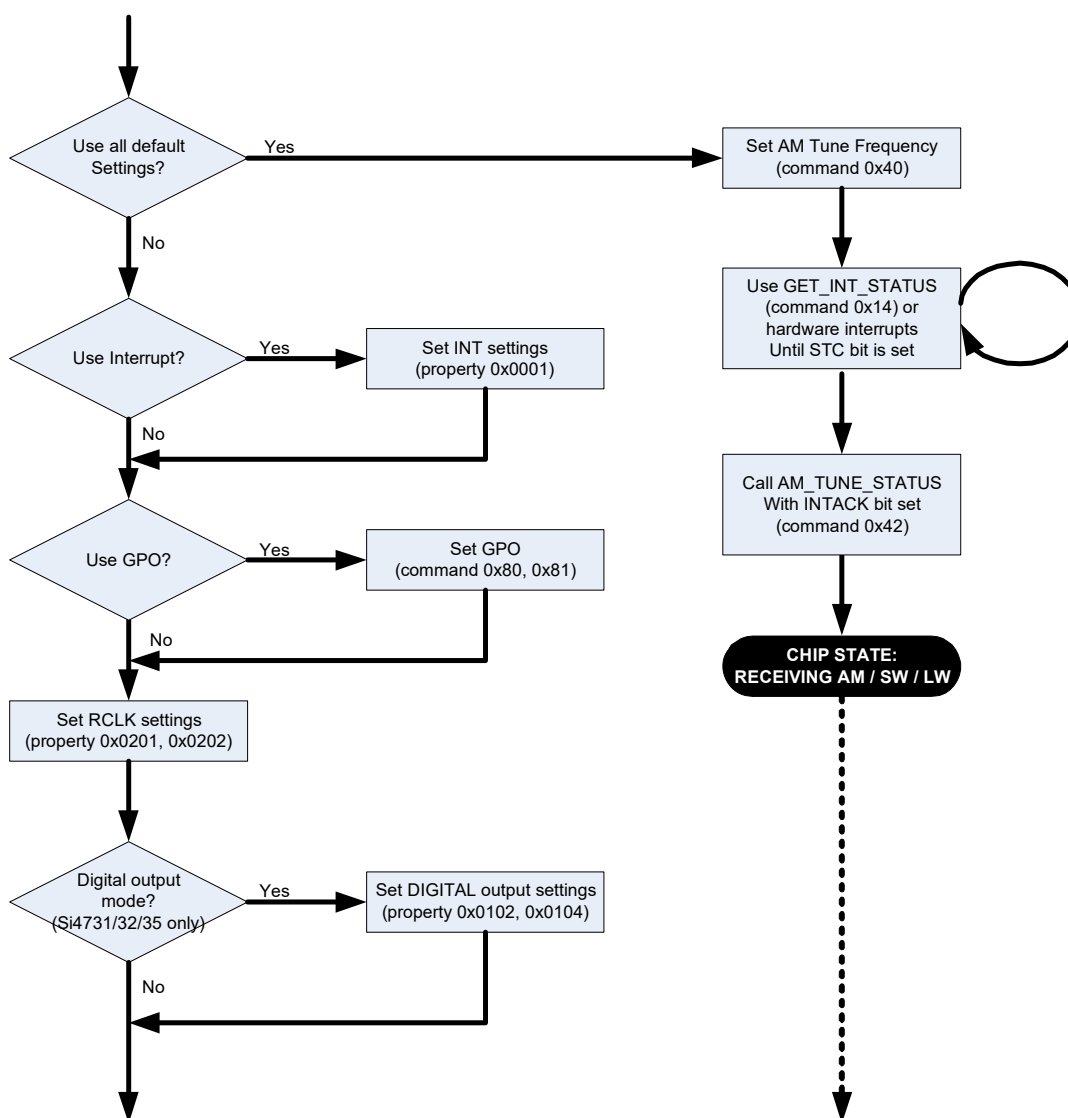
The device sets the CTS bit (and optional interrupt) to indicate that it is ready to accept the next command. The CTS bit also indicates that the POWER_UP, GET_REV, POWER_DOWN, GET_PROPERTY, GET_INT_STATUS, FM_TUNE_STATUS, and FM_RSQ_STATUS commands have completed execution.

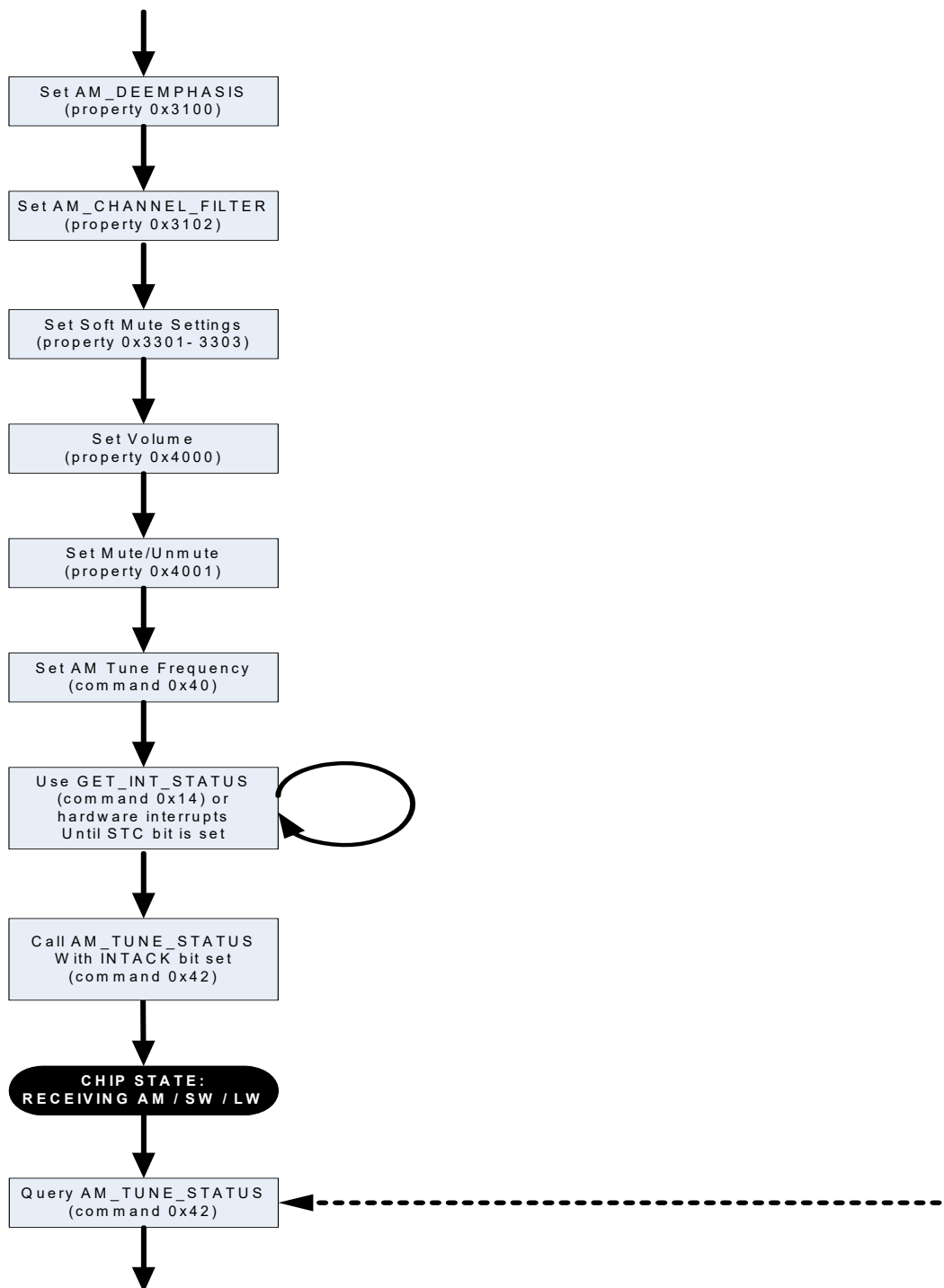
When performing a FM_TUNE_FREQ or FM_SEEK_START CTS will indicate that the device is ready to accept the next command even though the operation is not complete. GET_INT_STATUS or hardware interrupts should be used to query for the STC bit to be set prior to performing other commands. Use FM_TUNE_STATUS to clear the STC bit after it has been set.

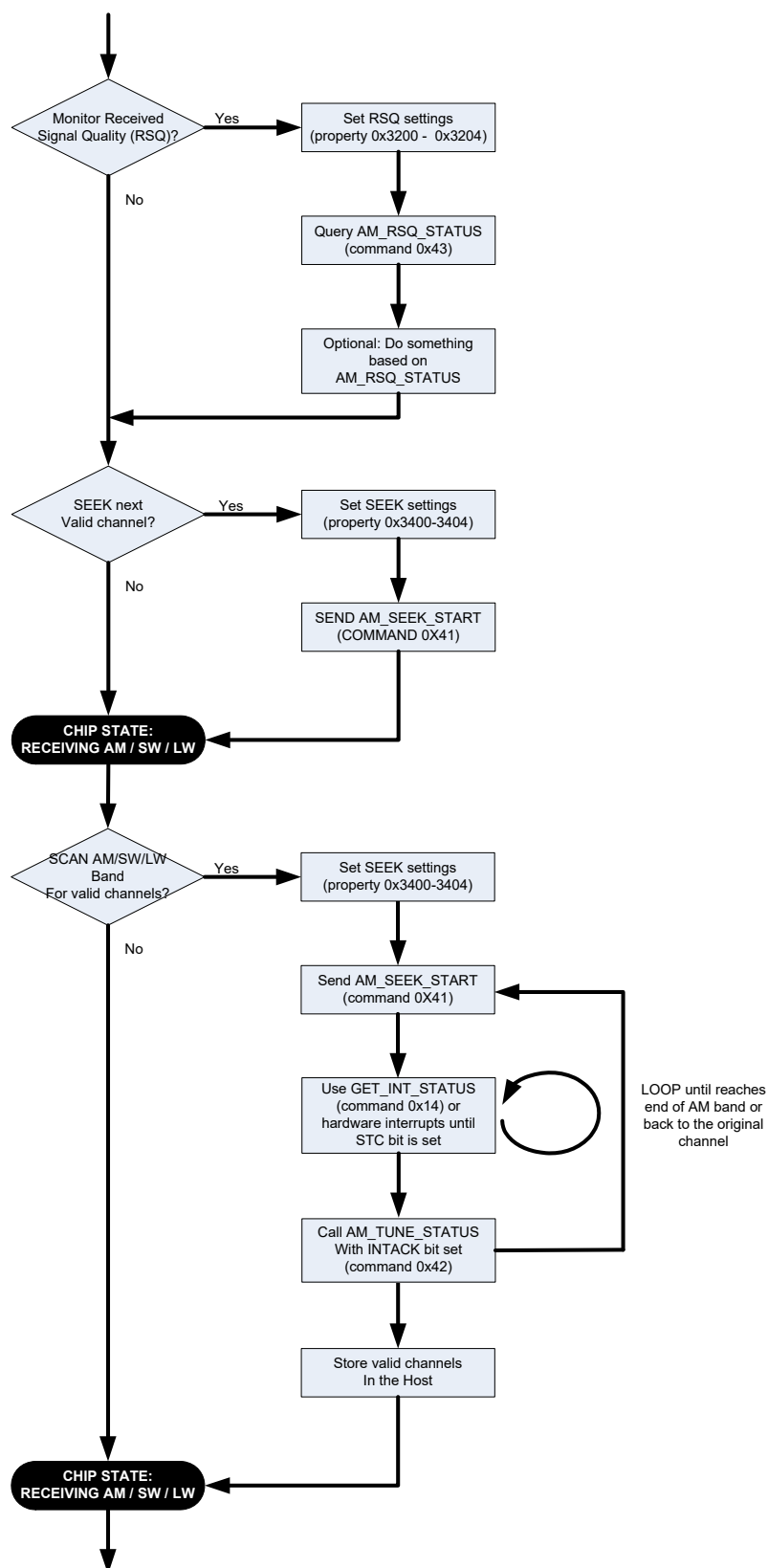
11.2. Programming Example for the AM/LW/SW Receiver

The following flowchart shows an overview of how to program the AM/LW/SW receiver.









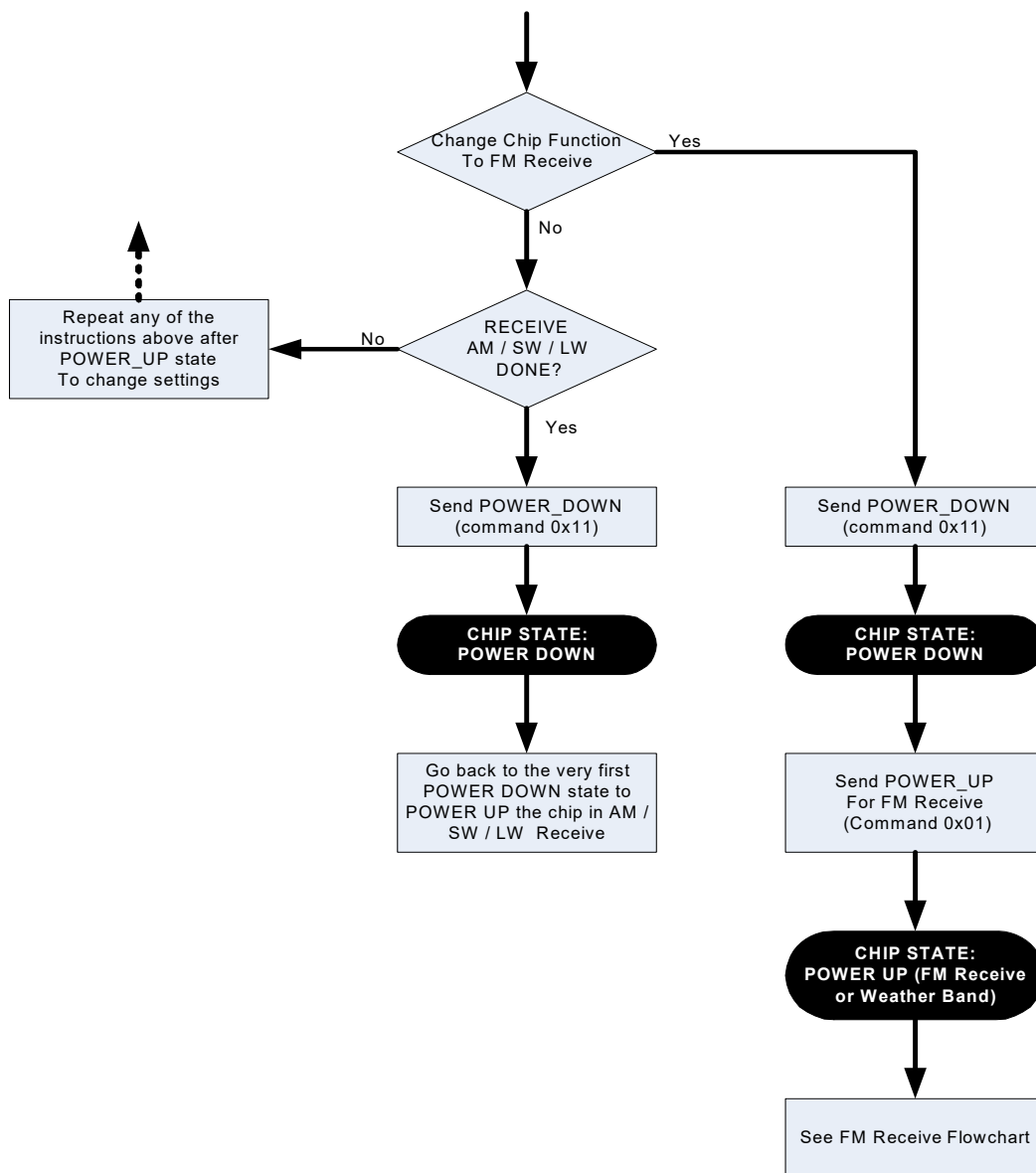


Table 35 provides an example of programming the AM/LW/SW receiver. The table is broken into three columns. The first column lists the action taking place: command (CMD), argument (ARG), status (STATUS) or response (RESP). For SET_PROPERTY commands, the property (PROP) and property data (PROPD) are indicated. The second column lists the data byte or bytes in hexadecimal that are being sent or received. An arrow preceding the data indicates data being sent from the device to the system controller. The third column describes the action.

Note that in some cases the default properties may be acceptable and no modification is necessary. Refer to Section “5. Commands and Properties” for a full description of each command and property.

Table 35. Programming Example for the AM/LW/SW Receiver

| Action | Data | Description |
|--------------------------------|-------|--|
| Powerup in Digital Mode | | |
| CMD | 0x01 | POWER_UP |
| ARG1 | 0xC1 | Set to AM/LW/SW Receive. Enable interrupts. |
| ARG2 | 0xB0 | Set to Digital Audio Output |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| | | Action: Ensure that DCLK and DFS are already supplied |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x01 | DIGITAL_OUTPUT_SAMPLE_RATE |
| ARG3 (PROP) | 0x04 | |
| ARG4 (PROPD) | 0xBB | Sample rate = 48000 Hz = 0xBB80 |
| ARG5 (PROPD) | 0x80 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x01 | DIGITAL_OUTPUT_FORMAT |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | Mode: I ² S, stereo, 16bit, sample on rising edge of DCLK. |
| ARG5 (PROPD) | 0x00 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| | | Action: Go to Configuration (bypass “Powerup in analog mode” section). The rest of the programming is the same as analog. |
| Powerup in Analog Mode | | |
| CMD | 0x01 | POWER_UP |
| ARG1 | 0xC1 | Set to AM/LW/SW Receive. Enable interrupts. |
| ARG2 | 0x05 | Set to Analog Audio Output |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| Configuration | | |
| CMD | 0x10 | GET_REV |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x1F | Part Number, HEX (0x1F = 31 dec. = Si4731) |
| RESP2 | →0x32 | Firmware Major Rev, ASCII (0x32 = 2) |
| RESP3 | →0x30 | Firmware Minor Rev, ASCII (0x30 = 0) |
| RESP4 | →0x85 | Patch ID MSB, example only |
| RESP5 | →0xC5 | Patch ID LSB, example only |
| RESP6 | →0x32 | Component Firmware Major Rev, ASCII (0x32 = 2) |
| RESP7 | →0x30 | Component Firmware Minor Rev, ASCII (0x30 = 0) |
| RESP8 | →0x42 | Chip Rev, ASCII (0x42 = revB) |

Table 35. Programming Example for the AM/LW/SW Receiver (Continued)

| Action | Data | Description |
|--------------|-------|--|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x00 | GPO_IEN |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x00 | Set STCIEN, ERRIEN, CTSIEN |
| ARG5 (PROPD) | 0xC1 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x02 | REFCLK_FREQ |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x7E | REFCLK = 32500 Hz |
| ARG5 (PROPD) | 0xF4 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x02 | REFCLK_PRESCALE |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x01 | Divide by 400 |
| ARG5 (PROPD) | 0x90 | (example RCLK = 13 MHz, REFCLK = 32500 Hz) |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x40 | RX_VOLUME |
| ARG3 (PROP) | 0x00 | |
| ARG4 (PROPD) | 0x00 | Output Volume = 63 |
| ARG5 (PROPD) | 0x3F | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x31 | AM_CHANNEL_FILTER |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x01 | 4 kHz Bandwidth = 0x01 |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x31 | AM_DEEMPHASIS |
| ARG3 (PROP) | 0x00 | |
| ARG4 (PROPD) | 0x00 | 50 μ s |
| ARG5 (PROPD) | 0x01 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

Table 35. Programming Example for the AM/LW/SW Receiver (Continued)

| Action | Data | Description |
|--------------|-------|--|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x32 | AM_RSQ_INTERRUPTS |
| ARG3 (PROP) | 0x00 | |
| ARG4 (PROPD) | 0x00 | Interrupt when SNR higher than RSQ SNR threshold |
| ARG5 (PROPD) | 0x08 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x32 | AM_RSQ_SNR_HIGH_THRESHOLD |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x0A | 10 dB = 0x0A |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x32 | AM_RSQ_SNR_LOW_THRESHOLD |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x0A | 10 dB = 0x0A |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x32 | AM_RSQ_RSSI_HIGH_THRESHOLD |
| ARG3 (PROP) | 0x03 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x1E | 30 dBμV = 0x1E |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x32 | AM_RSQ_RSSI_LOW_THRESHOLD |
| ARG3 (PROP) | 0x04 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x0A | 10 dBμV = 0x0A |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x33 | AM_SOFT_MUTE_MAX_ATTENUATION |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x0A | 10 dB attenuation = 0x0A |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

Table 35. Programming Example for the AM/LW/SW Receiver (Continued)

| Action | Data | Description |
|--------------|-------|-----------------------------------|
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x33 | AM_SOFT_MUTE_SNR_THRESHOLD |
| ARG3 (PROP) | 0x03 | |
| ARG4 (PROPD) | 0x00 | |
| ARG5 (PROPD) | 0x09 | 9 dB = 0x09 |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x34 | AM_SEEK_BAND_BOTTOM |
| ARG3 (PROP) | 0x00 | |
| ARG4 (PROPD) | 0x02 | 520 kHz = 0x0208 |
| ARG5 (PROPD) | 0x08 | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x34 | AM_SEEK_BAND_TOP |
| ARG3 (PROP) | 0x01 | |
| ARG4 (PROPD) | 0x06 | 1710 kHz = 0x06AE |
| ARG5 (PROPD) | 0xAE | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x34 | AM_SEEK_FREQ_SPACING |
| ARG3 (PROP) | 0x02 | |
| ARG4 (PROPD) | 0x00 | 10 kHz = 0x000A |
| ARG5 (PROPD) | 0x0A | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x34 | AM_SEEK_SNR_THRESHOLD |
| ARG3 (PROP) | 0x03 | |
| ARG4 (PROPD) | 0x00 | 0x000B = 11 dB |
| ARG5 (PROPD) | 0x0B | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x12 | SET_PROPERTY |
| ARG1 | 0x00 | |
| ARG2 (PROP) | 0x34 | AM_SEEK_RSSI_THRESHOLD |
| ARG3 (PROP) | 0x04 | |
| ARG4 (PROPD) | 0x00 | 0x002A = 42 dBμV |
| ARG5 (PROPD) | 0x2A | |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

Table 35. Programming Example for the AM/LW/SW Receiver (Continued)

| Action | Data | Description |
|--------|-------|--|
| CMD | 0x40 | AM_TUNE_FREQ |
| ARG1 | 0x00 | |
| ARG2 | 0x03 | Set frequency to 1000 kHz = 0x03E8 |
| ARG3 | 0xE8 | |
| ARG4 | 0x00 | Automatically select tuning capacitor |
| ARG5 | 0x00 | Reply Status. Clear-to-send high. |
| STATUS | →0x80 | |
| CMD | 0x14 | GET_INT_STATUS |
| STATUS | →0x81 | Reply Status. Clear-to-send high. STCINT = 1. |
| CMD | 0x41 | AM_SEEK_START |
| ARG1 | 0x0C | Seek up and wrap at band boundary |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| CMD | 0x14 | GET_INT_STATUS |
| STATUS | →0x81 | Reply Status. Clear-to-send high. STCINT = 1. |
| CMD | 0x42 | AM_TUNE_STATUS |
| ARG1 | 0x01 | Clear STC interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x01 | Channel is valid, AFC is not railed, and seek did not wrap at AM band boundary |
| RESP2 | →0x03 | Frequency = 0x03E8 = 1000 kHz |
| RESP3 | →0xE8 | |
| RESP4 | →0x2A | RSSI = 0x2A = 42d = 42 dBμV |
| RESP5 | →0x1A | SNR = 0x1A = 26d = 26 dB |
| RESP6 | →0x0D | Value the antenna tuning capacitor is set to. |
| RESP7 | →0x95 | 0x0D95 = 3477 dec. |
| CMD | 0x43 | AM_RSQ_STATUS |
| ARG1 | 0x01 | Clear STC interrupt. |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |
| RESP1 | →0x00 | No SNR high, low, RSSI high, or low interrupts. |
| RESP2 | →0x01 | Channel is valid, soft mute is not activated, and AFC is not railed |
| RESP3 | →0x00 | |
| RESP4 | →0x2A | RSSI = 0x2A = 42d = 42 dBμV |
| RESP5 | →0x1A | SNR = 0x1A = 26d = 26 dB |
| CMD | 0x11 | POWER_DOWN |
| STATUS | →0x80 | Reply Status. Clear-to-send high. |

The device sets the CTS bit (and optional interrupt) to indicate that it is ready to accept the next command. The CTS bit also indicates that the POWER_UP, GET_REV, POWER_DOWN, GET_PROPERTY, GET_INT_STATUS, AM_TUNE_STATUS, and AM_RSQ_STATUS commands have completed execution.

When performing a AM_TUNE_FREQ or AM_SEEK_START CTS will indicate that the device is ready to accept the next command even though the operation is not complete. GET_INT_STATUS or hardware interrupts should be used to query for the STC bit to be set prior to performing other commands. Use AM_TUNE_STATUS to clear the STC bit after it has been set.

DOCUMENT CHANGE LIST

Revision 1.2 to Revision A

- Updated document revision numbering from decimal to alphanumeric.
- Removed “5.1. Commands and Properties for the FM/RDS Transmitter (Si4710/11/12/13/20/21)”.
- Removed “5.4. Commands and Properties for the WB Receiver (Si4707/36/37/38/39/42/43)”.
- Removed “11. FM Transmitter” section.
- Removed “12.1. Programming Example for the FM/RDS Transmitter”.
- Removed Appendix A.
- Removed Appendix B.
- Removed references to FM Transmitter and WB Receiver.
- Changed “TX_TUNE_FREQ” to “FM_TUNE_FREQ”.
- Removed references to Si4707, Si471x, Si472x, Si474x, Si4784, and Si4785.
- Removed reference to SAME function.
- Changed “station” to “frequency”.

Revision 1.1 to Revision 1.2

- Added information that Digital Output is available in Si4704-D60 and later.
- Added errata for the digital audio input for three devices: Si4710-B30, Si4712-B30, Si4720-B20.

Revision 1.0 to Revision 1.1

- Added Si4704/05/30/31-D62 part information.
- Removed AUXIN components from Si4704/05/30/31/34/35-D60 parts.

Revision 0.9 to Revision 1.0

- Removed information about AUXIN components.
- Added notes to powerup command section.

Revision 0.8 to Revision 0.9

- Added Si4732 AM/SW/LW/FM RDS Receiver support.

Revision 0.7 to Revision 0.8

- Corrected pin numbers of LIN and RIN for Si4704/05/3x-D60 parts.
- Added more explanations to property 0x1900 and 0x3103.
- Added AUXIN Components in Tables 33, 38, and 41.

Revision 0.6 to Revision 0.7

- Added FM_BLEND_MAX_STEREO_SEPARATION property

Revision 0.5 to Revision 0.6

- Added Appendix A and Appendix B.

Revision 0.41 to Revision 0.5

- Combined information in AN332 Rev. 0.41 and AN344 Rev. 0.4 into AN332 Rev. 0.5.
- Added information for Si47xx-D50 and Si47xx-D60 parts.

Revision 0.4 to Revision 0.41

- Minor edits.

Revision 0.3 to Revision 0.4

- Added Si4704/05/30/31/34/35/36/37/38/39-C40 receiver support and additional AM properties.
- Added Si4784/85-B20 receiver support.
- Updated product matrix in Table 1.
- Updated with corrections to couple commands and properties.

Revision 0.2 to Revision 0.3

- Added notes to AM/SW/LW Receiver Reference Clock section.
- Removed Si4706/07/4x-related material.
- Updated product matrix in Table 1.

Revision 0.1 to Revision 0.2

- Updated Product Matrix in Table 1.
- Added Si4706 FM and High-Performance RDS Receiver support.
- Added Si4707 WB/SAME Receiver support.
- Added Si4740/41 multipath, blend, and AGC properties.
- Added Si4749 High-Performance RDS Receiver support.
- Updated Firmware, Library, and Component Compatibility tables.
- Added Command Timing Parameters for the WB Receiver.
- Updated FM Transmitter maximum audio volume recommendations.

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