

YIC



YIC51818GMGG-33-C

Standard Precision GNSS Antenna Module

Datasheet

Revision History

Date	Reversion	Description
2021/1/21	1.0	First Draft, Based on YIC51818GMGG-33-C
2024/12/26	2.0	Description: Added Cable Assembly Link

Directory

Revision History.....	2
1. Product Information	4
1.1 Product Description	4
1.2 Product Features	4
1.3 Product Specifications	5
1.4 DC Electrical Characteristics	6
2. Pin Assignment	7
2.1 JST Connector	7
2.1.1 Ordering Information of the Cable Connector Assembly for P1 to Host.....	7
2.2 Dimensions	8
3. Application Circuit : (Example).....	8
4. Software Protocol	9
5. Protocol.....	10
5.1 GGA--- Global Positioning System Fixed Data	10
5.2 GLL--- Geographic Position – Latitude/Longitude	11
5.3 GSA---GNSS DOP and Active Satellites.....	12
5.4 GSV---GNSS Satellites in View.....	13
5.5 RMC---Recommended Minimum Specific GNSS Data	14
5.6 VTG---Course Over Ground and Ground Speed.....	15

1. Product Information

1.1 Product Description

YIC51818GMGG-33-C is a compact, high performance and low power consumption, standalone multiple GPS/GNSS antenna module. The module can simultaneously acquire and track multiple satellite constellations that include GPS, QZSS , GLONASS, Galileo, BeiDou and SBAS. It features low power and small form factor.

Applications

- Automotive navigation
- Personal positioning
- Fleet management
- Mobile phone navigation
- Marine navigation

1.2 Product Features

- High performance and low power consumption GPS chipset
- Very high sensitivity
- Extremely fast TTFF (Time To First Fix) at low signal level
- Two serial ports
- Built-in LNA
- Compact size suitable for space-sensitive application
- Support NMEA 0183 and MTK binary protocol
- Module connected to host through cable connector

1.3 Product Specifications

GNSS Receiver		
Chip	MediaTek	
Frequency	GPS, GALILEO, QZSS: L1 1575.42MHz, C/A code GLONASS: L1 1598.0625MHz ~ 1605.375MHz, C/A code	
Channels	Support 99 channels (33 Tracking, 99 Acquisition)	
Update rate	1Hz default, up to 10Hz	
Sensitivity	Tracking	-161dBm, up to -165dBm (with external LNA)
	Cold start	-142.5dBm, up to -148dBm (with external LNA)
Acquisition Time	Hot start (Open Sky)	< 1s
	Cold Start (Open Sky)	< 38s
		< 18s with AGPS
Position Accuracy	Autonomous	5m (2D RMS).
	SBAS	2.5m (depends on accuracy of correction data).
Max. Altitude	< 18,000 m, up to 50,000m by request	
Max. Velocity	Velocity < 515 m/s	
Protocol Support	NMEA 0183	9600 bps, 8 data bits, no parity, 1 stop bits (default) 1Hz: GGA, GLL, GSA, GSV, RMC, VTG
Physical Characteristic		
Dimensions	18.5mm *18.5mm * 6.8mm ±0.2mm	

1.4 DC Electrical Characteristics

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Units
Input Voltage	VCC		3.0	3.3	5.5	V
Input Backup Battery Voltage	V_BCKP		2.0		4.3	V
Supply Current	I _{ss}	VCC = 3.3V Peak Acquisition Tracking Standby		31 24 ⁽²⁾ 600	150 ⁽¹⁾	mA mA mA uA
Backup Battery Current	I _{bat}	VCC = 0V		7		uA
High Level Input Voltage	V _{IH}		2.0		3.6	V
Low Level Input Voltage	V _{IL}		-0.3		0.8	V
High Level Input Current	I _{IH}	no pull-up or down	-1		1	uA
Low Level Input Current	I _{IL}	no pull-up or down	-1		1	uA
High Level Output Voltage	V _{OH}		2.4		3.3	V
Low Level Output Voltage	V _{OL}				0.4	V
High Level Output Current	I _{OH}			2		mA
Low Level Output Current	I _{OL}			2		mA

Note 1: This happens when downloading AGPS data to Module.

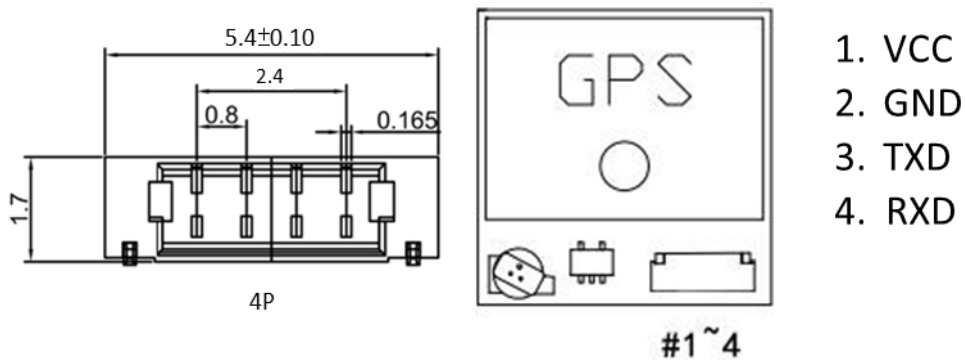
Note 2: Measured when position fix (1Hz) is available, input voltage is 3.3V and the function of self-generated ephemeris prediction is inactive.

Temperature characteristics

Parameter	Symbol	Min.	Typ.	Max.	Units
Operating Temperature	T _{opr}	-40	25	85	°C
Storage Temperature	T _{stg}	-40	25	85	°C

2. Pin Assignment

2.1 JST Connector



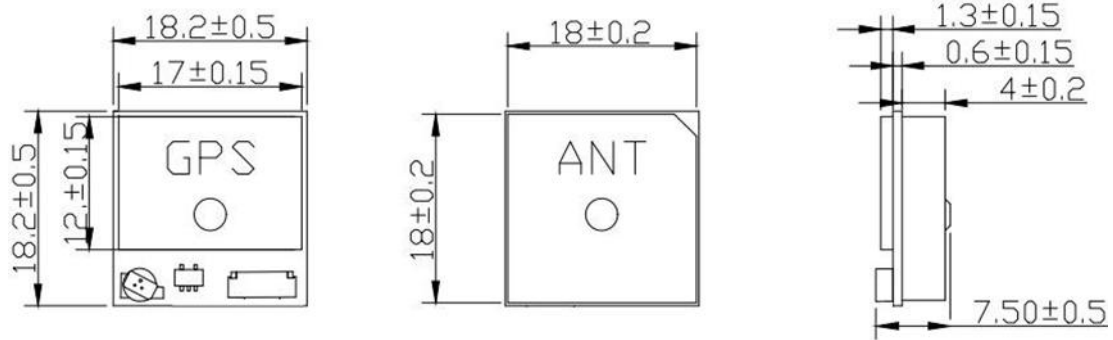
Pin NO.	Pin Name	I/O	Remark	Description
1.	VCC	I	Module Power Supply	4 Pole 0.8mm Pitch Connector
2.	GND	G	Ground	
3.	TXD	O	UART/TTL Serial Data Output	
4.	RXD	I	UART/TTL Serial Data Input	

2.1.1 Ordering Information of the Cable Connector Assembly for P1 to Host

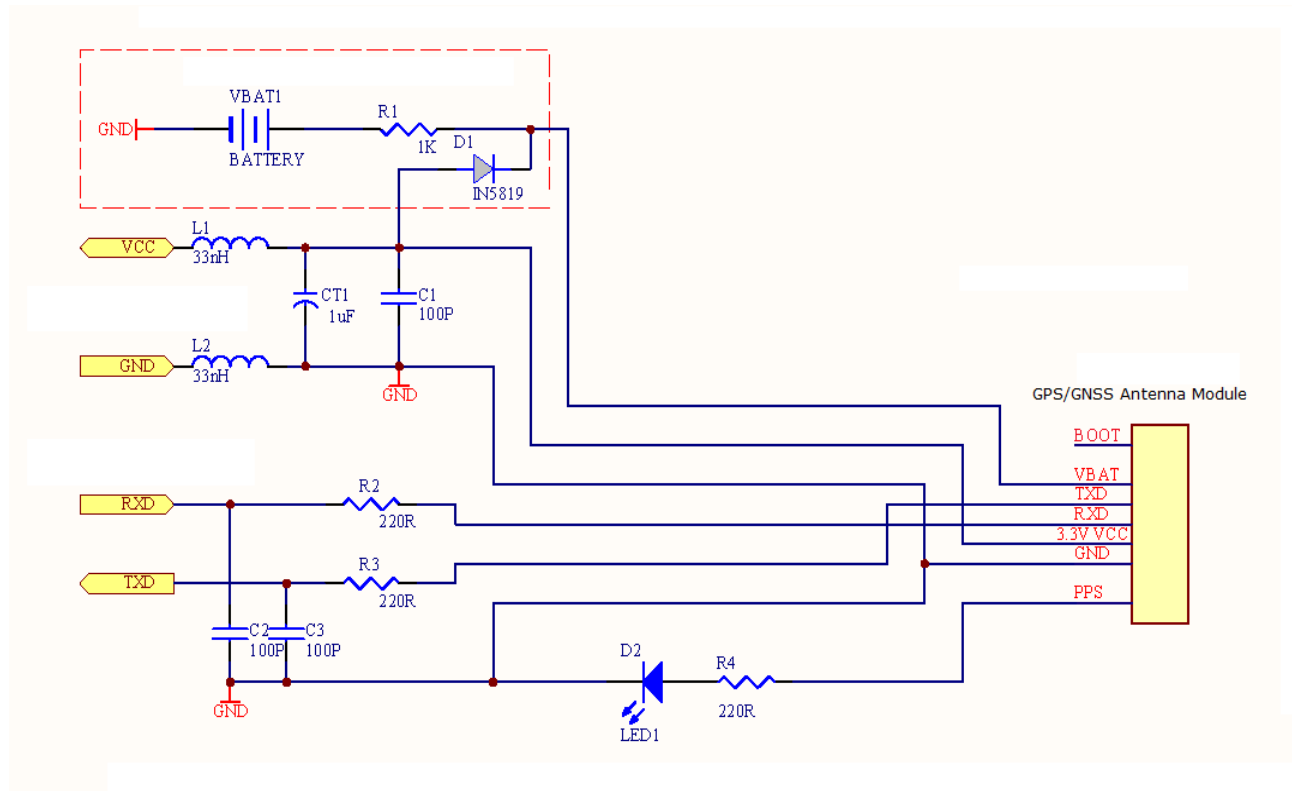
Orderable Part Number: [J0408-A32-J0408-35](#)

*Also supports Customization.

2.2 Dimensions



3. Application Circuit : (Example)



4. Software Protocol

Table 4.1 NMEA output message

NMEA	Description
GGA	Global positioning system fixed data
GLL	Geographic position - latitude/longitude
GSA	GNSS DOP and active satellites
GSV	GNSS satellites in view
RMC	Recommended minimum specific GNSS data
VTG	Course over ground and ground speed

5. Protocol

5.1 GGA--- Global Positioning System Fixed Data

Table 4.2 contains the values for the following example:

\$GPGGA,060406.000,2503.7148,N,12138.7451,E,2,17,0.71,116.7,M,15.3,M,0000,0000*6D

Table4. 2 GGA Data Format

Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Time	060406.000		hhmmss.sss
Latitude	2503.7148		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12138.7451		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Position Fix Indicator	2		See Table 3.3
Satellites Used	17		Range 0 to 33
HDOP	0.71		Horizontal Dilution of Precision
MSL Altitude	116.7	mters	
Units	M	mters	
Geoid Separation	15.3	mters	
Units	M	mters	
Age of Diff. Corr.	0000	second	Null fields when DGPS is not used
Diff. Ref. Station ID	0000		
Checksum	*6D		
<CR> <LF>			End of message termination

Table4.3 Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3-5	Not supported
6	Dead Reckoning Mode, fix valid

5.2 GLL--- Geographic Position – Latitude/Longitude

Table4.4 contains the values for the following example:

\$GNGLL,2503.7148,N,12138.7451,E,060406.000,A,D*46

Table3.4 GLL Data Format

Name	Example	Units	Description
Message ID	\$GNGLL		GLL protocol header (GPGLL or GNGLL; GP indicates the device receives GPS satellites signal only and GN indicates the position is calculated with BEIDOU satellite signal)
Latitude	2503.7148		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12138.7451		dddmm.mmmm
E/W indicator	E		E=east or W=west
UTC Time	060406.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Mode	D		A=autonomous, D=DGPS, E=DR, N=Data not valid, R=Coarse Position, S=Simulator
Checksum	*46		
<CR> <LF>			End of message termination

5.3 GSA---GNSS DOP and Active Satellites

Table 4.5 contains the values for the following example:

\$GNGSA,A,3,205,207,210,202,201,203,209,208,,,,,1.18,0.71,0.95*1C

Table3. 5 GSA Data FormatName	Example	Units	Description
Message ID	\$GNGSA		GSA protocol header (GNGSA or GPGSA; GP indicates the device receives GPS satellites signal only and GN indicates the position is calculated with BEIDOU satellite signal).First row of GSA message contains GPS & QZSS satellites and second row of GSA message contains BEIDOU satellites.
Mode 1	A		See Table 4.6
Mode 2	3		See Table 4.7
ID of satellite used	22		Sv on Channel 1
ID of satellite used	21		Sv on Channel 2
....			
ID of satellite used			Sv on Channel 12
PDOP	1.18		Position Dilution of Precision
HDOP	0.71		Horizontal Dilution of Precision
VDOP	0.95		Vertical Dilution of Precision
Checksum	*2C		
<CR> <LF>			End of message termination

Table 4.6 Mode 1

Value	Description
M	Manual- forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

Table 4.7 Mode 2

Value	Description
1	Fix not available
2	2D
3	3D

5.4 GSV---GNSS Satellites in View

Table 4.8 contains the values for the following example:

\$GPGSV,6,2,21,203,58,205,39,25,56,138,39,201,55,141,34,206,50,168,*45

\$GPGSV,6,3,21,210,49,282,34,12,48,076,39,204,39,118,,14,38,322,37*77

\$GPGSV,6,4,21,193,37,180,34,202,36,246,29,24,23,041,34,31,21,244,*71

\$GPGSV,6,5,21,21,17,198,33,205,16,258,28,15,12,092,33,208,09,169,30*7B

\$GPGSV,6,6,21,51,,,*7E

Table 4.8 GSV Data Format

Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Total number of messages1	6		Range 1 to 6
Message number1	1		Range 1 to 6
Satellites in view	21		
Satellite ID	18		Channel 1 (Range 01 to 237), GPS Satellites ID : 01~32, SBAS Satellites ID : 33~64, QZSS Satellites ID:193~196, &BEIDOU Satellites ID : 201~214
Elevation	78	degrees	Channel 1 (Range 00 to 90)
Azimuth	169	degrees	Channel 1 (Range 000 to 359)
SNR (C/No)	36	dB-Hz	Channel 1 (Range 00 to 99, null when not tracking)
Satellite ID	207		Channel 4 (Range 01 to 237) , GPS Satellites ID : 01~32, SBAS Satellites ID : 33~64, QZSS Satellites ID:193~196, &BEIDOU Satellites ID : 201~214
Elevation	63	degrees	Channel 4 (Range 00 to 90)
Azimuth	328	degrees	Channel 4 (Range 000 to 359)
SNR (C/No)	38	dB-Hz	Channel 4 (Range 00 to 99, null when not tracking)
Checksum	*7B		
<CR> <LF>			End of message termination

Depending on the number of satellites tracked multiple messages of GSV data may be required.

5.5 RMC---Recommended Minimum Specific GNSS Data

Table 4.9 contains the values for the following example:

\$GNRMC,060406.000,A,2503.7148,N,12138.7451,E,0.01,0.00,180313,,D*78

Table 4.9 RMC Data Format

Name	Example	Units	Description
Message ID	\$GNRMC		RMC protocol header (GNRMC or GPRMC; GP indicates the device receives GPS satellites signal only and GN indicates the position is calculated with BEIDOU satellite signal)
UTC Time	060406.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	2503.7148		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12138.7451		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Speed over ground	0.01	knots	True
Course over ground	0.00	degrees	
Date	180313		ddmmyy
Magnetic variation		degrees	
Variation sense			E=east or W=west (Not shown)
Mode	D		A=autonomous, D=DGPS, E=DR, N=Data not valid, R=Coarse Position, S=Simulator
Checksum	*78		
<CR> <LF>			End of message termination

5.6 VTG---Course Over Ground and Ground Speed

Table 4.10 contains the values for the following example:

\$GPVTG,0.00,T,,M,0.01,N,0.02,K,D*3B

Table 4.10 VTG Data Format

Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
Course over ground	0.00	degrees	Measured heading
Reference	T		True
Course over ground		degrees	Measured heading
Reference	M		Magnetic
Speed over ground	0.01	knots	Measured speed
Units	N		Knots
Speed over ground	0.02	km/hr	Measured speed
Units	K		Kilometer per hour
Mode	D		A=autonomous, D=DGPS, E=DR, N=Data not valid, R=Coarse Position, S=Simulator
Checksum	*3B		
<CR> <LF>			End of message termination